



O5

Servo system

DS5□2/DS5□1 compact servo | DM6C multi-axis servo

DL6 linear drive servo | DF3 low voltage servo | MS6 motor | MF motor

Servo system overview

Compact servo system



The compact servo system currently has 6 subseries of products, including pulse type and bus type. In addition to all the functions of the universal series, its outstanding advantage lies in its slim and compact size, which can save more installation space.

Suitable for fields such as 3C, textile, printing, packaging, food, pharmaceutical electronics, environmental protection, etc.

Compatible motor: MS6 series.

Bus type	DS5C1	0.1kW~45kW	EtherCAT
	DS5C2	0.1kW~32kW	EtherCAT
	DS5P	0.1kW~7.5kW	PROFINET
Pulse type	DS5L1	0.1kW~3kW	Modbus
	DS5L2	0.1kW~3kW	Modbus
	DS5K2	0.1kW~7.5kW	Modbus

Linear drive servo system



The linear drive servo system currently has one subseries, equipped with long line drive, frequency division output, position comparison output, probe function, motor temperature sampling and other functions. It comes standard with multiple protection functions such as dynamic braking, STO safety torque off, overcurrent protection, etc. The introduction of a new gantry synchronization algorithm ensures the high synchronization of the two axes during operation. The new TYPE-C debugging port and positioning accuracy compensation function help achieve higher absolute positioning accuracy.

Suitable for applications such as lithium battery stacking, die bonder, optical inspection platforms, UV printing, etc.

Suitable motor: Linear motor.

Bus type	DL6	2.8A~6A	EtherCAT
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Multi-axis servo system



The multi-axis servo system currently has one subseries, which has multiple advantages such as high dynamic response, space saving, high efficiency and energy saving, flexible configuration, and high protection. It comes standard with STO function and independent supply of 24V control electricity, making it safer and more reliable.

Suitable for fields such as printing and packaging, forging machines, wire cutting, silicon semiconductor, laser cutting, etc.

Compatible motor: MS6 series.

Bus type	DM6C	0.4kW~160kW	EtherCAT
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Low voltage servo system



The low-voltage servo system currently has one subseries of bus type, with a compact design, lightweight and compact body, rich interfaces, support for communication protocols such as CANopen and Modbus, low-voltage DC power supply, built-in 24V brake power output, and gain adjustment in just three steps, reducing debugging time.

Suitable for AGV, sorting, logistics warehousing, medical and other fields.

Suitable motors: MF3 series, MF5 series.

Bus type	DF3E	0.2kW~1.5kW	CANopen
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*Note: The models that have been put into production can be found in the subsequent model list. Some models are still under development, please stay tuned.

High performance servo system

Excellent performance, safe and reliable,
convenient and easy to use, compact size



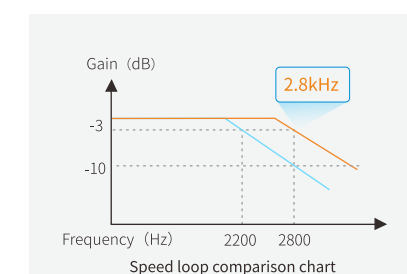
DS5L2 series high performance servo driver



■ Excellent performance

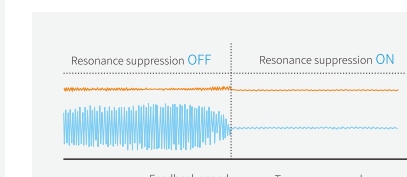
High dynamic response

- The speed loop response bandwidth of up to 2.8kHz can meet the requirements of devices with fast response speed and high accuracy.



Resonance suppression

- The resonance suppression control algorithm can effectively shorten the setting time, eliminate mechanical resonance, and make path tracking smooth and accurate.
- Resonance frequency automatic inspection, with stronger usability.
- Improved vibration frequency recognition accuracy by 50% (compared to DS5L1).
- 50% reduction in resonance frequency analysis time (compared to DS5L1).



High precision positioning

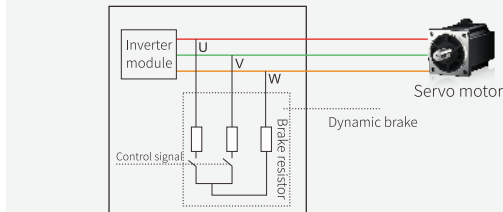
- Equipped with 19-bit magnetic encoder and 23-bit optical encoder with high resolution, it can help servo motors improve low-speed vibration suppression ability, reduce speed fluctuations, and make the servo system run more smoothly and accurately.



Safe and reliable

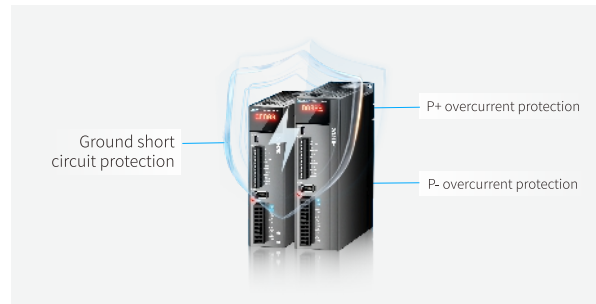
Standard dynamic braking

- When the motor is running, in the event of a power outage or alarm, the servo will be turned off and the three-phase circuit of the motor will be short circuited. The servo motor will quickly stop, ensuring the safety of operators and machine equipment.



Multiple protection functions

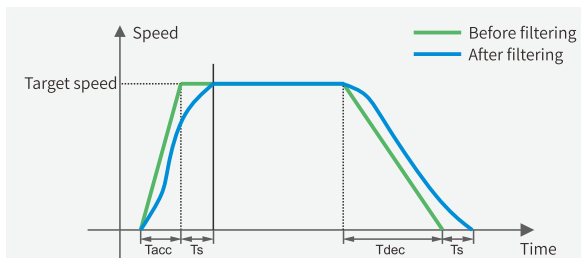
- Supports multiple protection functions, such as P+ overcurrent protection, ground short circuit protection, P- overcurrent protection, etc., with ultra-low failure rate, users can use it with peace of mind.



Stable and easy to use

S-shaped acceleration and deceleration curve

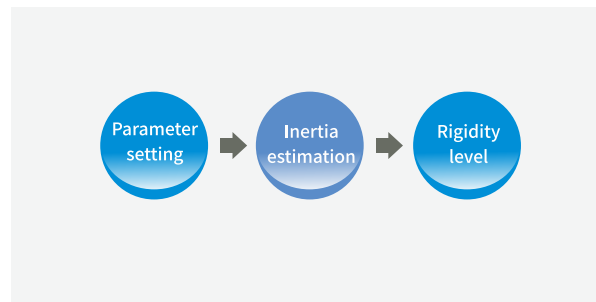
- The S-shaped acceleration and deceleration curve can effectively overcome mechanical vibrations caused by sudden speed changes, making operation smoother and more stable.



Note: Only the speed mode is effective.

Quick adjustment to shorten positioning time

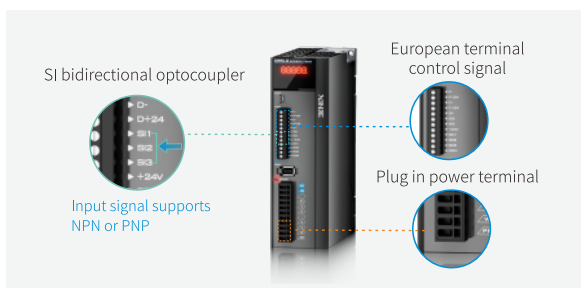
- Load inertia estimation, search for optimal gain, and complete positioning within 20ms.
- Driver panel offline adjustment.
- The rigidity level can reach up to level 41.



*Note: DSSL2 covers 32 levels of rigidity.

Convenient and easy to use

- Easy to operate terminal design improves wiring efficiency and saves maintenance time.
- Gain adjustment free, strong parameter applicability. Users do not need complex gain tuning, debugging is simple and convenient, and can greatly shorten debugging time.



Perfectly compatible in size

- The DS5L2 series is fully compatible with the DS5L1 series (same power range), ensuring worry free replacement.



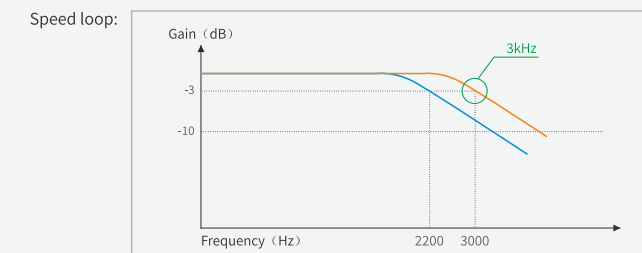
DS5K2 series high performance servo driver



Excellent performance

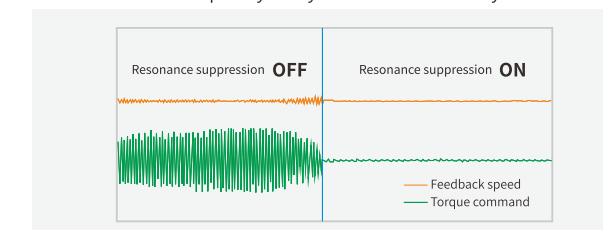
High dynamic response

- 3kHz speed loop response bandwidth. High dynamic response, improving production efficiency.
- Advanced control algorithms provide the optimal solution for achieving fast and flexible results in fast positioning systems.



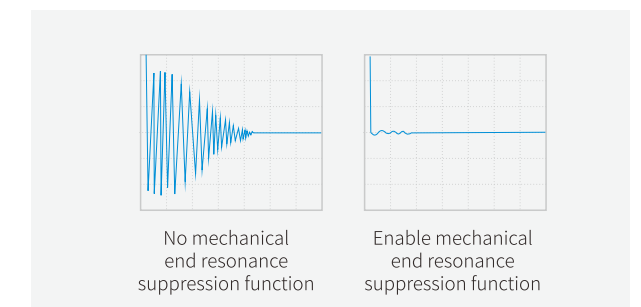
Resonance suppression

- The resonance suppression control algorithm can effectively shorten the setting time, eliminate mechanical resonance, and make path tracking smooth and accurate.
- Resonance frequency automatic inspection, with stronger usability.
- The accuracy of vibration frequency recognition has been improved by 50%.
- The resonance frequency analysis time is reduced by 50%.



Mechanical end resonance suppression

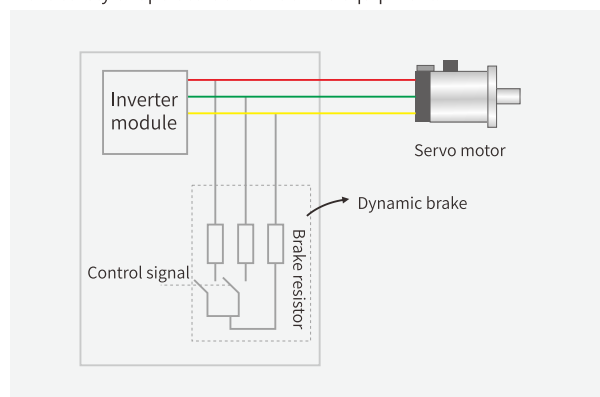
- By using advanced control algorithms, vibration and noise suppression of mechanical ends can be achieved. Effectively solve the vibration at the end of the cantilever mechanism, shorten the setting time, and improve product accuracy.



Safe and reliable

Dynamic braking

- When the motor is running, in the event of a power outage or alarm, the servo will be turned off and the three-phase circuit of the motor will be short circuited. The servo motor will quickly stop, ensuring the safety of operators and machine equipment.



Multiple protection functions

- Supports multiple protection functions, such as ground short circuit protection, P- overcurrent protection, etc., with ultra-low failure rate, users can use it with peace of mind.



Stable and easy to use

The system runs more smoothly and has higher positioning accuracy

- Equipped with high-resolution encoder, 19-bit magnetic encoder and 23-bit optical encoder, it can help servo motors improve low-speed vibration suppression ability, reduce speed fluctuations, and make the servo system run more smoothly and accurately.
- Suitable for MS6-B3/MS6G series high protection single/multi turn integrated motors, with simpler and more convenient selection.
- Lower speed and torque fluctuations assist in the smooth operation of torque control equipment.



Fully functional

- The DS5K2 series has complete functions, including long line drive, frequency division output, analog, RS485 communication, and more.



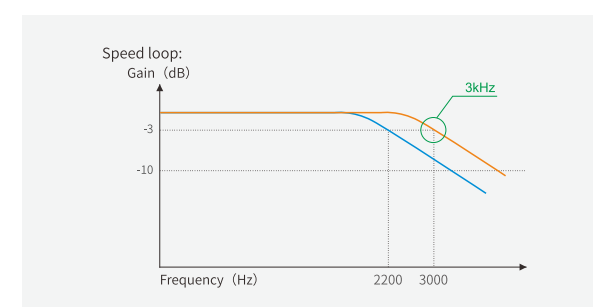
DS5C2 series high performance servo driver



Excellent performance

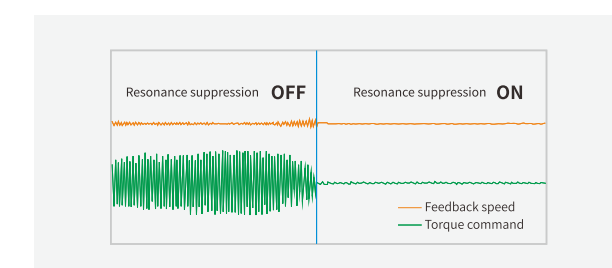
High dynamic response

- 3kHz speed loop response bandwidth, synchronization period 250us, high dynamic response, improve production efficiency.
- Advanced control algorithms provide the optimal solution for achieving fast and flexible results in fast positioning systems.



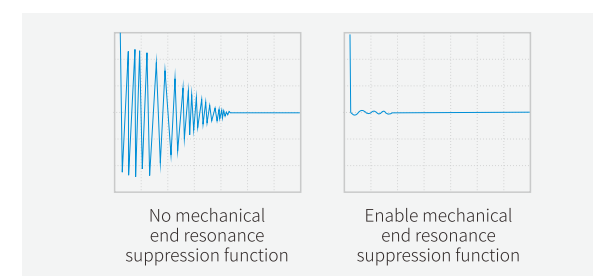
Resonance suppression

- The resonance suppression control algorithm can effectively shorten the setting time, eliminate mechanical resonance, and make path tracking smooth and accurate.
- Resonance frequency automatic inspection, with stronger usability.
- The accuracy of vibration frequency recognition has been improved by 50%.
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Mechanical end resonance suppression

- By using advanced control algorithms, vibration and noise suppression of mechanical ends can be achieved. Effectively solve the vibration at the end of the cantilever mechanism, shorten the setting time, and improve product accuracy.



MS6-B3 series servo motor

High protection level | lightweight design |
high-precision positioning



Higher protection level

- The MS6 series motor structure has been optimized, further improving the protection level. The B1/B2 series can achieve a protection level of IP66, and the B3 series can achieve IP67.



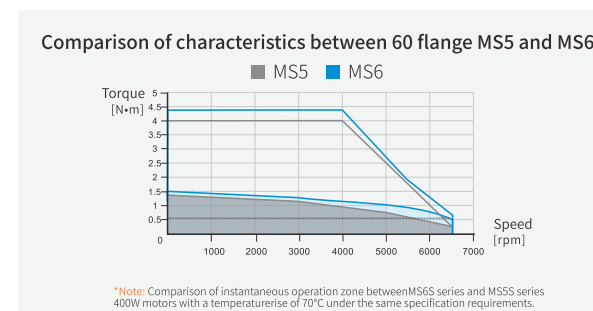
Lightweight motor

- The body of the MS6 series motor is further shortened, with a maximum reduction of 18% compared to the MS5 series motor.



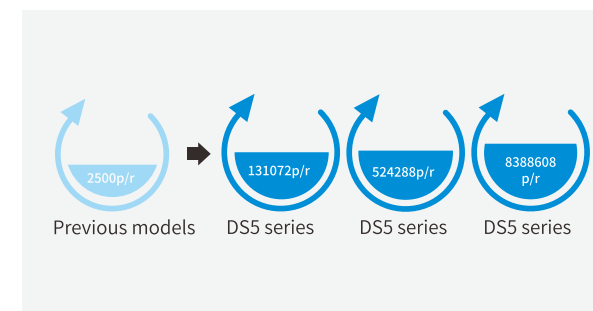
Higher torque output

- The MS6 series 400W motor can currently exceed the speed limit to 6500rpm, while maintaining 80% of its rated output at the maximum speed.



Encoder resolution

- The entire series comes standard with 17-bit, 19-bit, and 23-bit encoders to choose from.
- Realize higher precision position control and stable low-speed operation.
- The magnetic encoder has enhanced resistance to oil stains and vibration.



Brand new exterior structure

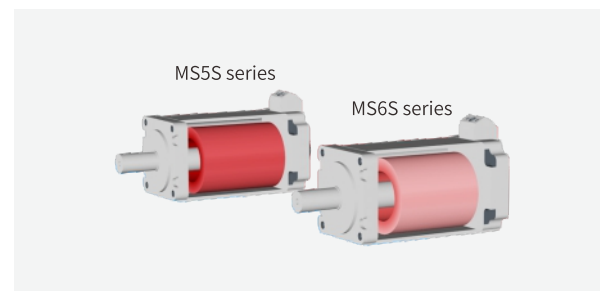
MS6 series B3 motor

- The brand new black body and frosted texture effectively reduce the tactile temperature of the motor.



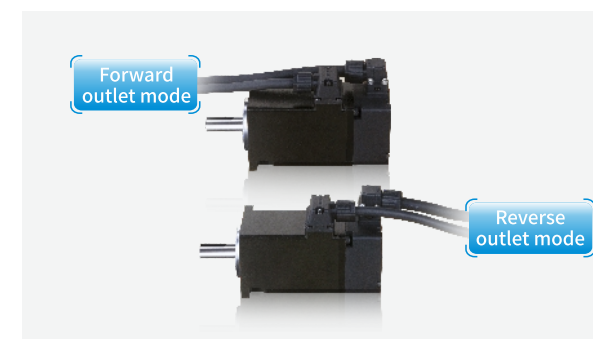
Low noise, low temperature rise

- Effective noise reduction. Compared with the previous generation motor, the winding temperature rise of B3 motor can be reduced by up to 20°C (taking 400W as an example).



Flexible configuration to meet different needs

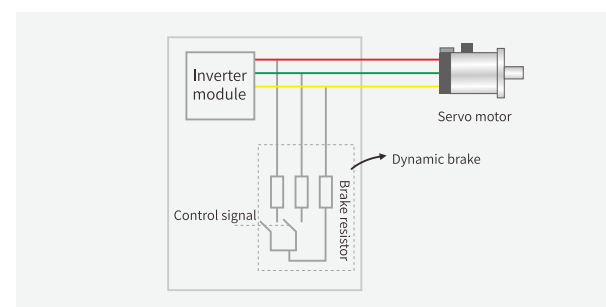
- Provide low inertia and high inertia motor options, suitable for a wider range of equipment scenarios.
- Power-off brake, oil seal, etc. are optional.
- The B3 series has optional forward and reverse outlet modes.
- The B3 series can be configured with connectors to convert to Amp adapter cables.
- The B3 series can be equipped with oil resistant cables.



■ Safe and reliable

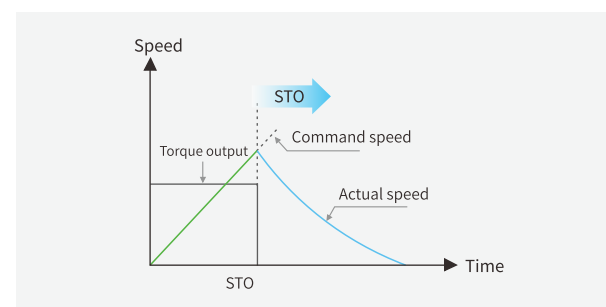
Dynamic braking

- When the motor is running, in the event of a power outage or alarm, the servo will be turned off and the three-phase circuit of the motor will be short circuited. The servo motor will quickly stop, ensuring the safety of operators and machine equipment.



Safe torque off (SIL3 level)

- Support STO. When the safe torque function is enabled, the internal hardware circuit of the driver will trigger, forcibly shutting down the power transistor of the driver, causing the motor to stop running and protecting personal and equipment safety.



Multiple protection functions

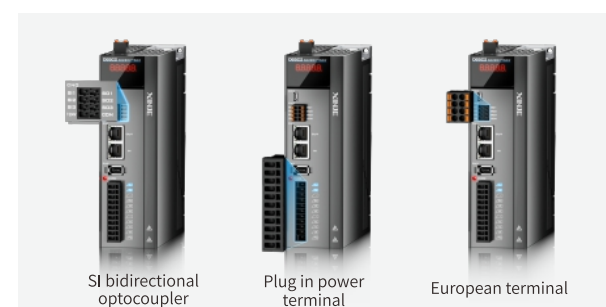
- Support multiple protection functions, such as P+ overcurrent protection, ground short circuit protection, P- overcurrent protection, etc., with ultra-low failure rate, users can use it with peace of mind.



■ Stable and easy to use

Easy to wiring and quickly debug

- Easy to operate terminal design improves wiring efficiency and saves maintenance time.
- Adopting standard RJ45 industrial Ethernet fast interface, greatly improves wiring efficiency.
- Gain adjustment free, strong parameter applicability.
- Users do not need complex gain tuning, debugging is simple and convenient, and can greatly shorten debugging time.



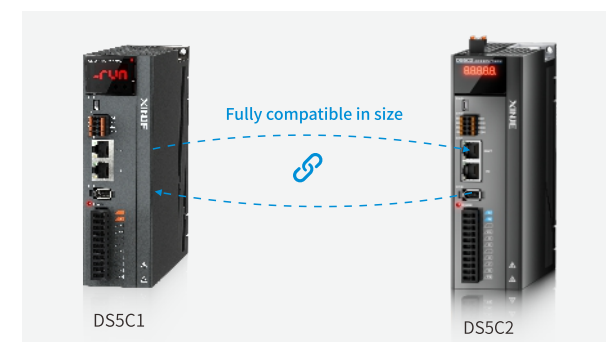
The system runs more smoothly and has higher positioning accuracy

- Suitable for MS6-B3 series high protection single/multi turn integrated motors, with simpler and more convenient selection.
- Lower speed and torque fluctuations assist in the smooth operation of torque control equipment.



Compatible in size and accessible for machine replacement

- The DS5C2 series is fully compatible with the DS5C1 series (same power range), ensuring worry free replacement.



MS6-B4 series servo motor



■ Ultra short body

- After optimizing the magnetic circuit and structural design, the motor body is shorter than similar products.
- Compared with B1 motor, B4 motor has a maximum body reduction of 33%.
- The body length of the 400W non brake motor is only 80.2mm, and the body length of the 750W non brake motor is only 89.2mm.



■ Higher precision

- Equipped with a 17-bit high-resolution encoder, it can help servo motors improve their low-speed vibration suppression ability, reduce speed fluctuations, and make the servo system run more smoothly and accurately.



■ High protection level

- The MS6 series B4 motor has further upgraded its structural design, with a body protection level of up to IP67.



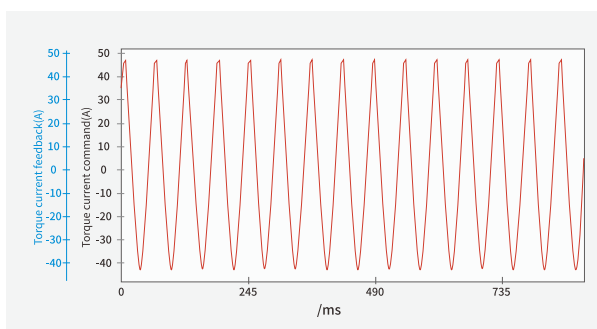
MS6S-130 series servo motor

Instantaneous response | precision control | efficient and stable



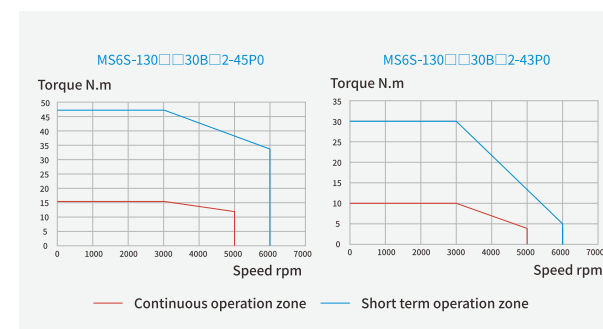
■ Lower inertia, higher response

- Stronger acceleration and deceleration rapid response capability, higher motor overload capacity.



■ Higher speed

- The rated speed of the MS6S series 130 flange motor has been increased to 3000rpm, and the maximum speed has been increased to 6000rpm.



■ Higher precision

- 19-bit/23-bit absolute value encoders are optional.



■ Higher protection level

- The protection level of the MS6H-130 series motor is IP65, and the MS6S-130 series has optimized the motor structure, raising the protection level to IP67. It is dustproof and waterproof, and is not afraid of harsh environments.



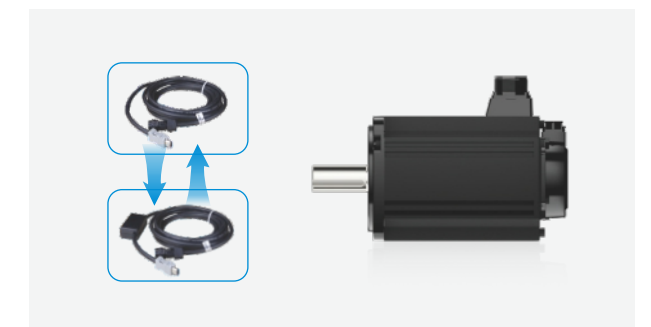
■ More reliable

- The installation design of the front cover bearing adopts larger specifications of bearings, resulting in a longer motor life and stronger reliability.



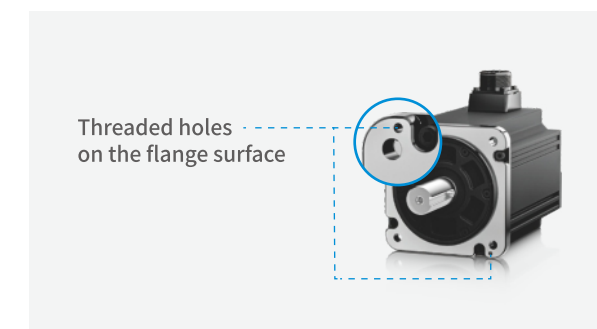
■ Simple selection and flexible configuration

- Standard single/multi turn integrated encoder, when switching between single/multi turn, only the encoder cable (battery box) needs to be replaced.



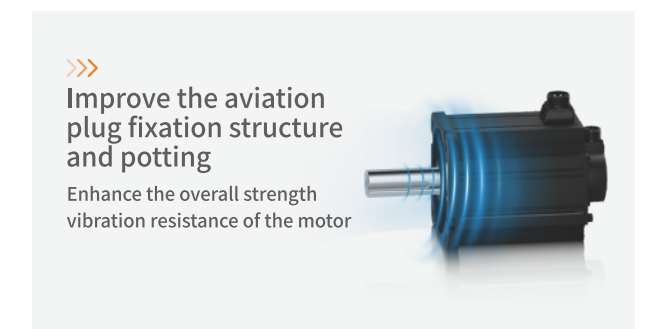
■ Easy to disassemble and assemble

- Add threaded holes on the flange surface throughout the whole series to facilitate assembly and disassembly.



■ Optimized design for greater stability

- To enhance the overall strength and vibration resistance of the motor, a new body structure design has been adopted. Measures such as potting the stator, optimizing the rotor bearing fixation method, improving the aviation plug fixation method, and reducing the height of the aviation plug have been implemented to make the motor more stable and reliable.



MS6G-130 series servo motor

The best choice for compact device scenarios

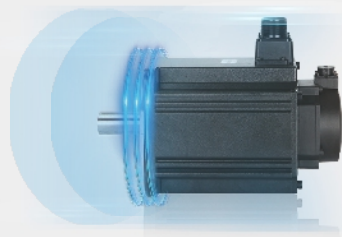
■ Reliable operation

- By integrating the end cap and body, improving the fixed structure of the aviation plug and potting, the overall strength and vibration resistance ability of the motor can be enhanced.



End cap and body integration, improve the aviation plug fixation structure and potting

Enhance the overall strength
vibration resistance of the motor



- 17-bit/19-bit/23-bit absolute value encoders are optional.



Adapt to multiple encoders

17-bit, 19-bit, 23-bit
absolute value encoders are
optional

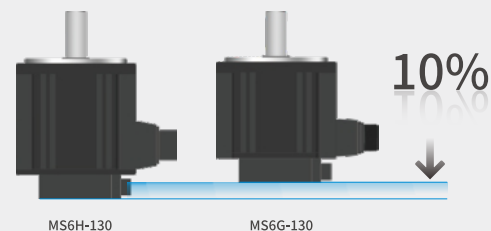
- Low temperature rise and low noise.



■ Shorter body

- Compared with the MS6H series high inertia servo motor, the MS6G series has a shorter body, about 10% shorter, making it more suitable for compact equipment scenarios.
- Black body, matte texture, effectively reduces the tactile temperature on the surface of the motor body.

*Note: Taking 1.5kW as an example.



■ Ultra protection

- The protection level of the MS6H-130 series B2 motor is IP65, and the MS6G-130 series has optimized the motor structure, raising the protection level to IP67, dustproof and waterproof, and is not afraid of harsh environments.



MS6G-180 series servo motor

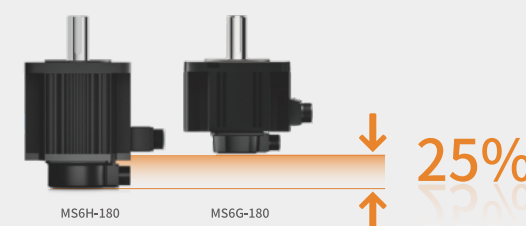
Short body | High reliability | More precise positioning



■ Lightweight design, shorter body

- Compared with the MS6H series servo motor, the MS6G series has a body length reduction of about 25%, more competent in compact equipment scenarios.
- The black body and frosted texture effectively reduce the tactile temperature on the surface of the motor body.

*Note: Taking 3kW as an example.

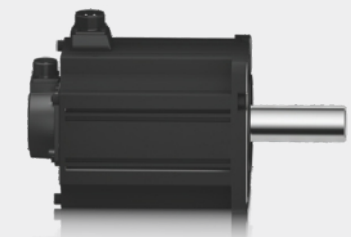


The body length of the 3kW non brake motor is only **162mm**

The body length of the 4.4kW non brake motor is only **185mm**

■ High precision encoder for more accurate positioning

- 19-bit and 23-bit absolute value encoders can be selected for higher positioning accuracy.



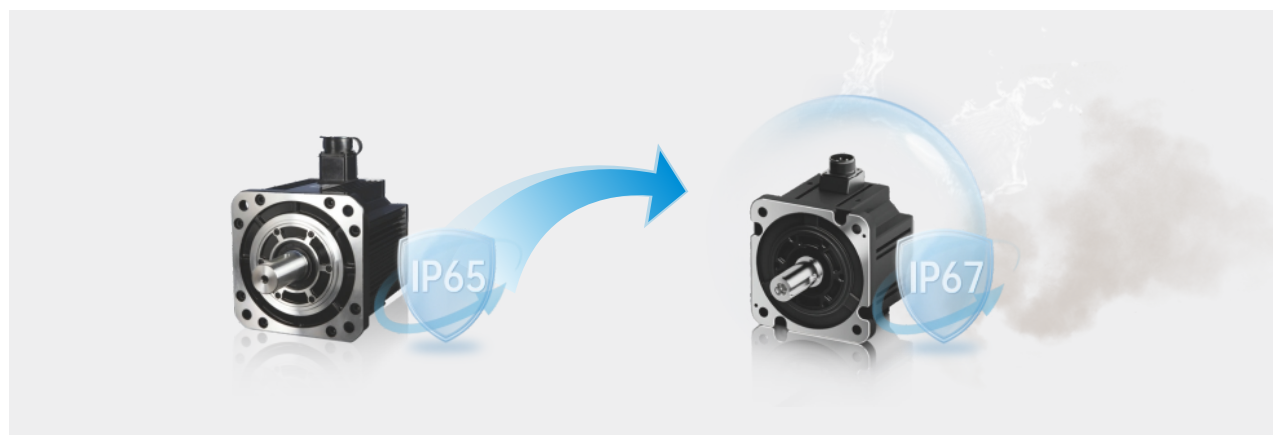
Compatible with various encoders

19-bit / 23-bit

MS6G-180 series servo motor

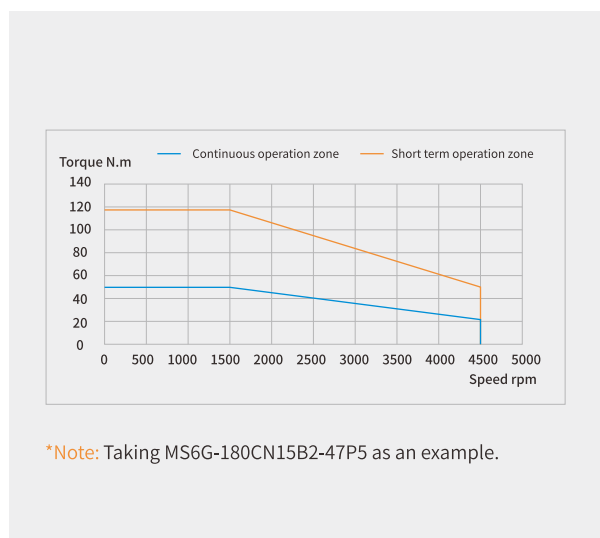
■ High protection level, fearless of harsh environments

- The protection level of the MS6H-180 series B2 motor is IP65, and the MS6G-180 series has optimized the motor structure, raising the protection level to IP67, dustproof and waterproof, and is not afraid of harsh environments.



■ Ultra-high overspeed capability

- The motor has an ultra-high weak magnetic field expansion capability, increasing the maximum operating speed to 4500rpm.



■ Improved vibration resistance and more reliable operation

- To enhance the overall strength and vibration resistance of the motor, a new body structure design has been adopted, along with measures such as stator potting, optimizing the rotor bearing fixation method, improving the fixation method for aviation plug, and reducing the height of the aviation connectors. These measures make the motor more stable and reliable.



■ Simple selection and flexible configuration

- The MS6G-180 series motor comes standard with a single/multi turn integrated encoder. When switching between single turn and multi turn, only the encoder cable (battery box) needs to be replaced.

Liquid cooled servo motor

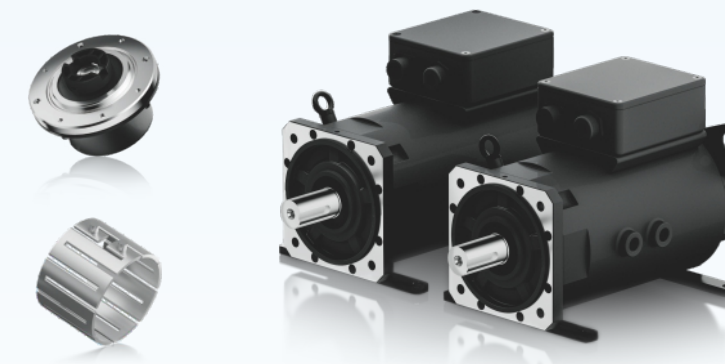
High precision | Low temperature rise High reliability | High protection

■ High reliability

- Using a cross-coupling installation method for the encoder enhances vibration and impact resistance.
- The rotor features a built-in structure, significantly improving the motor's resistance to demagnetization.

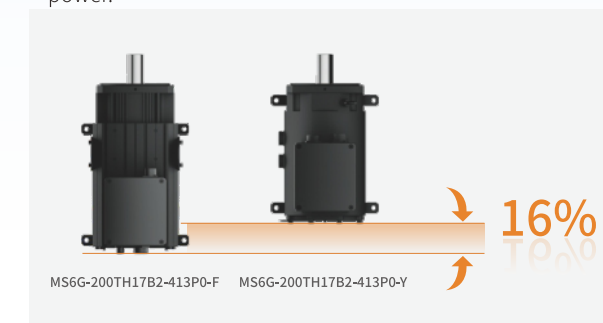
■ Low temperature rise

- An axial Z-shaped water channel structure design is used, with cooling fluid for heat dissipation, significantly reducing the motor's temperature rise.



■ High power density

- Compact structural design, with a body length shortened by about 16% compared to air-cooled motors of the same power.



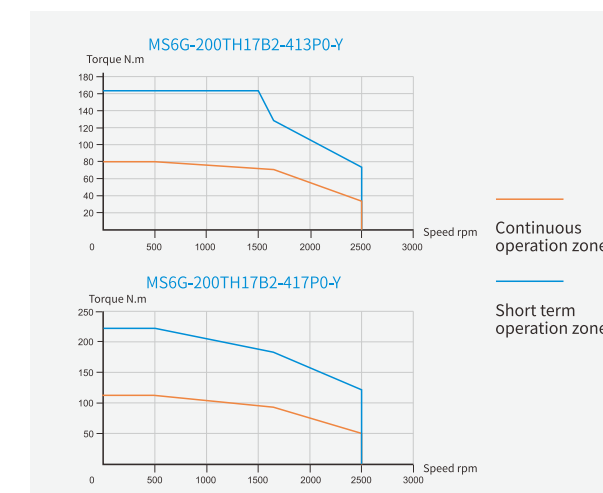
■ High-precision

- Standard 23-bit high-precision absolute value optical encoder.



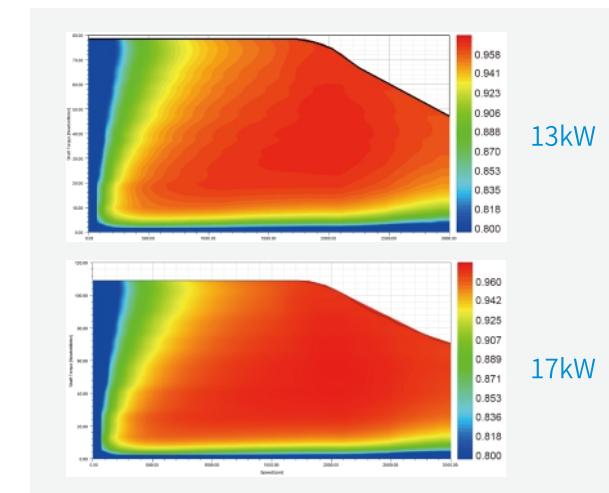
■ High performance

- New electromagnetic scheme design, compatible with DS5C2/DM6C series high-performance servo drivers to meet high dynamic response requirements.



■ High energy efficiency

- By optimizing the motor's magnetic circuit design and selectively using materials with low losses, such as silicon steel sheets and oil seals, the overall losses of the motor are effectively controlled, achieving a high-efficiency motor design.



Typical applications

■ Mechanical arm

The robotic arm is the most widely used automated mechanical device in the field of robotics technology, and its presence can be seen in industrial manufacturing, medical treatment, entertainment services, military, semiconductor manufacturing, and space exploration. Although they have different forms, they all share a common feature of being able to receive instructions and accurately locate a certain point in three-dimensional (or two-dimensional) space.



■ High speed cutting machine

High speed cutting machine combines ultrasonic welding technology with traditional cutting. When the ultrasonic generator is working, the ultrasonic energy is transmitted to the welding head through the ultrasonic transducer and violently vibrates and rubs against the cutting die, thereby achieving the cutting effect, making the cut products more beautiful, sturdy, and efficient in production.



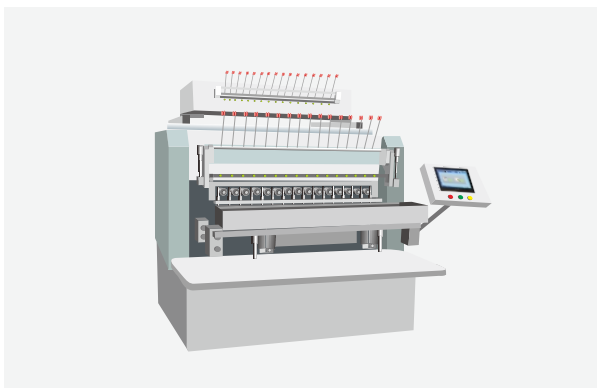
■ Rotary die cutting machine

The rotary die cutting machine performs die cutting processing with the continuous rotation of a rotary cutter and is one of the most efficient types of die cutting machines. The circular blade die cutting achieves the purpose of die cutting by compressing the material between the cutting edge and the anvil roll. This improves both the speed and precision of die cutting. Additionally, it can achieve one-time product forming through multi-axis registration die cutting, overcoming the disadvantages of traditional multiple die cutting processes.



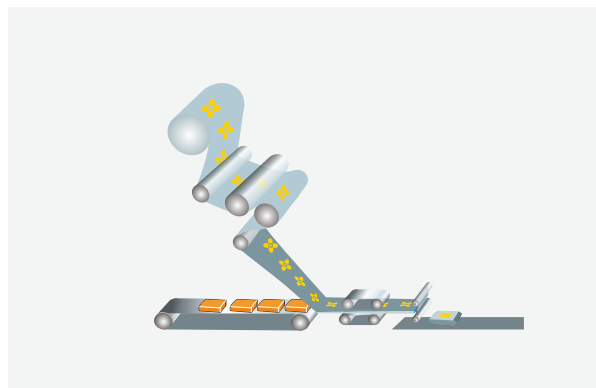
■ 16-axis high-speed winding machine

A high-speed winding machine is equipment used to wind linear objects onto specific workpieces, commonly used for winding copper wire. Traditionally, high-speed winding was achieved by combining a variable frequency motor with a tension control system. However, with the increasing demand for efficiency in modern industry, servos can replace the original variable frequency motors to achieve high-speed and highly efficient production.



■ Three-servo packaging machine

Packaging machinery refers to machines that can complete all or part of the packaging process for products and goods. The packaging process includes main operations such as filling, wrapping, and sealing, as well as related pre- and post-operations like cleaning, stacking, and disassembling. Additionally, packaging can involve operations such as measuring and stamping on the package. Using machinery to package products can improve productivity, reduce labor intensity, accommodate the needs of large-scale production, and meet cleanliness and hygiene standards.



XINJE SERVO software

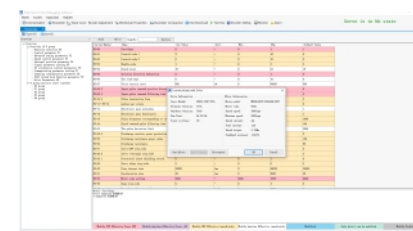
Help users better understand the operation of the equipment



■ Servo communication interface

Efficient and fast communication identification

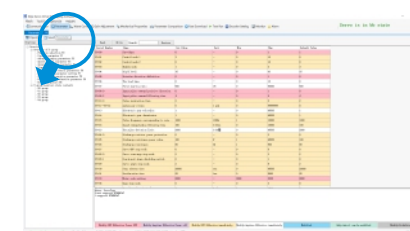
Xinje servo software can do Modbus-RTU communication with servo driver through RS232, and can automatically read motor parameters without viewing motor code.



■ Parameter setting interface

Intuitive and understandable parameter setting

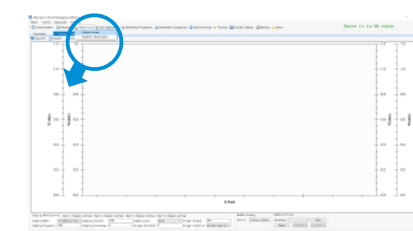
Xinje servo software has the functions of reading, modifying, saving and downloading, and is equipped with detailed parameter description. The parameter list directly indicates the effective time of parameters with different colors, which makes the distinction more eye-catching.



■ Curve acquisition interface

Convenient and practical curve acquisition

Xinje servo software has powerful servo data acquisition function, including speed, position, current, bus voltage and other basic information acquisition. Help you have a deeper and comprehensive understanding of servo operation and improve the control scheme.

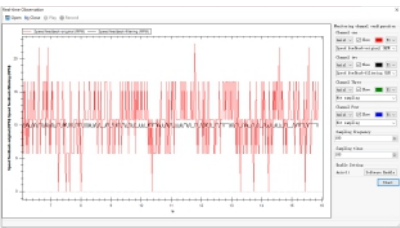


XINJE SERVO software

Real time observation interface

Real time dynamic curve observation

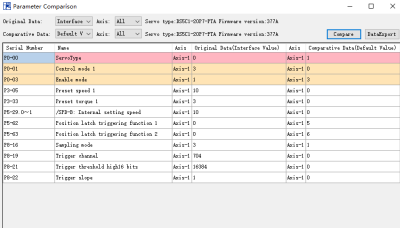
Xinje servo software can collect basic information such as speed, torque, position and bus voltage to help you understand the servo operation in real time and adjust the control scheme efficiently and timely.



Parameter comparison interface

Simple and clear parameter comparison

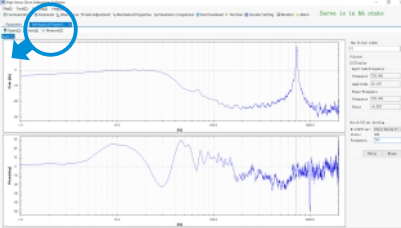
The parameter comparison function of Xinje servo software allows customers to easily compare preset values, current driver values, file values, and pairwise comparison of the current upper computer interface.



Mechanical property measurement interface

Precise resonance recognition

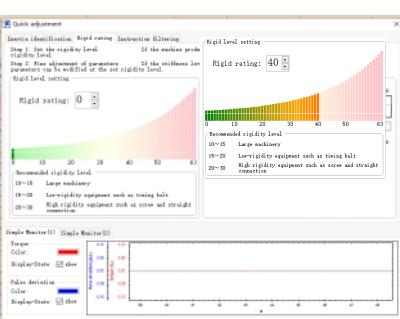
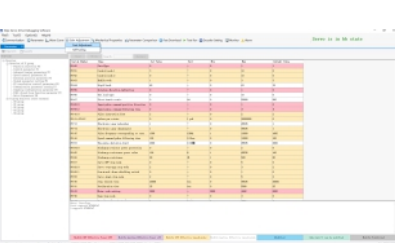
Xinje software has the function of mechanical characteristic measurement, which can automatically measure the resonance frequency according to the operation of mechanical load. It is equipped with five notch filters to ensure the stable and reliable operation of the equipment and sweep away the load vibration.



Gain adjustment interface

Fast adjustment

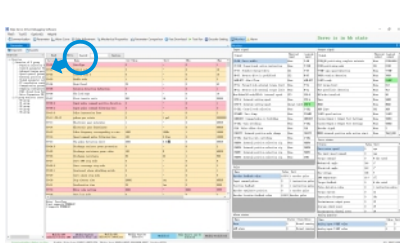
The fast adjustment / self-tuning mode can identify the inertia. The user can configure the appropriate mode, method, load type, foundation and other parameters according to the equipment operation status for the upper computer to set the best gain parameters, or adjust the rigidity level according to the equipment operation status.



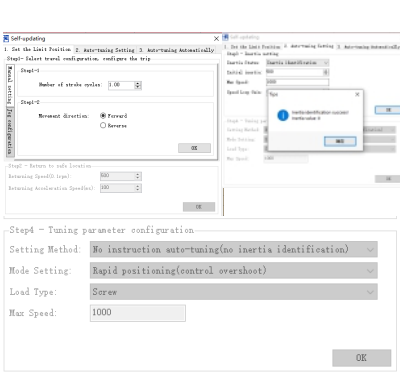
Monitor interface

Rich and comprehensive real-time monitoring

Xinje servo software has real-time status, alarm monitor and servo operation status, which are all under your control.



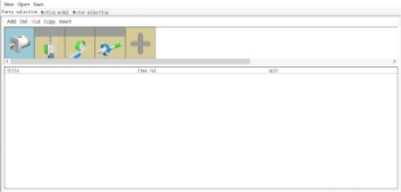
Self-tuning interface



Tool interface

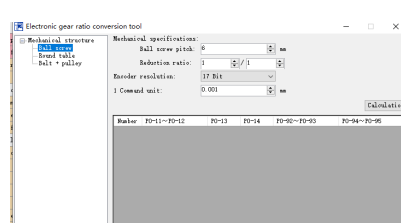
Motor selection tool

Xinje servo software has its own motor selection tool, which automatically matches the best motor model through the selection of equipment components and the establishment of motion model.



Electronic gear ratio conversion

Xinje servo software can accurately calculate the number of pulses per revolution and electronic gear ratio of screw, disc and pulley mechanical structures according to the mechanical specifications.



Naming rule

DS5 series servo driver naming rule

DS 5 - P - PTA - H

① Name

Symbol	Product name
DS	Servo driver

② Series

Symbol	Product series
5	Series 5

③ Type

Symbol	Product series
L	Basic pulse type
K	Standard pulse type
C	EtherCAT bus type
P	Profinet bus type

④ Product version

Symbol	Version
1	Compact
2	High-Performance
5	Flagship

⑤ Voltage specification

Symbol	Rated input voltage
2	AC220V
4	AC380V

⑥ Driver power

Symbol	Rated output power (kW)
0P1	0.1
0P2	0.2
0P4	0.4
0P7	0.75
1P0	1.0
1P5	1.5
2P3	2.3
2P6	2.6

Symbol	Rated output power (kW)
3P0	3.0
5P5	5.5
7P5	7.5
11P0	11
15P0	15
22P0	22
32P0	32
45P0	45

⑦ Encoder specification

Symbol	Encoder specification
T	Communication type encoder

⑧ Product type

Symbol	Product type
default	Standard driver
H	Enhanced driver
FH	High protection driver
FS	STO model driver

DS5 series servo driver model list

Power[kW]	Series	DS5L2 series Compact pulse type enhanced version	DS5C2 series Compact bus type enhanced version	DS5K2 series Compact standard type enhanced version	DS5L1 series Compact pulse type	DS5C1 series Compact bus type	DS5P series PROFINET bus type
0.1		DS5L2-20P1-PTA	DS5C2-20P1-PTA	DS5K2-20P1-PTA	DS5L1-20P1-PTA	DS5C1-20P1-PTA	DS5P-20P1-PTA
0.2		DS5L2-20P2-PTA	/	/	DS5L1-20P2-PTA	DS5C1-20P2-PTA	DS5P-20P2-PTA
0.4		DS5L2-20P4-PTA	DS5C2-20P4-PTA	DS5K2-20P4-PTA	DS5L1-20P4-PTA	DS5C1-20P4-PTA	DS5P-20P4-PTA
0.75		DS5L2-20P7-PTA	DS5C2-20P7-PTA	DS5K2-20P7-PTA	DS5L1-20P7-PTA	DS5C1-20P7-PTA	DS5P-20P7-PTA
1.0		DS5L2-21P0-PTA	DS5C2-21P0-PTA	DS5K2-21P0-PTA	DS5L1-21P0-PTA	DS5C1-21P0-PTA	DS5P-21P0-PTA
1.5		DS5L2-21P5-PTA	DS5C2-21P5-PTA	DS5K2-21P5-PTA	DS5L1-21P5-PTA	DS5C1-21P5-PTA	DS5P-21P5-PTA
2.3		DS5L2-22P3-PTA	DS5C2-22P3-PTA	DS5K2-22P3-PTA	DS5L1-22P3-PTA	DS5C1-22P3-PTA	DS5P-22P3-PTA
2.6		DS5L2-22P6-PTA	DS5C2-22P6-PTA	DS5K2-22P6-PTA	DS5L1-22P6-PTA	DS5C1-22P6-PTA	DS5P-22P6-PTA
3.0		DS5L2-41P0-PTA	DS5C2-41P0-PTA	DS5K2-41P0-PTA	DS5L1-41P0-PTA	DS5C1-41P0-PTA	DS5P-41P0-PTA
1.5		DS5L2-41P5-PTA	DS5C2-41P5-PTA	DS5K2-41P5-PTA	DS5L1-41P5-PTA	DS5C1-41P5-PTA	DS5P-41P5-PTA
2.3		DS5L2-42P3-PTA	DS5C2-42P3-PTA	DS5K2-42P3-PTA	DS5L1-42P3-PTA	DS5C1-42P3-PTA	DS5P-42P3-PTA
3.0		DS5L2-43P0-PTA	DS5C2-43P0-PTA	DS5K2-43P0-PTA	DS5L1-43P0-PTA	DS5C1-43P0-PTA	DS5P-43P0-PTA
5.5		/	DS5C2-45P5-PTA	DS5K2-45P5-PTA	/	DS5C1-45P5-PTA	DS5P-45P5-PTA
7.5		/	DS5C2-47P5-PTA	DS5K2-47P5-PTA	/	DS5C1-47P5-PTA	DS5P-47P5-PTA
11		/	/	/	/	DS5C1-411P0-PTA	/
15		/	DS5C2-415P0-PTA	/	/	DS5C1-415P0-PTA	/
22		/	DS5C2-422P0-PTA (在研)	/	/	DS5C1-422P0-PTA	/
32		/	DS5C2-432P0-PTA (在研)	/	/	DS5C1-432P0-PTA	/
45		/	/	/	/	DS5C1-445P0-PTA	/

DS5 series servo driver specification list

DS5 driver specification													
Function	Control mode				Control method								
	Position control	Speed control	Torque control	Bus control	Pulse	Long line drive	Analog input	External displacement sensor	ABZ differential feedback	RS232	RS485	SI input	SO output
Pulse type DS5L1/L2 series	●	●	●		●					●	●	3	3
EtherCAT type DS5C1/C2 series	●	●	●	●						●		3	3
Standard type DS5K2 series	●	●	●		●	●	●		●	●	●	8	6
Profinet type DS5P series	●	●	●	●						●		5	3

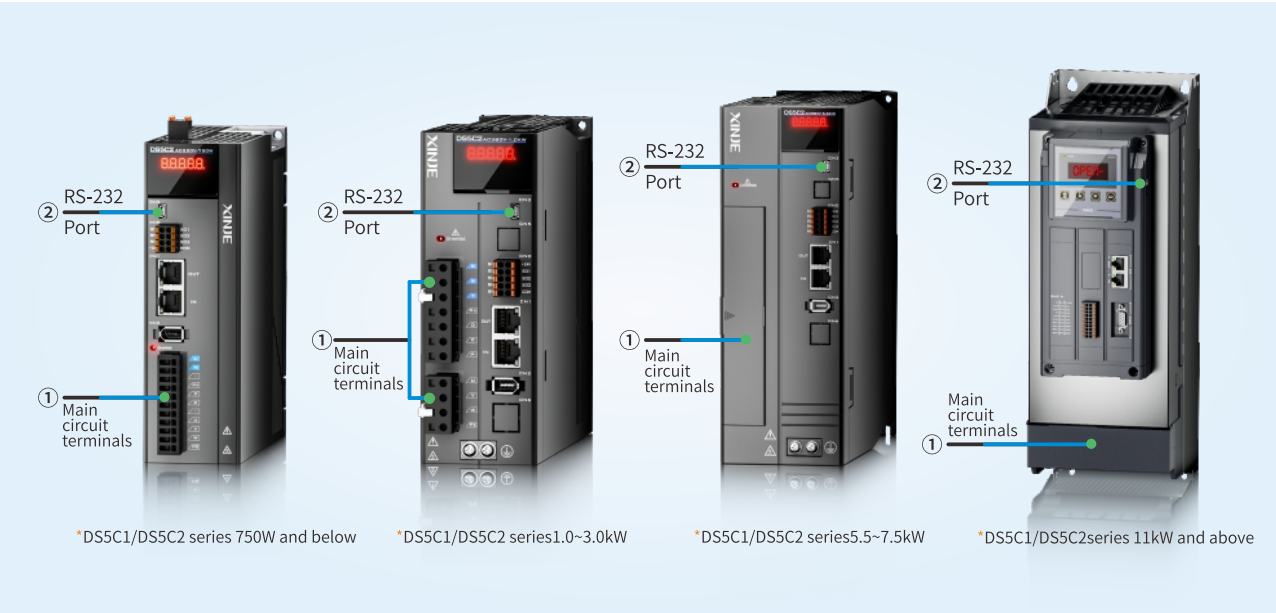
*Note: The DS5L1/L2/C1/C2 series 1kW-7.5kW servo drivers have 5 inputs and 3 outputs, the DS5C1/C2 series 11kW and above drivers have 5 inputs and 4 outputs, and the DS5C1/C2 series 11kW and above drivers support pulse control mode.

Technical specification

Specification	Model	Pulse type	EtherCAT bus type	Standard type	PROFINET bus type
		DS5L1 series/DS5L2 series	DS5C1 series/DS5C2 series	DS5K2 series	DS5P series
Basic specification	Power range(kW)	0.1~3.0/0.1~3.0	0.1~45.0/0.1~32.0	0.1~7.5	0.1~7.5
	Input power supply	Single phase/three-phase AC200~240V, 50Hz/60Hz; Three phase AC380V~440V, 50Hz/60Hz			
	Encoder feedback	17bit/19bit/23bit communication encoder			
	Control method	Three phase full wave rectification IPM, PWM control, sine wave current drive mode			
	Ambient temperature	Operation: -10℃~40℃ (no condensation) / storage: -20℃~60℃ (no condensation)			
	Ambient humidity	Operation/Storage: below 90%RH (no condensation)			
	Vibration/impact resistance	4.9m/s ² / 19.6m/s ²			
	Electronic cam	no			
	Protection function	Overvoltage, undervoltage, overheating, overcurrent, overload, overspeed, analog input abnormality, excessive position deviation, output short circuit, encoder abnormality, regeneration abnormality protection, overtravel protection, oscillation protection, phase loss protection, etc			
	Dynamic brake	DS5L2, DS5L1(1~3kW) standard configured	DS5C2, DS5C1(1~7.5kW) standard configured	DS5K2 standard configured	no
	Communication function	RS232: Standard ModbusRTU protocol RS485: Standard ModbusRTU protocol	RS232: Standard ModbusRTU protocol EtherCAT: EtherCAT bus communication	RS232: Standard ModbusRTU protocol RS485: Standard ModbusRTU protocol	RS232: Standard ModbusRTU protocol Profinet: Profinet bus communication
	Braking resistor	750W~3.0kW with built-in resistor			21P0 and above with built-in resistor
	Display and operation	5-digit LED indicator light, power indicator light, 4 operation buttons			
Position output	Output form	no	ABZ differential feedback output	no	
	Frequency division function	no	Yes	no	
	Collector Z-phase output	Yes			
	Analog input	no	Yes	no	
I/O signal	Digital input (SI)	3channels (750Wand below) 5channels (above750W)	3channels (750Wand below) 5channels (above750W)	8 channels	5 channels
	Digital output (SO)	3 channels	3 channels (below11kW) 4 channels (11kW and above)	6 channels	3 channels
Position control mode	Maximum input pulse frequency	Collector open circuit: 200kpps(optocoupler) Differential input: 500kpps (optocoupler)	Collector open circuit: 200kpps(optocoupler) Differential input: 500kpps (optocoupler) (11kW and above supported)	Collector open circuit: 200kpps(optocoupler) Differential input: 500kpps (optocoupler)	Not support
	Pulse command mode	3.3V-5V/18-24V pulse+direction, AB phase pulse, CW/CCW signal	3.3V-5V/18-24V pulse+direction, AB phase pulse, CW/CCW signal	3.3V-5V/18-24V pulse+direction, AB phase pulse, CW/CCW signal	Not support
	Control mode	External pulse/internal position	Internal position/EtherCAT motion bus	External pulse/internal position	PROFINET motion bus/internal position
	Feedforward compensation	0~100% (set resolution to 1%)			
	Positioning completed width setting	1~65535 instruction units (set resolution to 1 instruction unit)			
Speed control mode	Electronic gear ratio	1/65530≤B/A≤65535			
	Control mode	Analog speed control (only supported by DS5K2), internal three-stage speed, external speed mode			
	Command smoothing mode	Low-pass filter, smoothing filter			
	Analog input	Voltage range	no	-10V~+10V	no
	Input impedance	no	no	72KΩ	no
Torque control mode	Torque limit	Internal parameters		Internal parameters/external analog value	Internal parameters
	Rate of speed change	When the rated external load changes from 0 to 100%: less than ±0.01% (at rated speed)			
		Rated voltage ±10%: 0.01% (at rated speed)			
		Environmental temperature 20±25℃: less than ±0.01% (at rated speed)			
Bus control mode	Control mode	Analog torque control (only supported by DS5K2), internal torque			
	Analog input	Voltage range	no	-10V~+10V	no
	Input impedance	no	no	72KΩ	no
	Speed limit	Internal parameters		Internal parameters/external analog value	Internal parameters
Bus control mode	Communication protocol	no	EtherCAT protocol	no	PROFINET protocol

Terminal definition

DS5C1/DS5C2 series



① Main circuit terminal definition

DS5C1/DS5C2-20P1/20P2/20P4-PTA

Terminal	Function	Explanation
L/N	Main circuit power input terminal	Single phase 200~240V, 50/60Hz
●	Empty pin	/
P+, C	Use external regenerative resistor	Connect the regenerative resistor to the P+ and C terminals. P0-25=power value, P0-26=resistance value
U, V, W, PE	Motor connection terminal	Connect to the motor

DS5C1/DS5C2-20P7-PTA

Terminal	Function	Explanation
L/N	Main circuit power input terminal	Single phase 200~240V, 50/60Hz
●	Empty pin	/
P+, D, C	Use built-in regenerative resistor	Short circuit P+ and D terminals, disconnect P+ and C
	Use external regenerative resistor	Connect the regenerative resistor to the P+ and C terminals, and disconnect the P+ and D. Set P0-25=power value, P0-26=resistance value
●	Empty pin	/
U, V, W, PE	Motor connection terminal	Connect to the motor

DS5C1/DS5C2-45P5/47P5-PTA

Terminal	Function	Explanation
R, S, T	Main circuit power input terminal	Three phase 380~440V, 50/60Hz
P+, D, C	Use external regenerative resistor	Connect the regenerative resistor to the P+ and C terminals, and disconnect the P+ and D. Set P0-25=power value, P0-26=resistance value
P+, P-	Bus terminal	Real time voltage of the busbar can be measured, please be aware of the danger
U, V, W	Motor connection terminal	Connect to the motor *Note: The ground wire is on the heat sink, please check before powering on.
⊕	Grounding terminal	Connect to the motor grounding terminal and perform grounding treatment

② RS-232 port

Pin	Name	Explanation
1	TXD	RS232 send
2	RXD	RS232 receive
3	GND	RS232 signal ground

*Note: PE is the grounding terminal.

DS5C1/DS5C2-21P0/21P5/22P3/22P6-PTA

Terminal	Function	Explanation
L1, L2, L3	Main circuit power input terminal	Single/three-phase 200~240V, 50/60Hz
P+, D, C	Use built-in regenerative resistor	Short circuit P+ and D terminals, disconnect P+ and C
	Use external regenerative resistor	Connect the regenerative resistor to the P+ and C terminals, and disconnect the P+ and D. Set P0-25=power value, P0-26=resistance value
P+, P-	Bus terminal	Real time voltage of the busbar can be measured, please be aware of the danger
U, V, W	Motor connection terminal	Connect to the motor *Note: The ground wire is on the heat sink, please check before powering on.
⊕	Grounding terminal	Connect to the motor grounding terminal and perform grounding treatment

DS5C1/DS5C2-41P0/41P5/42P3/43P0-PTA

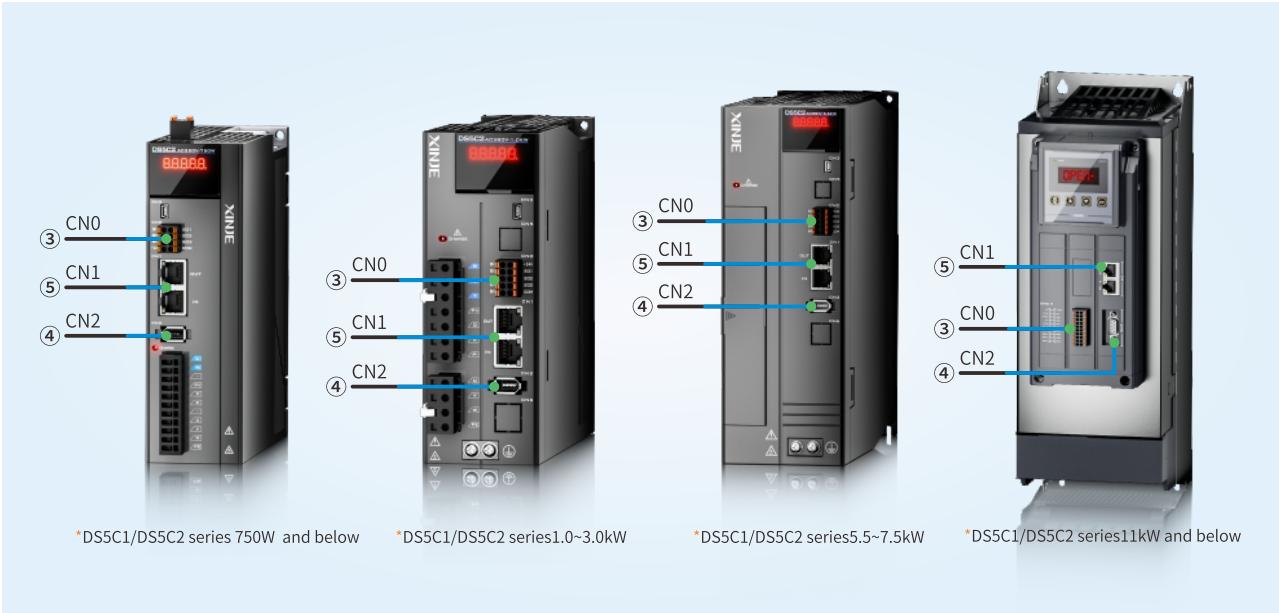
Terminal	Function	Explanation
R, S, T	Main circuit power input terminal	Three phase 380~440V, 50/60Hz
P+, D, C	Use built-in regenerative resistor	Short circuit P+ and D terminals, disconnect P+ and C
	Use external regenerative resistor	Connect the regenerative resistor to the P+ and C terminals, and disconnect the P+ and D. Set P0-25=power value, P0-26=resistance value
P+, P-	Bus terminal	Real time voltage of the busbar can be measured, please be aware of the danger
U, V, W	Motor connection terminal	Connect to the motor *Note: The ground wire is on the heat sink, please check before powering on.
⊕	Grounding terminal	Connect to the motor grounding terminal and perform grounding treatment

DS5C1/DS5C2-411P0/415P0/422P0/432P0/445P0-PTA

Terminal	Function	Explanation
R, S, T	Main circuit power input terminal	Single phase 380~440V, 50/60Hz
●	Empty pin	/
U, V, W	Motor connection terminal	Connect to the motor *Note: The ground wire is on the heat sink, please check before powering on.
P+, PB	Use external regenerative resistor	Connect the regenerative resistor to P+ and PB. Set P0-25=power value, P0-26=resistance value
P+, P-	Bus terminal	Real time voltage of the busbar can be measured, please be aware of the danger
PE, PE	Grounding terminal	Only supported by 11, 15kW

Terminal definition

| DS5C1/DS5C2 series



③ CN0 port

DS5C1/DS5C2 series 750W and below

Pin	Name
SI1	High speed input terminal 1
SI2	High speed input terminal 2
SI3	Ordinary input terminal 3
+24V	Input terminal +24V
SO1	Output terminal 1
SO2	Output terminal 2
SO3	Output terminal 3
COM	Output terminal ground

④ CN2 port

DS5C1/DS5C2 series 0.1~7.5kW

Pin	Name
1	5V
2	GND
3	/
4	/
5	485-A
6	485-B

DS5C1/DS5C2 series 11kW and above

No.	Definition	No.	Definition
1	Temperature-	6	GND
2	Temperature+	7	GND
3	485-B	8	5V
4	485-A	9	5V
5	PE		

DS5C1/DS5C2 series 1~7.5kW

Pin	Explanation	Name	Explanation
SI1	Input terminal 1	24V	+24 input common terminal
SI2	Input terminal 2	SO1	Output terminal 1
SI3	Input terminal 3	SO2	Output terminal 2
SI4	Input Terminal 4 (High Speed)	SO3	Output terminal 3
SI5	Input Terminal 5 (High Speed)	COM	Output terminal ground

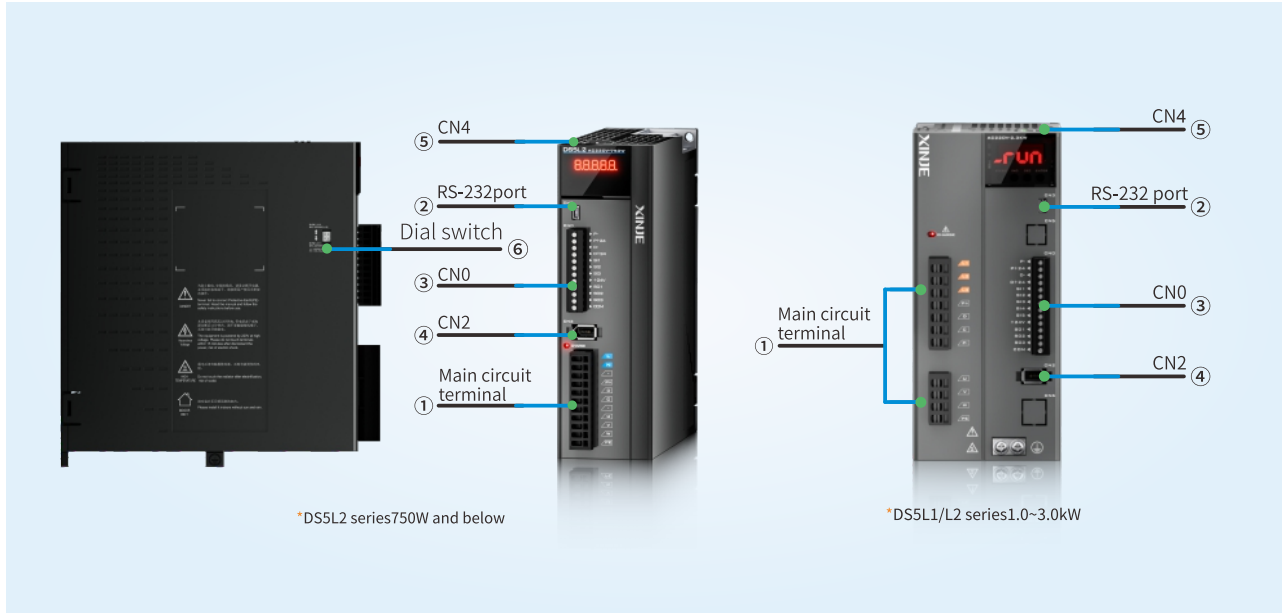
DS5C1/DS5C2 series 11kW and above

Pin	Explanation	Name	Explanation
P-	Pulse-	+24V	Input terminal common terminal
P+5	Pulse +5V	SI1	Input terminal
P+24	Pulse pulse +24V	SI2	Input terminal
D-	Direction-	SI3	Input terminal
D+5	Direction +5V	SI4	Input terminal (high-speed)
D+24	Direction +24V	SI5	Input terminal (high-speed)
SO1+	Output terminal +	SO1-	Output terminal-
SO2+	Output terminal +	SO2-	Output terminal-
SO3+	Output terminal +	SO3-	Output terminal-
SO4+	Output terminal +	SO4-	Output terminal-

⑤ CN1 port

Pin	Name	Explanation
1	TX A+	TRANSMIT A+
2	TX A-	TRANSMIT A-
3	RX A+	RECEIVE A+
4	/	/
5	/	/
6	RX A-	RECEIVE A-
7	/	/
8	/	/
9	TX B+	TRANSMIT B+
10	TX B-	TRANSMIT B-
11	RX B+	RECEIVE B+
12	/	/
13	/	/
14	RX B-	RECEIVE B-
15	/	/
16	/	/

| DS5L1/L2 series



① Definition of main circuit terminals

DS5L1/L2-20P1/20P2/20P4-PTA

Terminal	Function	Explanation
L/N	Main circuit power input terminal	Single phase 200~240V, 50/60Hz
●	Empty pin	/
P+, C	Use external regenerative resistor	Connect the regenerative resistor to the P+ and C terminals.
U, V, W, PE	Motor connection terminal	Connect to the motor

DS5L1/L2-20P7-PTA

Terminal	Function	Explanation
L/N	Main circuit power input terminal	Single phase 200~240V, 50/60Hz
●	Empty pin	/
P+, D, C	Use built-in regenerative resistor	Short circuit P+ and D terminals, disconnect P+ and C
	Use external regenerative resistor	Connect the regenerative resistor to the P+ and C terminals, and disconnect the P+ and D. Set P0-25=power value, P0-26=resistance value
●	Empty pin	/
U, V, W, PE	Motor connection terminal	Connect to the motor

② RS-232 port

Pin	Name	Explanation
1	TXD	RS232 send
2	RXD	RS232 receive
3	GND	RS232 signal ground

④ CN2 port

Pin	Name	Pin	Name
1	5V	4	/
2	GND	5	485-A
3	/	6	485-B

⑤ CN4-485 port

Pin	Name
4	485-A
5	485-B
6	485-GND
Others	RESERVED

⑥ Dial switch

Dial 1	Dial 2	Status
ON	ON	Pulse input differential 5V
OFF	OFF	Pulse input collector 24V

*Note: The directions of the two dials must be consistent. If they are not consistent, once the driver pulse terminal is powered on, the pulse terminal will be burned out.

*Note: PE is the grounding terminal.

DS5L1/L2-21P0/21P5/22P3/22P6-PTA

Terminal	Function	Explanation
L1, L2, L3	Main circuit power input terminal	Single/three-phase 200~240V, 50/60Hz
	Use built-in regenerative resistor	Short circuit P+ and D terminals, disconnect P+ and C
P+, D, C	Use external regenerative resistor	Connect the regenerative resistor to the P+ and C terminals, and disconnect the P+ and D. Set P0-25=power value, P0-26=resistance value
P+, P-	Bus terminal	Real time voltage of the busbar can be measured, please be aware of the danger
U, V, W	Motor connection terminal	Connect to the motor
⊕	Grounding terminal	Connect to the motor grounding terminal and perform grounding treatment

DS5L1/L2-41P0/41P5/42P3/43P0-PTA

Terminal	Function	Explanation
R, S, T	Main circuit power input terminal	Three phase 380~440V, 50/60Hz
	Use built-in regenerative resistor	Short circuit P+ and D terminals, disconnect P+ and C
P+, D, C	Use external regenerative resistor	Connect the regenerative resistor to the P+ and C terminals, and disconnect the P+ and D. Set P0-25=power value, P0-26=resistance value
P+, P-	Bus terminal	Real time voltage of the busbar can be measured, please be aware of the danger
U, V, W	Motor connection terminal	Connect to the motor
⊕	Grounding terminal	Connect to the motor grounding terminal and perform grounding treatment

③ CN0 port

DS5L1/L2 series 750W and below

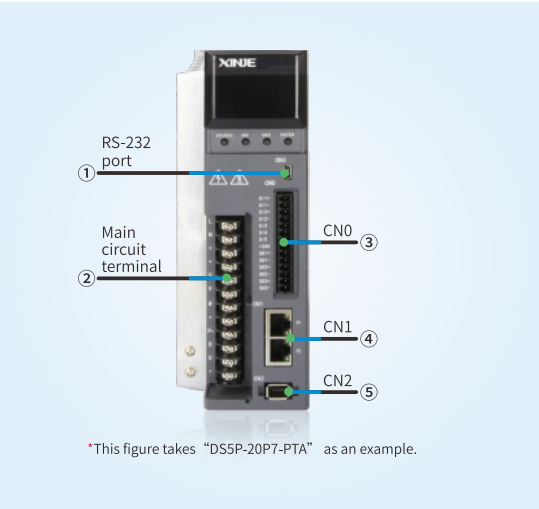
Pin	Name
P-	Pulse input PUL-
P+24(5V)	Pulse input external power supply
D-	Direction input DIR-
D+24(5V)	Directional input external power supply
SI1	Input terminal 1
SI2	Input terminal 2
SI3	Input terminal 3
+24V	Input terminal +24V
SO1	Output terminal 1
SO2	Output terminal 2
SO3	Output terminal 3
COM	Output terminal ground

DS5L1/L2 series above 750W

Pin	Name
P-	Pulse input PUL-
P+24(5V)	Collector open circuit input
D-	Direction input DIR-
D+24(5V)	Collector open circuit input
SI1	Input terminal 1
SI2	Input terminal 2
SI3	Input terminal 3
SI4	Input terminal 4
SI5	Input terminal 5
+24V	Input +24V
SO1	Output terminal 1
SO2	Output terminal 2
SO3	Output terminal 3
COM	Output terminal ground

Terminal definition

| DS5P series



① RS-232 port

Pin	Name	Explanation
1	TXD	RS232 send
2	RXD	RS232 receive
3	GND	RS232 signal ground

② Definition of main circuit terminals

Terminal	Function	Explanation
L/N R/S/T	Main circuit power input terminal	Single/three-phase AC200~240V, 50/60Hz Three phase AC380~440V, 50/60Hz
●	Empty pin	/
U/V W/PE	Motor connection terminal	Connect to the motor Note: The ground wire is on the heat sink. Please check before powering on
P+, D, C	Use built-in regenerative resistor	Short circuit P+ and D terminals, disconnect P+ and C
	Use built-in regenerative resistor	Connect the regenerative resistor to the P+ and C terminals, and disconnect the P+ and D, P0-25=power value, P0-26=resistance value

③ CN0 port

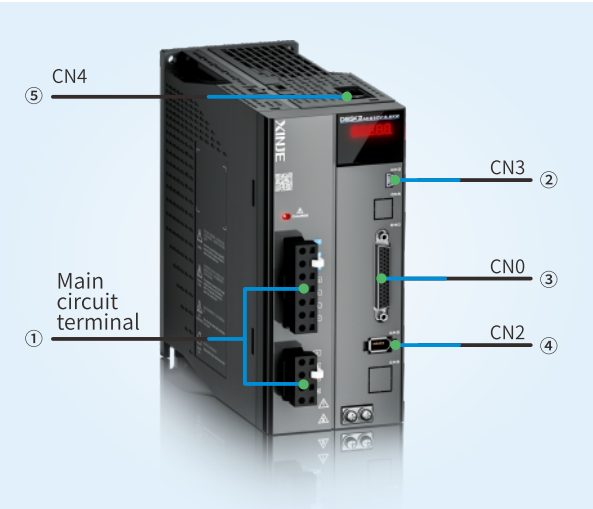
Name	Explanation	Name	Explanation
SI1+	High speed S1+	24V	Input common terminal
SI1-	High speed S1-	SO1+	Output terminal
SI2+	High speed S1+	SO1-	Output terminal
SI2-	High speed S1-	SO2+	Output terminal
SI3	Input terminal	SO2-	Output terminal
SI4	Input terminal	SO3+	Output terminal
SI5	Input terminal	SO3-	Output terminal

⑤ CN2 port

Pin	Name
1	5V
2	GND
3	/
4	/
5	485-A
6	485-B

Terminal definition

| DS5K2 series



② RS-232 port

Pin	Name	Explanation
1	TXD	RS232 send
2	RXD	RS232 receive
3	GND	RS232 signal ground

③ CN0 port

No.	Name	Explanation	No.	Name	Explanation
1	P-	Pulse-	23	SI4	Input terminal
2	P+5	Pulse +5V	24	SI6	Input terminal
3	P+24	Pulse +24V	25	SI7	Input terminal
4	D-	Direction-	26	GND	Long line drive ground
5	D+5	Direction +5V	27	SI8+	High speed input terminal
6	D+24	Direction +24V	28	SI8-	High speed input terminal
7	SO1	Output terminal	29	SI5	High speed input terminal
8	SO2	Output terminal	30	+24V	High speed input terminal
9	SO3	Output terminal	31	T-REF+	External torque analog differential input+
10	SO4	Output terminal	32	T-REF-	External torque analog differential input-
11	SO5+	Output terminal	33	V-REF+	External speed analog differential input+
12	SO5-	Output terminal	34	V-REF-	External speed analog differential input-
13	SO6+	Output terminal	35	OA+	Encoder frequency division output OA+
14	SO6-	Output terminal	36	OA-	Encoder frequency division output OA-
15	COM	Output common terminal	37	OB+	Encoder frequency division output OB+
16	NC	Reserved	38	OB-	Encoder frequency division output OB-
17	NC	Reserved	39	OZ+	Encoder frequency division output OZ+
18	NC	Reserved	40	OZ-	Encoder frequency division output OZ-
19	GND	Analog input ground	41	HPUL+	Long line drive high-speed pulse+
20	SI1	Input terminal	42	HPUL-	Long line drive high-speed pulse-
21	SI2	Input terminal	43	HDIR+	Long line drive high-speed direction+
22	SI3	Input terminal	44	HDIR-	Long line drive high-speed direction-

④ CN2 port

No.	Definition
1	5V
2	GND
3	/
4	/
5	485-A
6	485-B

① Definition of main circuit terminals

DS5K2-20P1/20P4-PTA

Terminal	Function	Explanation
L/N	Main circuit power input terminal	Single phase200~240V, 50/60Hz
●	Empty pin	/
P+, C	Use external braking resistor	Connect the regenerative resistor to the P+ and C terminals, P0-25=power value, P0-26=resistance value
U, V, W	Motor connection terminal	Connect to the motor
PE	Motor grounding terminal	Connect to the motor grounding terminal and perform grounding treatment

DS5K2-20P7-PTA

Terminal	Function	Explanation
L/N	Main circuit power input terminal	Single phase200~240V, 50/60Hz
●	Empty pin	/
P+, D, C	Use built-in braking resistor	Short circuit P+ and D terminals, disconnect P+ and C
	Use external braking resistor	Connect the regenerative resistor to the P+ and C terminals, and disconnect the P+ and D, P0-25=power value, P0-26=resistance value
U, V, W	Motor connection terminal	Connect to the motor
PE	Motor grounding terminal	Connect to the motor grounding terminal and perform grounding treatment

DS5K2-21P0/21P5/22P3/22P6-PTA

Terminal	Function	Explanation
L1, L2, L3	Main circuit power input terminal	Three phase (L1 · L2 · L3) AC200~240V, 50/60Hz Or single-phase (L1 · L3) AC200~240V, 50/60Hz
P+, D, C	Use built-in braking resistor	Short circuit P+ and D terminals, disconnect P+ and C
	Use external braking resistor	Connect the regenerative resistor to the P+ and C terminals, and disconnect the P+ and D, P0-25=power value, P0-26=resistance value
P+, P-	Bus terminal	Real time voltage of the busbar can be measured, please be aware of the danger
U, V, W	Motor connection terminal	Connect to the motor
PE	Motor grounding terminal	Connect to the motor grounding terminal and perform grounding treatment

DS5K2-41P0/41P5/42P3/43P0-PTA

Terminal	Function	Explanation
R, S, T	Main circuit power input terminal	Three phase AC380~440V, 50/60Hz
P+, D, C	Use built-in braking resistor	Short circuit P+ and D terminals, disconnect P+ and C
	Use external braking resistor	Connect the regenerative resistor to the P+ and C terminals, and disconnect the P+ and D, P0-25=power value, P0-26=resistance value
P+, P-	Bus terminal	Real time voltage of the busbar can be measured, please be aware of the danger
U, V, W	Motor connection terminal	Connect to the motor
PE	Motor grounding terminal	Connect to the motor grounding terminal and perform grounding treatment

DS5K2-45P5/47P5-PTA

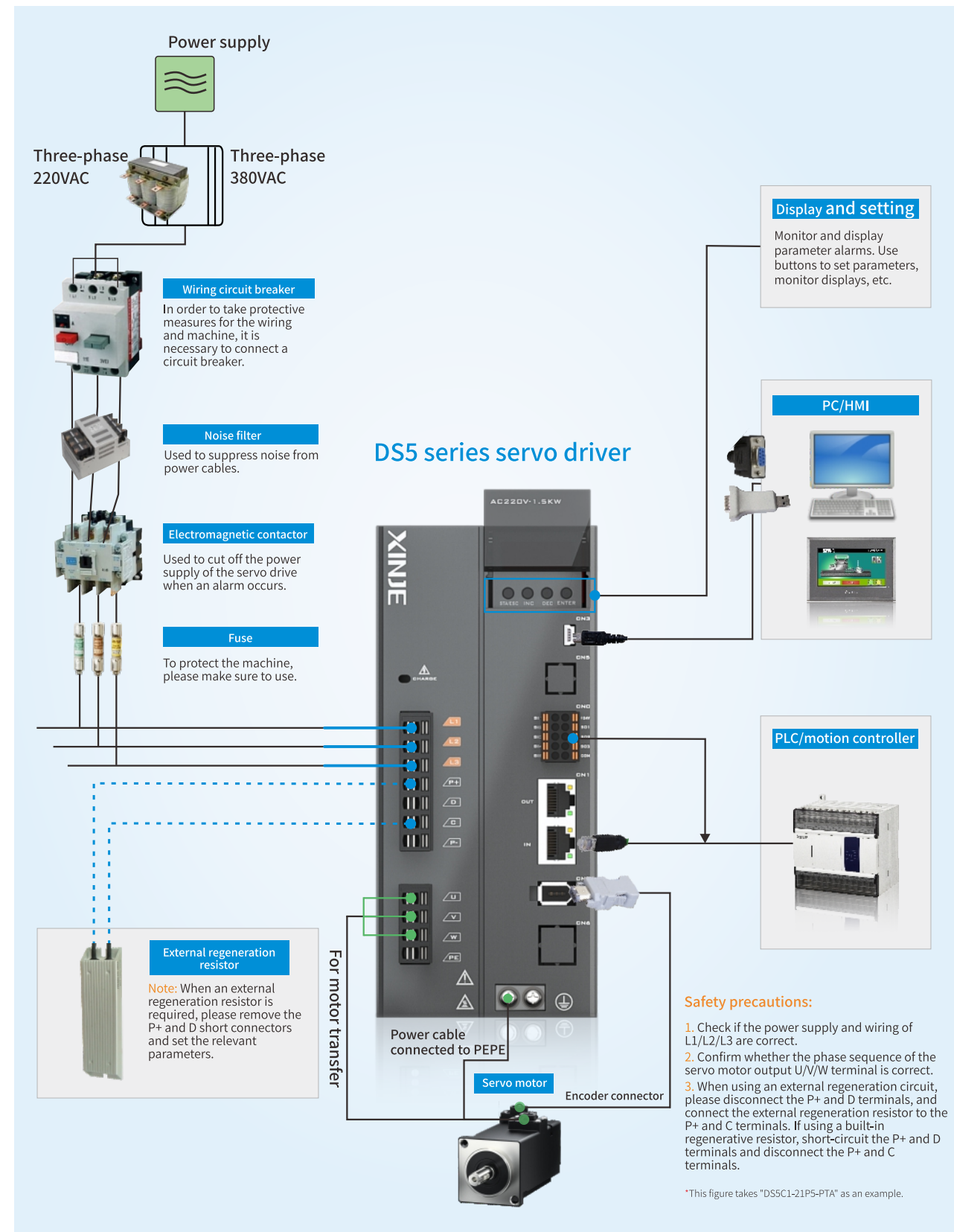
Terminal	Function	Explanation
R, S, T	Main circuit power input terminal	Three phase AC380~440V, 50/60Hz
P+, D, C	Use built-in braking resistor	Short circuit P+ and D terminals, disconnect P+ and C (This model does not have a built-in braking resistor and is not supported)
	Use external braking resistor	Connect the regenerative resistor to the P+ and C terminals, and disconnect the P+ and D, P0-25=power value, P0-26=resistance value
P+, P-	Bus terminal	Real time voltage of the busbar can be measured, please be aware of the danger
U, V, W	Motor connection terminal	Connect to the motor
PE	Motor grounding terminal	Connect to the motor grounding terminal and perform grounding treatment

⑤ CN4 port-RS485

No.	Definition
4	485-A
5	485-B
6	485GND
Others	Reserved

Peripheral device wiring

DS5 series



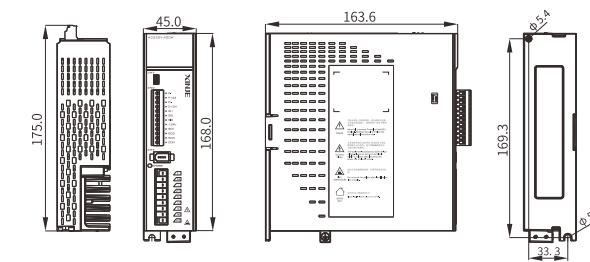
Driver dimension diagram (Unit: mm)

DS5L1/L2-20P1/2/4-PTA

DS5C1/C2-20P1/2/4-PTA

DS5N1-20P1/2/4-PTA

DS5K2-20P1/20P4-PTA

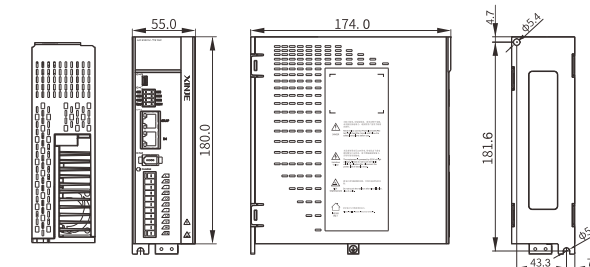


DS5L1/L2-20P7-PTA

DS5C1/C2-20P7-PTA

DS5N1-20P7-PTA

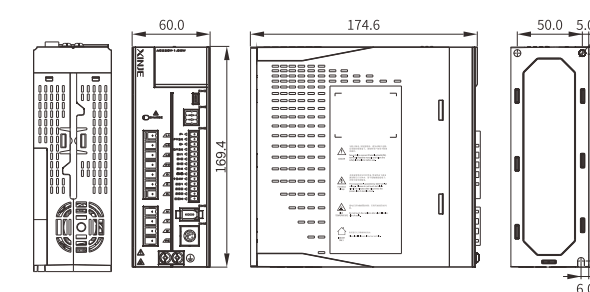
DS5K2-20P7-PTA



DS5L1/L2-21P0/41P0/41P5-PTA

DS5C1/C2-21P0/41P0/41P5-PTA

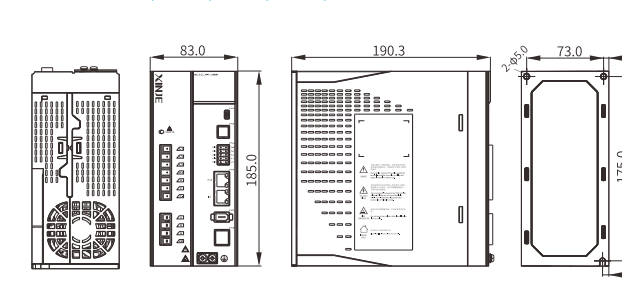
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DS5L1/L2-21P5/22P3/22P6/42P3/43P0-PTA

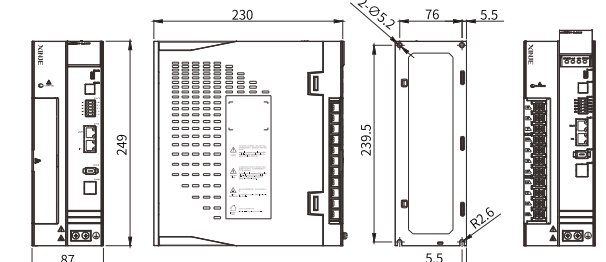
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DS5K2-21P5/22P3/22P6/42P3/43P0-PTA

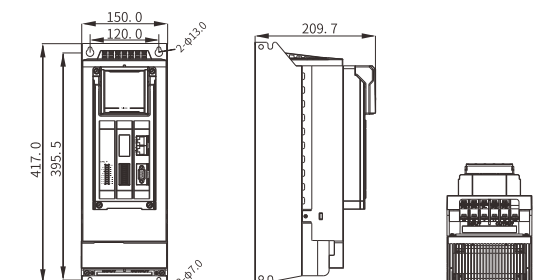


DS5C1/C2-45P5/47P5-PTA

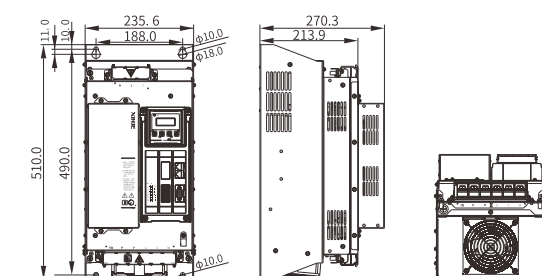
DS5K2-45P5/47P5-PTA



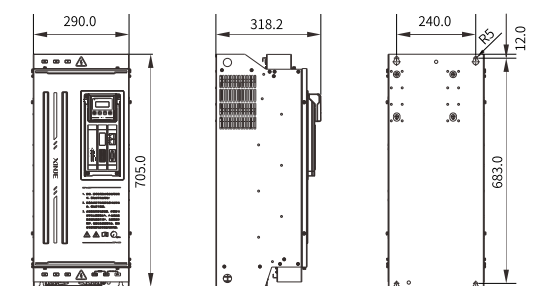
DS5C1/C2-411P0/415P0-PTA



DS5C1-422P0/432P0-PTA

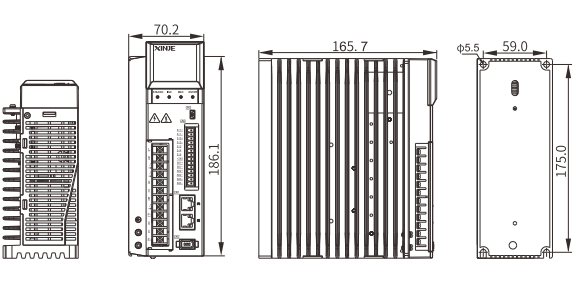


DS5C1-437P0/445P0/455P0-PTA

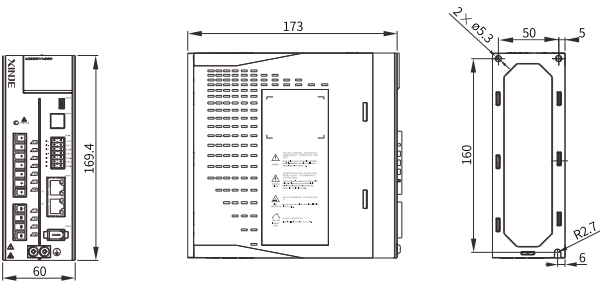


Driver dimension diagram (Unit: mm)

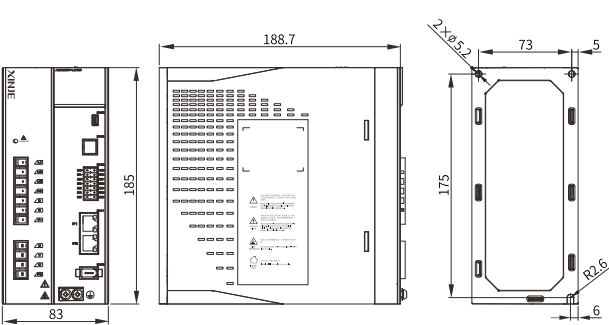
DS5P-20P1/20P2/20P4/20P7-PTA



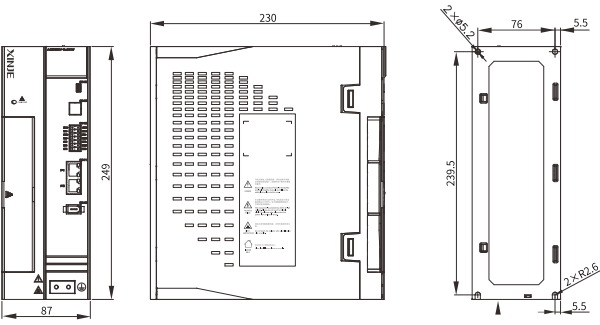
DS5P-21P0/41P0/41P5-PTA



DS5P-21P5/22P3/22P6/42P3/43P0-PTA



DS5P-45P5/47P5-PTA



Naming rule

MS6 servo motor naming rule

MS6H - 80 C N 30 B Z 3 - 2 0P7 - □

① Inertia type		② Frame		③ Encoder structure		④ Encoder specification		⑤ speed		⑩ Rated power	
Symbol	Inertia	Symbol	Frame	Symbol	Type	Symbol	Specification	Symbol	Rated speed (rpm)	Symbol	Rated power (kW)
MS6L	Ultra-low inertia motor	25	Frame 25	C	Magnetic encoder	M	Multi turn 17-bit	15	1500	0A5	0.05
MS6S	Low inertia motor	40	Frame 40	T	Optical encoder	N	Single/multi turn integrated 19-bit	20	2000	0P1	0.1
MS6G	Medium inertia motor	60	Frame 60			L	Multi turn 23-bit	25	2500	0P2	0.2
MS6H	High inertia motor	80	Frame 80			H	High performance multi turn 23-bit	30	3000	0P4	0.4
		100	Frame 100							0P7	0.75
		110	Frame 110							0P8	0.85
		130	Frame 130							1P0	1
		180	Frame 180							1P3	1.3
		200	Frame 200							1P5	1.5
		220	Frame 220							1P8	1.8
		265	Frame 265							2P0	2.0
										2P3	2.3
										3P0	3.0
										4P4	4.4
										5P5	5.5
										7P5	7.5
										11P0	11
										13P0	13
										17P0	17
										21P0	21
										27P0	27
										30P0	30
										48P0	48
										60P0	60
										75P0	75

⑥ Motor shaft specification		⑦ Power-off brake		⑧ Motor connector type	
Symbol	Shaft specification	Symbol	Power-off brake	Symbol	Connector type
A	With key, no oil seal, with threaded hole	Z	With brake	2	Aviation connector
B	With key, with oil seal, with threaded hole	empty	Without brake	3	Connection form
C	No key, no oil seal, with threaded hole			4	Amp plug (motor body IP67)
D	No key, with oil seal, with threaded hole				
E	Special shaft specifications (length, shaft diameter, etc.)				

⑨ Power supply voltage		⑪ Motor heat dissipation method	
Symbol	Power supply voltage	Symbol	Heat dissipation method
2	220V	Default	Natural heat dissipation
4	380V	F	Air cooling
		Y	Liquid cooling

*NOTE: The provided explanation is only an example, please refer to the detailed parameters of the motor for specific models. Our company provides combination models of CM, CN, TL, and TH. Currently, only the MS6 series 130 flange 2.3kW and 180 flange 5.5kW and

Motor driver specification list

MS6 MOTOR												
Item	100W	200W	400W	750W	850W	1.0kW	1.3kW	1.5kW	1.8kW	2.3kW	2.5kW	3.0kW
Ultra low inertiaMS6L								100			100	
Low inertia MS6S			60	80		80 100		100				130
Medium inertia MS6G					130	130		110 130		130		180
High inertia MS6H	40	60	60	80	130	80	130	130	130	130		180

Item	4.4kW	5kW	5.5kW	7.5kW	13kW	17kW	21kW	27kW	30kW	48kW	60kW	75kW
Ultra low inertiaMS6L												
Low inertia MS6S		130										
Medium inertia MS6G	180		180	180	200	200	200	200	265	265	265	265
High inertia MS6H	180		180	180								

Note: 40/60/80/110/130/180/220/265 represents the motor base. The motor marked with "" is still under development, please stay tuned. Provide models with a voltage level of 220V. Provide models with a voltage level of 380V. Provide models with a voltage level of 220V/380V.

MS6L ultra low inertia

Motor specification 1.5kW/2.5kW

Motor model		MS6L ultra low inertia		
		100□□30B□2	100□□30B□2	100□□30B□2
		21P5	41P5	42P5
Rated power [kW]		1.5	1.5	2.5
Voltage level		AC220V	AC380V	AC380V
Rated speed [rpm]		3000	3000	3000
Maximum speed [rpm]		6000	6000	6000
Rated torque [N·m]		4.9	4.9	8
Maximum torque [N·m]		14.7	14.7	24
Rated current [mA]		9500	6700	9700
Rotor inertia [10 ⁻⁴ ·kg·m ²]		2550(3123)	2550(3123)	3840(4315)
Inertia type		ultra low inertia	ultra low inertia	ultra low inertia
Recommended rotor inertia ratio		15	15	15
Electrical constant e(ms)		11.63	12.08	13.16
Mechanical constant m(ms)		0.73	0.37	0.30
Back EMF constant		48	71	77
Torque constant (Nm/A)		0.516	0.731	0.82
Pole pairs		5	5	5
Encoder bits		19/23	19/23	19/23
Encoder type		Magnetic(optical)	Magnetic(optical)	Magnetic(optical)
Motor insulation grade		ClassF(155°C)		
Protection level		IP67		
Using environment	Ambient temperature	-15°C~+40°C (not frozen)		
	Ambient humidity	Relative humidity <90% (non condensing)		
Braking parameter	Static friction torque [N·m]	≥10		
	Rated power [W]	17.6		
	Attraction time [ms]	≤100		
	Release time [ms]	≤50		
	Excitation current DC[V]	0.734		
	Attraction voltage DC[V]	≤16.8		
	Release voltage DC[V]	1~8		
Excitation voltage DC[V]		DC24±10%		

MS6L series T/N curve

Three torque-speed graphs are shown, each with a blue box indicating the motor code:

- Motor code: 8023/8823/A023/A823** (MS6L-100CN/TH30B(Z)2-21P5): The graph shows a constant torque of approximately 14.5 N·m from 0 to 3000 rpm, followed by a linear decrease to about 5.5 N·m at 6000 rpm. The continuous working area is shaded blue.
- Motor code: 8123/8923/A123/A923** (MS6L-100CN/TH30B(Z)2-41P5): The graph shows a constant torque of approximately 14.5 N·m from 0 to 3000 rpm, followed by a linear decrease to about 5.5 N·m at 6000 rpm. The continuous working area is shaded blue.
- Motor code: 8128/8928/A128/A928** (MS6L-100CN/TH30B(Z)2-42P5): The graph shows a constant torque of approximately 24 N·m from 0 to 3000 rpm, followed by a linear decrease to about 4 N·m at 6000 rpm. The continuous working area is shaded blue.

Motor dimension (unit: mm)

Technical drawing of the M6 12-1 motor showing three views: front, side, and top.

- Front View (Left):** Shows a circular motor body with a diameter of $\varnothing 90$ and a width of 20. The mounting flange has a diameter of $\varnothing 95$ and a thickness of 12. The motor is labeled "M6 12-1".
- Side View (Middle):** Shows the motor's profile with a total length of 100.3. The mounting flange has a diameter of $\varnothing 95$ and a thickness of 12. The motor is labeled "M6 12-1".
- Top View (Right):** Shows the motor's top with a diameter of $\varnothing 100.3$ and a mounting flange diameter of $\varnothing 95$. The motor is labeled "M6 12-1".

Motor model	LA±1		Inertia level
	Normal	With brake	
MS6L-100CN30B□2-21P5	180	205	Ultra low inertia
MS6L-100CN30B□2-41P5	180	205	
MS6L-100CN30B□2-42P5	228	253	
MS6L-100TH30B□2-42P5	241	266	

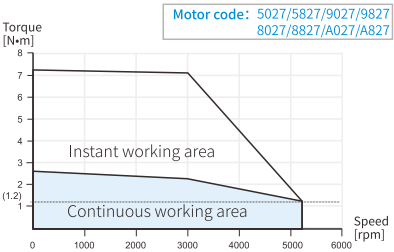
Series	Specification	2.3kW	2.3kW	3kW	4.4kW	5.5kW	7.5kW		
	Model	130□□15B□2	130□□15B□2	180□□15B□2	180□□15B□2	180□□15B□2	180□□15B□2		
MS6H high inertia	Frame [mm]	130	130	180	180	180	180		
	Rated torque(max torque)[N·m]	14.6(36.5)	14.6(36.5)	19(51.3)	28(84)	35(87.5)	48(120)		
	Rated speed(max speed)[r/min]	1500(2500)	1500(3000)	1500(3000)	1500(3000)	1500(3000)	1500(3000)		
	Inertia, none brake(brake)[10 ⁻⁴ kg·m ²]	35240(36260)	35240(36260)	51000(55490)	73280(78040)	90250(95200)	132000(134690)		
	Encoder bits	17/23	17/23	17/23	17/23	17/23	17/23		
	220V	✓							
	380V		✓	✓	✓	✓	✓		

MS6S low inertia

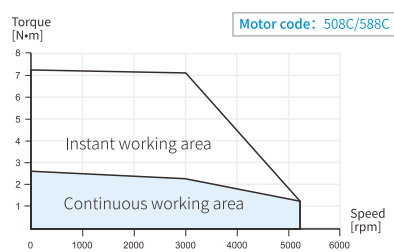
Motor specification of 400W/750W/1kW/1.5kW/3kW/5kW

Motor model	MS6S low inertia								
	60□□30B□3	60□□30B□4	80□□30B□3	80□□30B□4	80□□30B□3	100□□30B□2	100□□30B□2	130□□30B□2	130□□30B□2
	20P4	20P4	20P7	20P7	21P0	21P0	21P5	43P0	45P0
Rated power [kW]	0.4	0.4	0.75	0.75	1.0	1.0	1.5	3.0	5.0
Voltage level	AC220V							AC380V	
Rated speed [rpm]	3000	3000	3000	3000	3000	3000	3000	3000	3000
Maximum speed [rpm]	6500	6500	5200	5200	4000	4500	4500	6000	6000
Rated torque [N·m]	1.27	1.27	2.39	2.39	3.18	3.18	4.8	9.8	15.8
Maximum torque [N·m]	4.45	4.445	7.17	7.17	9.54	9.54	12	29.4	47.4
Rated current [mA]	2700	2700	4100	4100	4100	5700	8000	9200	14000
Rotor inertia [10 ⁻⁴ ·kg·m ²]	258(280)	247(279)	980(1004)	980(1104)	1182(1196)	1928(2200)	2818(2888)	5870(8500)	8570(10530)
Inertia type	Low inertia	Low inertia	Low inertia	Low inertia	Low inertia	Low inertia	Low inertia	Low inertia	Low inertia
Recommended rotor inertia ratio	30	30	20	20	20	15	15	10	10
Electrical constant e[ms]	2.96	3.11	5.53	5.53	5.89	10.34	10.791	22.13	22.13
Mechanical constant m[ms]	0.57(0.61)	0.55(0.62)	0.69(0.71)	0.69(0.78)	0.53	0.67	0.61	0.24(0.35)	0.24(0.35)
Back EMF constant	44.25	44	55	55	75	57	57	98	98
Torque constant (Nm/A)	0.47	0.47	0.58	0.58	0.78	0.55	0.6	1.07	1.07
Pole pairs	5								
Encoder bits	17/19/23	17	17/19/23	17	17/19/23	17/23	17	19/23	19/23
Encoder type	Magnetic(optical)	Magnetic	Magnetic(optical)	Magnetic	Magnetic(optical)	Magnetic(optical)	Magnetic	Magnetic(optical)	Magnetic(optical)
Motor insulation grade	ClassF(155°C)								
Protection level	IP67	IP67	IP67	IP67	IP67	IP65	IP66	IP67	IP67
Using environment	-15°C~+40°C (not frozen)								
	Relative humidity <90% (non condensing)								
Braking parameter	Static friction torque [N·m]	≥1.3	≥1.3	≥3.2	≥3.2	≥3.2	≥8	≥15	≥23.5
	Rated power [W]	7.4	7.4	11.5	11.5	11.5	17.6	16.9	23
	Attraction time [ms]	≤50	≤50	≤60	≤60	≤60	100	100	≤100
	Release time [ms]	≤30	≤30	≤30	≤30	≤30	50	50	≤60
	Excitation current DC[V]	0.308	0.308	0.48	0.48	0.48	0.733	0.733	0.945
	Attraction voltage DC[V]	<16.8	<16.8	<16.8	<16.8	<16.8	≤16.8	≤16.8	≤16.8
	Release voltage DC[V]	>1	>1	>1	>1	>1	≥1	≥1	≥1
	Excitation voltage DC[V]	DC24±10%							

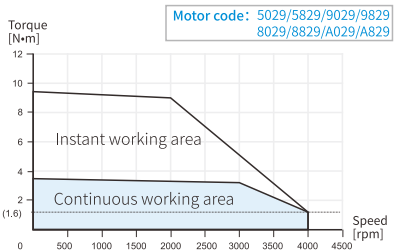
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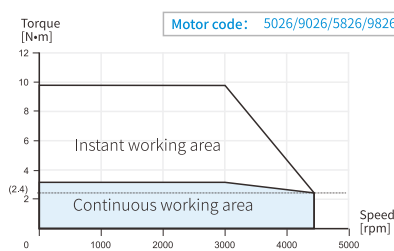
MS6S-80CM30B(Z)4-20P7



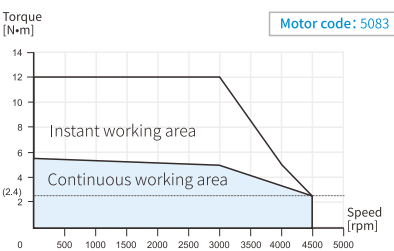
MS6S-80CM/CN/TH/TL30B(Z)3-21P0



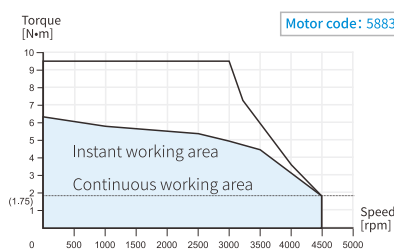
MS6S-100CM/TL30B(Z)2-21P0



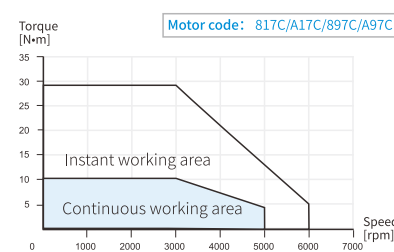
MS6S-100CM30B2-21P5



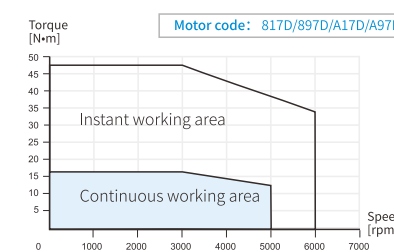
MS6S-100CM30B2-21P5



MS6S-130CN/TH30B(Z)2-43P0

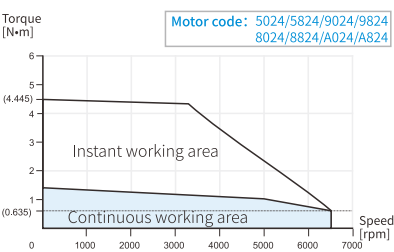


MS6S-130CN/TH30B(Z)2-45P0

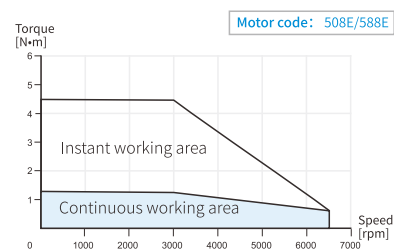


MS6S series T/N curve

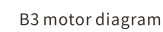
MS6S-60CM/CN/TH/TL30B(Z)3-20P4



MS6S-60CM30B(Z)4-20P4



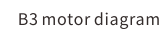
60 flange



60 flange



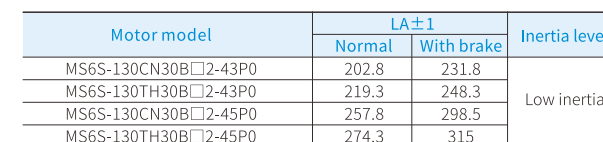
80 flange



80 flange



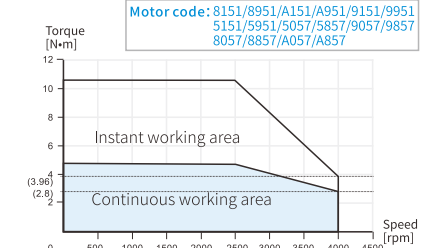
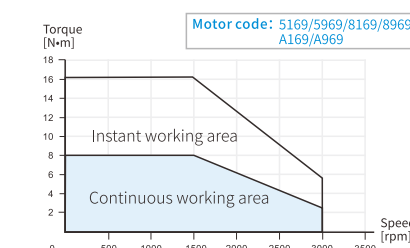
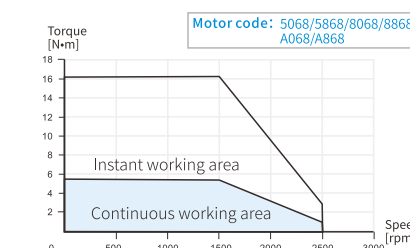
100 flange



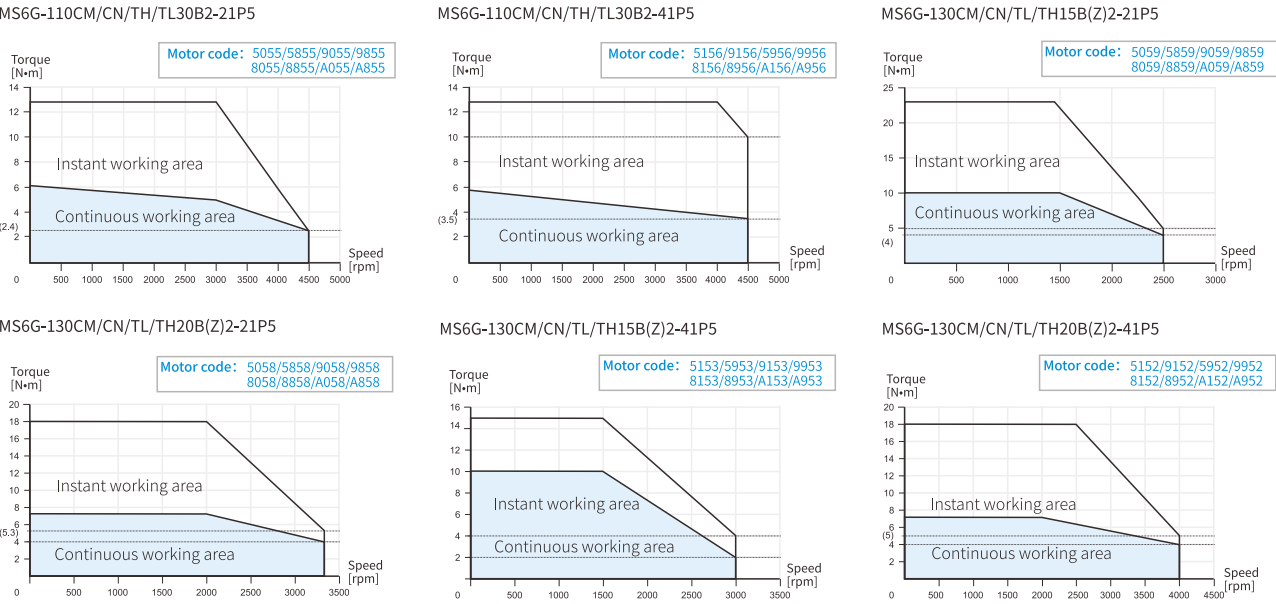
Motor specification of 0.8kW/1kW/1.5kW

Motor model		MS6G medium inertia									
		130□□15B□2	130□□15B□2	130□□25B□2	130□□25B□2	110□□30B□2	110□□30B□2	130□□20B□2	130□□15B□2	130□□20B□2	130□□15B□2
		20P8	40P8	21P0	41P0	21P5	41P5	21P5		41P5	
Rated power [kW]		0.85	0.85	1.0	1.0	1.5	1.5	1.5	1.5	1.5	1.5
Voltage level		AC220V	AC380V	AC220V	AC380V	AC220V	AC380V	AC220V	AC220V	AC380V	AC380V
Rated speed [rpm]		1500	1500	2500	2500	3000	3000	2000	1500	2000	1500
Maximum speed [rpm]		2500	3000	4000	4000	4500	4500	3000	2500	4000	3000
Rated torque [N·m]		5.4	5.4	4	4	4.78	4.78	7.2	10	7.2	10
Maximum torque [N·m]		16.2	16.2	12	12	12.7	13.5	18	25	21.6	25
Rated current [mA]		4300	2900	5900	3200	7500	6000	8000	8000	5300	5700
Rotor inertia [10 ⁻⁴ ·kg·m ²]		11770(14480)	11770(14480)	8030(8430)	8030(8430)	6200(/)	6200(/)	12140(14410)	17320(19670)	12140(14410)	17320(19670)
Inertia type		Medium inertia	Medium inertia	Medium inertia	Medium inertia	Medium inertia	Medium inertia	Medium inertia	Medium inertia	Medium inertia	Medium inertia
Recommended rotor inertia ratio		10	10	10	10	15	15	10	10	10	10
Electrical constant e(ms)		9.84	9.84	9.64	9.15	8.45	8.89	10.9	11.6	10.76	12.43
Mechanical constant m(ms)		1.63(2.01)	1.72(2.11)	2.01(2.11)	5.46(2.3)	4.05	1.36	1.39(1.65)	1.17(1.33)	1.38	1.1(1.25)
Back EMF constant		115	173	69	49.6	21	76.33	88	116	128	163
Torque constant (Nm/A)		1.26	1.86	0.68	1.25	0.64	0.8	0.9	1.25	1.36	1.75
Pole pairs		5									
Encoder bits		17/19/23									
Encoder type		Magnetic(optical)									
Motor insulation grade		ClassF(155°C)									
Protection level		IP67									
Using environment		-15°C~+40°C (not frozen)									
		Relative humidity <90% (non condensing)									
Braking parameter	Static friction torque [N·m]	≥15				≥6		≥15			
	Rated power [W]	16.9				18		16.9			
	Attraction time [ms]	≤100				≤100		≤100			
	Release time [ms]	≤60				≤50		≤60			
	Excitation current DC[V]	0.705				0.75		0.705			
	Attraction voltage DC[V]	≤16.8				≤16.8		≤16.8			
	Release voltage DC[V]	≥1				≥1		≥1			
		DC24±10%									

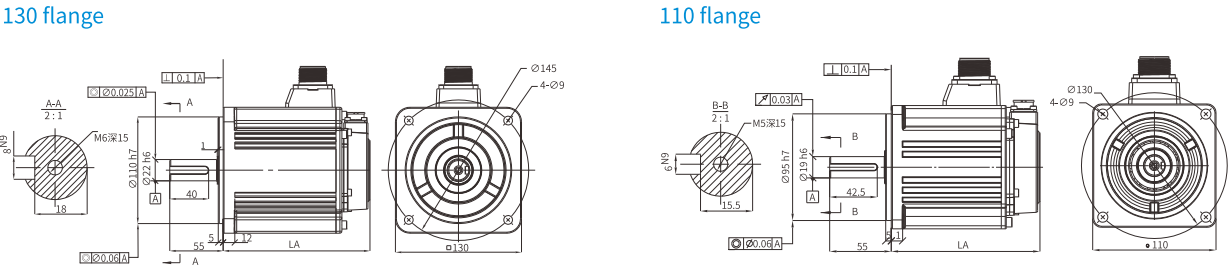
MS6G series T/N curve



MS6G series T/N curve



Motor dimension (unit: mm)



Motor model	LA±1		Shaft diameter ΦD	Inertia level
	Normal	With brake		
MS6G-130C□15B□2-□0P8	133.5	162.5	22	Medium inertia
MS6G-130TH15B□2-□0P8	150	179		
MS6G-130C□25B□2-□1P0	119.5	148.5		
MS6G-130T□25B□2-□1P0	136	165		
MS6G-130C□20B□2-□1P5	133.5	162.5		
MS6G-130T□20B□2-□1P5	150	179		
MS6G-130C□15B□2-□1P5	151.5	180.5		
MS6G-130T□15B□2-□1P5	168	197		

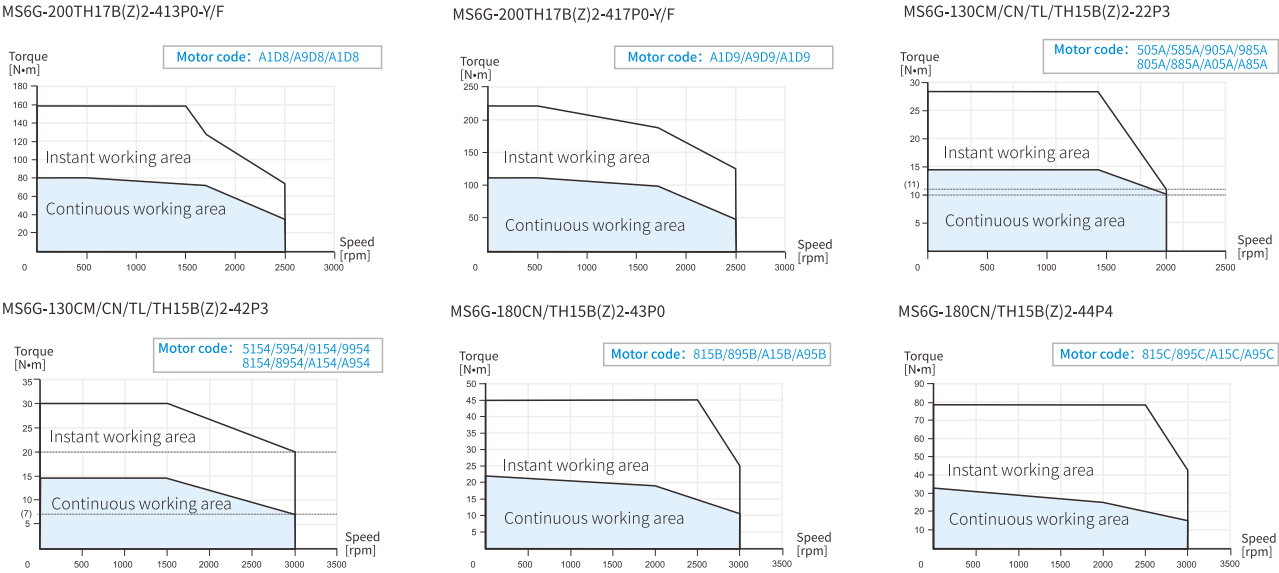
Motor model	LA±1		Inertia level
	Normal	With brake	
MS6G-110C□30B2-21P5/41P5	132.5	163.5	Medium inertia
MS6G-110T□30B2-21P5/41P5	149	180	

MS6G medium inertia

Motor specification of 2.3kW/3kW/4.4kW/5.5kW/7.5kW/13kW/17kW

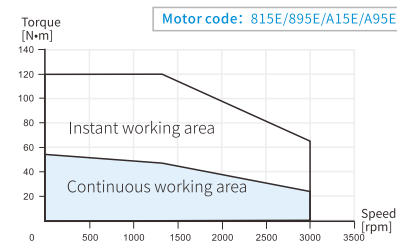
Motor model		MS6G medium inertia							
		130□□15B□2	130□□15B□2	180□□15B□2	180□□15B□2	180□□15B□2	180□□15B□2	200□□17B□2	200□□17B□2
		22P3	42P3	43P0	44P4	45P5	47P5	413P0	417P0
Rated power [kW]		2.3	2.3	3	4.4	5.5	7.5	13	17
Voltage level		AC220V	AC380V	AC380V	AC380V	AC380V	AC380V	AC380V	AC380V
Rated speed [rpm]		1500	1500	1500	1500	1500	1500	1700	1700
Maximum speed [rpm]		2000	3000	3000	3000	3000	3000	2500	2500
Rated torque [N·m]		14.6	14.6	19.1	28	35	48	70	95.5
Maximum torque [N·m]		29.2	36.5	47.75	84	87.5	120	175	238.75
Rated current [mA]		9000	8300	10500	16500	20500	25000	25000	35000
Rotor inertia [10 ⁻⁴ ·kg·m ²]		23020(28780)	23020(28780)	45790(47340)	67600(76770)	91360(100530)	135330(144500)	159350(165980)	195000(202056)
Inertia type		Medium inertia	Medium inertia	Medium inertia	Medium inertia	Medium inertia	Medium inertia	Medium inertia	Medium inertia
Recommended rotor inertia ratio		10	10	10	10	10	10	10	10
Electrical constant e(ms)		12.99	13.2	21.98	24.08	24.49	24.76	32.59	32.30
Mechanical constant m(ms)		0.84(1.05)	1.29(1.62)	1.23(1.28)	0.98(1.11)	0.97(1.07)	1.24(1.33)	1.29(1.35)	1.12
Back EMF constant		151(155)	166	167	155	156.77	124	274.12	275
Torque constant (Nm/A)		1.62	1.76	1.82	1.70	1.71	1.92	2.80	2.73
Pole pairs		5	5	5	5	5	5	4	4
Encoder bits		17/19/23	17/19/23	19/23	19/23	19/23	19/23	23	23
Encoder type		Magnetic(optical)						Optical	Optical
Motor insulation grade		ClassF(155℃)	ClassF(155℃)	ClassF(155℃)	ClassF(155℃)	ClassF(155℃)	ClassF(155℃)	ClassF(155℃)	ClassF(155℃)
Protection level		IP67	IP67	IP67	IP67	IP67	IP67	IP54	IP54
Using environment	Ambient temperature	-15℃~-+40℃ (not frozen)							
	Ambient humidity	Relative humidity <90% (non condensing)							
Braking parameter	Static friction torque [N·m]	≥15		≥55				≥150	
	Rated power [W]	16.9		31				61	
	Attraction time [ms]	≤100		≤200				≤300	
	Release time [ms]	≤60		≤100				≤50	
	Excitation current DC[V]	0.705		1.291				2.539	
	Attraction voltage DC[V]	≤16.8		16.8				≤19.2	
	Release voltage DC[V]	≥1		≥1				≠0;<8	
	Excitation voltage DC[V]	DC24±10%							

MS6G series T/N curve



MS6H high inertia

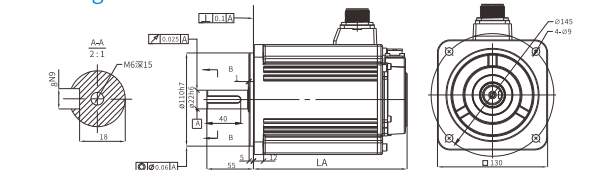
MS6G-180CN/TH15B(Z)2-47P5



Motor specification of 50W/100W/200W/400W/750W/1kW

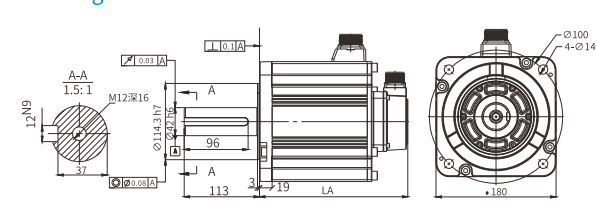
Motor model		MS6H high inertia										
		40□□30B□4	40□□30B□3	40□□30B□4	60□□30B□3	60□□30B□4	60□□30B□3	60□□30B□4	80□□30B□3	80□□30B□4	80□□30B□3	80□□30B□4
		20A5	20P1	20P1	20P2	20P2	20P4	20P4	20P7	20P7	21P0	21P0
Rated power [kW]		0.05	0.1	0.1	0.2	0.2	0.4	0.4	0.75	0.75	1.0	1.0
Voltage level		AC220V	AC220V	AC220V	AC220V	AC220V	AC220V	AC220V	AC220V	AC220V	AC220V	AC220V
Rated speed [rpm]		3000	3000	3000	3000	3000	3000	3000	3000	3000	3000	3000
Maximum speed [rpm]		6500	6500	6500	6500	6500	6500	6500	5200	5200	4000	4000
Rated torque [N·m]		0.16	0.32	0.32	0.64	0.64	1.27	1.27	2.39	2.39	3.18	3.18
Maximum torque [N·m]		0.56	0.96	1.12	2.24	2.24	4.45	4.45	7.17	7.17	9.54	9.54
Rated current [mA]		950	950	950	1900	1900	2800	2800	4100	4100	4100	4100
Rotor inertia [10 ⁻⁴ ·kg·m ²]		35.6(38.27)	64(67)	58.2(60.77)	271(281)	300(332)	530(550)	521(529)	1550(1569)	1578(1688)	2391(2410)	2362(2483)
Inertia type		High inertia										
Recommended rotor inertia ratio		30	30	30	30	30	30	30	20	20	20	20
Electrical constant e(ms)		0.77	1.04	0.88	1.67	1.48	1.7	1.7	4.58	4.58	4.97	4.61
Mechanical constant m(ms)		1.59(1.71)	1.16(1.21)	1.06(1.11)	1.26(1.29)	1.45(1.61)	0.93	0.93	1(1.02)	1(1.02)	0.93	0.77(0.81)
Back EMF constant		17	33	33	31	32	43.98	43.98	56	56	73	76
Torque constant (Nm/A)		0.17	0.34	0.34	0.34	0.34	0.45	0.45	0.58	0.58	0.78	0.78
Pole pairs		5	5	5	5	5	5	5	5	5	5	5
Encoder bits		17	17/19/23	17	17/19/23	17	17/19/23	17	17/19/23	17	17/19/23	17
Encoder type		Magnetic	Magnetic (optical)	Magnetic	Magnetic (optical)	Magnetic	Magnetic (optical)	Magnetic	Magnetic (optical)	Magnetic	Magnetic (optical)	Magnetic
Motor insulation grade		ClassF(155°C)										
Protection level		IP67										
Using environment	Ambient temperature	-10°C~+40% (not frozen)										
	Ambient humidity	20%-90% RH (non condensing)										
Braking parameter	Static friction torque [N·m]	≥0.32			≥1.3			≥3.2				
	Rated power [W]	6.1			7.4			11.5				
	Attraction time [ms]	≤40			≤50			≤60				
	Release time [ms]	≤20			≤30			≤30				
	Excitation current DC[V]	0.254			0.308			0.48				
	Attraction voltage DC[V]	≤16.8			<16.8			<16.8				
	Release voltage DC[V]	≥1			>1			>1				
Excitation voltage DC[V]		DC24±10%										

130 flange



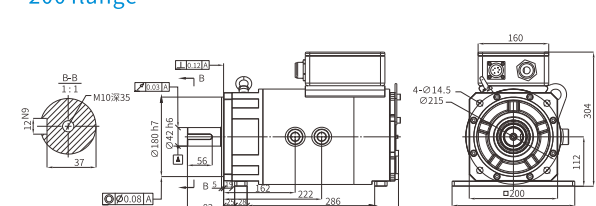
Motor model	LA±1		Shaft diameter φD	Inertia level
	Normal	With brake		
MS6G-130C□15E□2-□2P3	181.5	210.5	22	Medium inertia
MS6G-130T□15E□2-□2P3	198	227		

180 flange



Motor model	LA ± 1		Shaft diameter gD	Inert level
	Normal	With brake		
MS6G-180CN15B□2-45P5	208	252.5	42	Medium inert
MS6G-180CN15B□2-47P5	256	300.5	42	
MS6G-180TH15B□2-45P5	222.5	267	42	
MS6G-180TH15B□2-47P5	270.5	315	42	

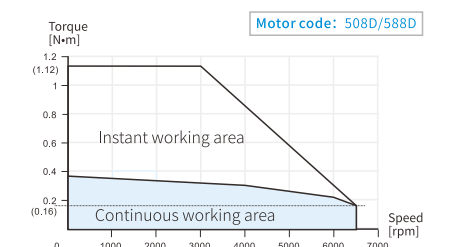
200 flange



Liquid cooled motor

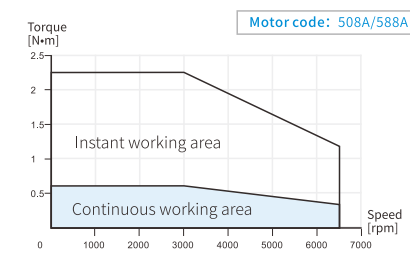
Motor model	LA±1		Inertia level
	Normal	With brake	
MS6G-200TH1B2-417P0-Y	396	/	Medium inertia
MS6G-200TH1B2-413P0-Y	361	/	

MS6H-40CM30B(Z)4-20P1

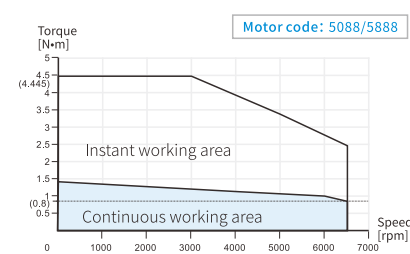


Motor dimension (unit: mm)

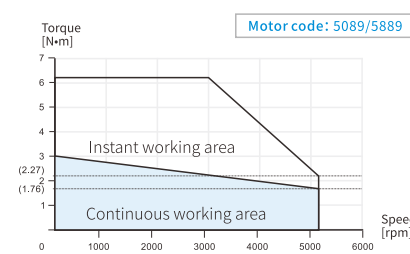
40 flange



Motor model	LA±1		Inertia level
	Normal	With brake	
MS6H-40CM30B□4-20A5	60.8	93.4	4000 mm²/s²



60 flange

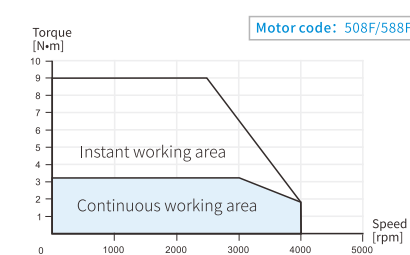


B3 motor diagram

Technical drawing of a B3 motor. The drawing includes a side view and a top view. The side view shows a motor with a base and a mounting flange. Dimensions include a base width of 11, a mounting flange diameter of 14, a mounting flange thickness of 20, a mounting flange width of 30, and a total width of 60. The top view shows a circular motor with a diameter of 11, a mounting flange diameter of 14, a mounting flange thickness of 20, a mounting flange width of 30, and a total width of 60. The drawing also includes a detail of the mounting flange with dimensions 11, 14, 20, 30, and 60.

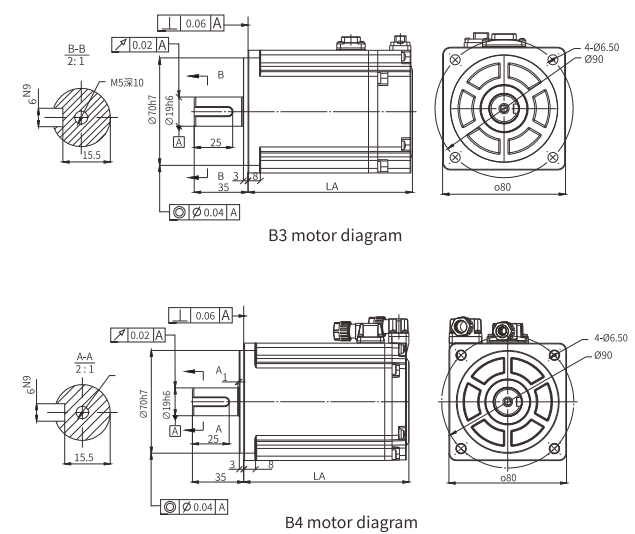
B4 motor diagram

Technical drawing of a B4 motor. The drawing includes a side view and a top view. The side view shows a motor with a base and a mounting flange. Dimensions include a base width of 11, a mounting flange diameter of 14, a mounting flange thickness of 20, a mounting flange width of 30, and a total width of 60. The top view shows a circular motor with a diameter of 11, a mounting flange diameter of 14, a mounting flange thickness of 20, a mounting flange width of 30, and a total width of 60. The drawing also includes a detail of the mounting flange with dimensions 11, 14, 20, 30, and 60.



Motor model	LA+1		Inertia level
	Normal	With brake	
MS6H-60□□30B□3-20P2	76.4	99.15	High inertia
MS6H-60□□30B□3-20P4	98.4	121.15	
MS6H-60CM30B□4-20P4	80.2	106.95	
MS6H-60CM30B□4-20P2	66.7	93.5	

80 flange



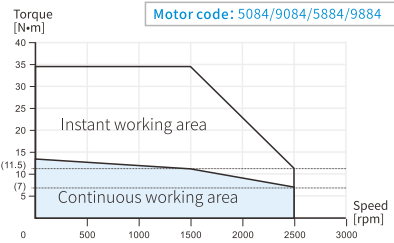
Motor model	LA ± 1		Inertia level
	Normal	With brake	
MS6H-80CM30B□□4-21P0	112.5	144	High inertia
MS6H-80□□□30B□3-20P7	107.1	132.1	
MS6H-80CM30B□□4-20P7	89.2	121.1	
MS6H-80□□□30B□3-21P0	134	159	

MS6H high inertia

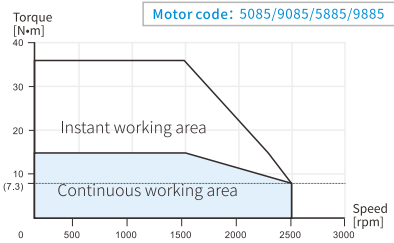
Motor specification of 850W/1.3kW/1.5kW/1.8kW/2.3kW

Motor model	MS6H High inertia							
	130□□15B□2	130□□15B□2	130□□15B□2	130□□20B□2	130□□15B□2	130□□15B□2	130□□15B□2	130□□15B□2
	20P8	40P8	41P3	21P5	21P8	41P8	22P3	42P3
Rated power [kW]	0.85	0.85	1.3	1.5	1.8	1.8	2.3	2.3
Voltage level	AC220V	AC380V	AC380V	AC220V	AC220V	AC380V	AC220V	AC380V
Rated speed [rpm]	1500	1500	1500	2000	1500	1500	1500	1500
Maximum speed [rpm]	3000	3000	3000	3000	2500	3000	2500	3000
Rated torque [N·m]	5.41	5.41	8.3	7.16	11.5	11.5	14.6	14.6
Maximum torque [N·m]	16.23	16.23	24.9	18	34.5	28.75	36.5	36.5
Rated current [mA]	6000	3500	6000	8000	10000	7400	11800	8500
Rotor inertia [10 ⁻⁷ kg·m ²]	13860(15340)	13860(15340)	20000(21440)	20000(21440)	28500(29940)	28500(29940)	35240(36260)	35240(36260)
Inertia type	High inertia	High inertia	High inertia	High inertia	High inertia	High inertia	High inertia	High inertia
Recommended rotor inertia ratio	10	10	10	10	10	10	10	10
Electrical constant e(ms)	6.944	6.722	9.229	8.409	8.37	9.973	9.893	9.887
Mechanical constant m(ms)	1.823(2.017)	1.844(2.041)	1.496(1.603)	1.523(1.633)	1.414(1.486)	1.252(1.316)	1.234(1.27)	1.249(1.285)
Back EMF constant	89	149	127	86	106	144	115	155
Torque constant (Nm/A)	0.902	1.546	1.383	0.895	1.15	1.554	1.237	1.718
Pole pairs	5							
Encoder bits	17/23							
Encoder type	Magnetic(optical)							
Motor insulation grade	ClassF(155°C)							
Protection level	IP65							
Using environment	Ambient temperature	-10°C~+40% (not frozen)						
	Ambient humidity							
Braking parameter	Static friction torque [N·m]	≥15						
	Rated power [W]	23						
	Attraction time [ms]	<100						
	Release time [ms]	<60						
	Excitation current DC[V]	0.96						
	Attraction voltage DC[V]	<18						
	Release voltage DC[V]	>1.5						
	Excitation voltage DC[V]	24±10%						

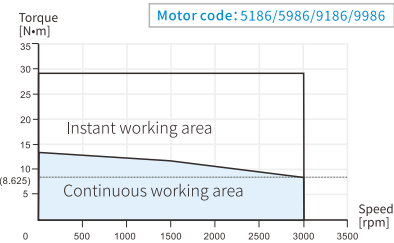
MS6H-130CM/TL15B(Z)2-21P8



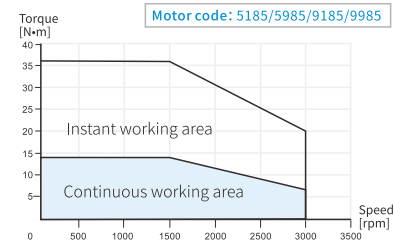
MS6H-130CM/TL15B(Z)2-22P3



MS6H-130CM/TL15B(Z)2-41P8

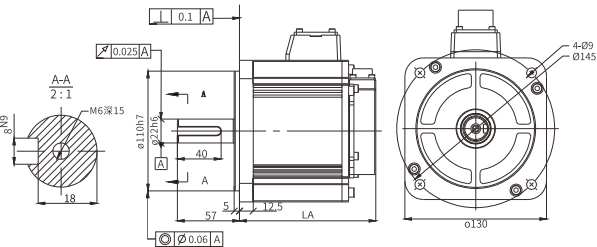


MS6H-130CM/TL15B(Z)2-42P3



Motor dimension (unit: mm)

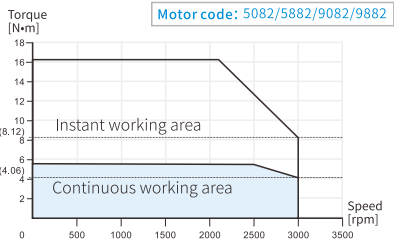
130 flange



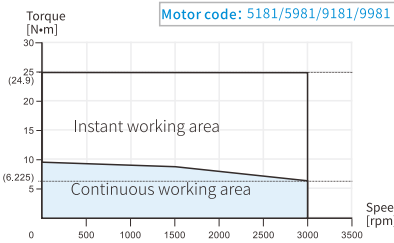
Motor model	LA±1		Inertia level
	Normal	With brake	
MS6H-130C□15B□2-20P8	126	156	High inertia
MS6H-130C□15B□2-40P8	126	156	
MS6H-130TL15B□2-20P8	142	172	
MS6H-130TL15B□2-40P8	142	172	
MS6H-130C□20B□2-21P5	148	178	
MS6H-130TL20B□2-21P5	164	194	
MS6H-130C□15B□2-21P8	175	205	
MS6H-130TL15B□2-21P8	191	221	
MS6H-130C□15B□2-22P3	195.6	225.6	
MS6H-130TL15B□2-22P3	211.6	241.6	
MS6H-130C□15B□2-41P3	148	178	
MS6H-130TL15B□2-41P3	164	194	
MS6H-130C□15B□2-41P8	175	205	
MS6H-130TL15B□2-41P8	191	221	
MS6H-130C□15B□2-42P3	195.6	225.6	
MS6H-130TL15B□2-42P3	211.6	241.6	

MS6H series T/N curve

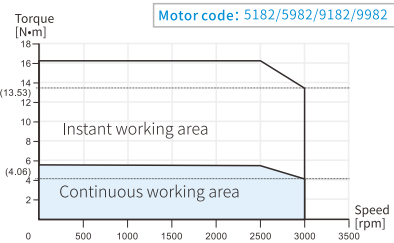
MS6H-130CM/TL15B(Z)2-20P8



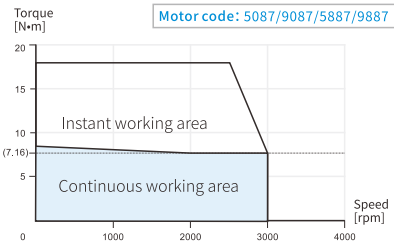
MS6H-130CM/TL15B(Z)2-41P3



MS6H-130CM/TL15B(Z)2-40P8



MS6H-130CM/TL20B(Z)2-21P5



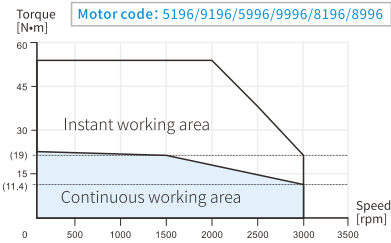
MS6H high inertia

Motor specification of 3kW/4.4kW/5.5kW/7.5kW

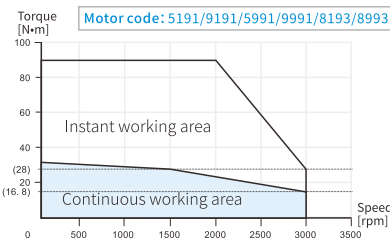
Motor model		MS6H High inertia			
		180□□15B□2	180□□15B□2	180□□15B□2	180□□15B□2
		43P0	44P4	45P5	47P5
Rated power [kW]		3.0	4.4	5.5	7.5
Voltage level		AC380V			
Rated speed [rpm]		1500	1500	1500	1500
Maximum speed [rpm]		3000	3000	3000	3000
Rated torque [N·m]		19	28	35	48
Maximum torque [N·m]		51.3	84	87.5	120
Rated current [mA]		11000	16500	19700	25000
Rotor inertia [10 ⁻⁴ ·kg·m ²]		51000(55490)	73280(78040)	90250(95200)	132000(134690)
Inertia type		High inertia	High inertia	High inertia	High inertia
Recommended rotor inertia ratio		10	10	10	10
Electrical constant e(ms)		22.539	25.547	26.195	25.176
Mechanical constant m(ms)		1.251(1.361)	1.023(1.09)	0.957(1.01)	0.907(0.925)
Back EMF constant		160	160	160	172
Torque constant (Nm/A)		1.727	1.636	1.777	1.92
Pole pairs		5			
Encoder bits		17/19/23			
Encoder type		Magnetic(optical)			
Motor insulation grade		ClassF(155°C)			
Protection level		IP65			
Using environment	Ambient temperature	-10°C~+40% (not frozen)			
	Ambient humidity	2.20%~90% RH (non condensing)			
Braking parameter	Static friction torque [N·m]	≥58			
	Rated power [W]	30			
	Attraction time [ms]	≤180			
	Release time [ms]	≤80			
	Excitation current DC[V]	1.25			
	Attraction voltage DC[V]	<16.8			
	Release voltage DC[V]	>1.5			
Excitation voltage DC[V]		24±10%			

MS6H series T/N curve

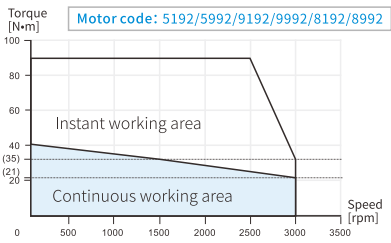
MS6H-180CN/CM/TL15B(Z)2-43P0



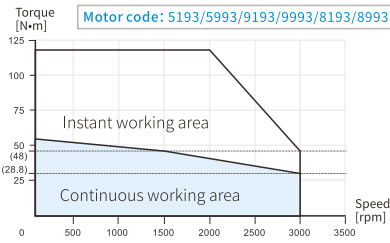
MS6H-180CN/CM/TL15B(Z)2-44P4



MS6H-180CN/CM15B/E(Z)2-45P5
MS6H-180TL15B(Z)2-45P5

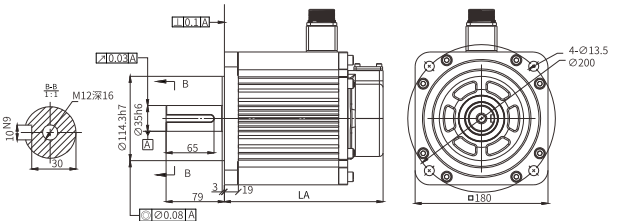


MS6H-180CN/CM15B/E(Z)2-47P5
MS6H-180TL15B/E(Z)2-47P5

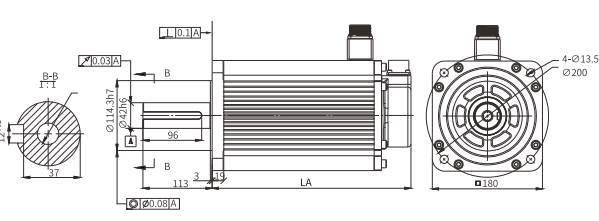


Motor dimension (unit: mm)

180 flange



Motor model	LA±1		LR ±0.5	LC	X	φD	Key width	Inertia level
	Normal	With brake						
MS6H-180□□15B□2-43P0	215	255	79	65	16	35	10	High inertia
MS6H-180□□15B□2-44P4	247	287						
MS6H-180□□15E□2-45P5	269	309						
MS6H-180□□15E□2-47P5	325	365						



Motor model	LA±1		LR ±0.5	LC	X	φD	Key width	Inertia level
	Normal	With brake						
MS6H-180□□15B□2-45P5	269	309	113	96	16	42	12	High inertia
MS6H-180□□15B□2-47P5	325	365						

Selection and configuration list

I MS6 series

DS5 series is compatible with MS6-B4 series motors								
Power(kW)	Inertia level	Motor model	Suitable driver	Voltage level	Encoder cable	Power cable	Brake cable	Cable accessory package
0.05	High inertia	MS6H-40CM30B4-20A5	DS5L1/C1/K1/N1-20P1-PTA	AC 220V	CP(T)-SP-BM-length	CM(T)-P07A-M-length	/	JAM-P9-P4
		MS6H-40CM30BZ4-20A5			CP(T)-SP-BM-length	CM(T)-P07A-M-length	CB(T)-P03-length	JAM-P9-P4-P2
0.1	High inertia	MS6H-40CM30B4-20P1	DS5L1/C1/K1/N1-20P1-PTA		CP(T)-SP-BM-length	CM(T)-P07A-M-length	/	JAM-P9-P4
		MS6H-40CM30BZ4-20P1			CP(T)-SP-BM-length	CM(T)-P07A-M-length	CB(T)-P03-length	JAM-P9-P4-P2
0.2	High inertia	MS6H-60CM30B4-20P2	DS5L1/C1/K1/N1-20P2-PTA		CP(T)-SP-BM-length	CM(T)-P07A-M-length	/	JAM-P9-P4
		MS6H-60CM30BZ4-20P2			CP(T)-SP-BM-length	CM(T)-P07A-M-length	CB(T)-P03-length	JAM-P9-P4-P2
0.4	Low inertia	MS6S-60CM30B4-20P4	DS5L1/C1/K1/N1-20P4-PTA		CP(T)-SP-BM-length	CM(T)-P07A-M-length	/	JAM-P9-P4
		MS6S-60CM30BZ4-20P4			CP(T)-SP-BM-length	CM(T)-P07A-M-length	CB(T)-P03-length	JAM-P9-P4-P2
	High inertia	MS6H-60CM30B4-20P4			CP(T)-SP-BM-length	CM(T)-P07A-M-length	CB(T)-P03-length	JAM-P9-P4-P2
		MS6H-60CM30BZ4-20P4			CP(T)-SP-BM-length	CM(T)-P07A-M-length	/	JAM-P9-P4
0.75	Low inertia	MS6S-80CM30B4-20P7	DS5L1/C1/K1/N1-20P7-PTA		CP(T)-SP-BM-length	CM(T)-P07A-M-length	CB(T)-P03-length	JAM-P9-P4-P2
		MS6S-80CM30BZ4-20P7			CP(T)-SP-BM-length	CM(T)-P07A-M-length	/	JAM-P9-P4
	High inertia	MS6H-80CM30B4-20P7			CP(T)-SP-BM-length	CM(T)-P07A-M-length	CB(T)-P03-length	JAM-P9-P4-P2
		MS6H-80CM30BZ4-20P7			CP(T)-SP-BM-length	CM(T)-P07A-M-length	/	JAM-P9-P4
1.0	High inertia	MS6H-80CM30B4-21P0	DS5L1/C1/K1/N1-20P7-PTA		CP(T)-SP-BM-length	CM(T)-P07A-M-length	/	JAM-P9-P4
		MS6H-80CM30BZ4-21P0			CP(T)-SP-BM-length	CM(T)-P07A-M-length	CB(T)-P03-length	JAM-P9-P4-P2

DS5 series is compatible with MS6-B3 series motors											
80 flange and below connector form motor											
Power [kW]	Inertia level	Motor model	Suitable driver	Voltage level	Forward outlet		Reverse outlet		The adapter cable only supports forward outlet		
					Encoder cable	Power cable	Encoder cable	Power cable			
0.1	High inertia	MS6H-40CM30B3-20P1	DS5L1/C1/K1-20P1-PTA DS5P-20P1-PTA	AC 220V	CP(T)-SE-BM-length	CM(T)-E03A-length	CP(T)-SF-BM-length	CM(T)-F03A-length	CPT-EP/CMT-EP03		
		MS6H-40CM30BZ3-20P1			CP(T)-SE-BM-length	CMB(T)-E03A-length	CP(T)-SF-BM-length	CMB(T)-F03A-length	CPT-EP/CMBT-EP03		
	High inertia	MS6H-40TL30B3-20P1			CP(T)-SE-BM-length	CM(T)-E03A-length	CP(T)-SF-BM-length	CM(T)-F03A-length	CPT-EP/CMT-EP03		
		MS6H-40TL30BZ3-20P1			CP(T)-SE-BM-length	CMB(T)-E03A-length	CP(T)-SF-BM-length	CMB(T)-F03A-length	CPT-EP/CMBT-EP03		
	High inertia	MS6H-40CN30B3-20P1	DS5L2/C2/K2-20P1-PTA		CP(T)-SE-BM-length	CM(T)-E03A-length	CP(T)-SF-BM-length	CM(T)-F03A-length	CPT-EP/CMT-EP03		
		MS6H-40CN30BZ3-20P1			CP(T)-SE-BM-length	CMB(T)-E03A-length	CP(T)-SF-BM-length	CMB(T)-F03A-length	CPT-EP/CMBT-EP03		
		MS6H-40TH30B3-20P1			CP(T)-SE-BM-length	CM(T)-E03A-length	CP(T)-SF-BM-length	CM(T)-F03A-length	CPT-EP/CMT-EP03		
		MS6H-40TH30BZ3-20P1			CP(T)-SE-BM-length	CMB(T)-E03A-length	CP(T)-SF-BM-length	CMB(T)-F03A-length	CPT-EP/CMBT-EP03		
	High inertia	MS6H-60CM30B3-20P2	DS5L1/C1/K1-20P2-PTA DS5P-20P2-PTA		CP(T)-SE-BM-length	CM(T)-E05A-length	CP(T)-SF-BM-length	CM(T)-F05A-length	CPT-EP/CMT-EP05		
		MS6H-60CM30BZ3-20P2			CP(T)-SE-BM-length	CMB(T)-E05A-length	CP(T)-SF-BM-length	CMB(T)-F05A-length	CPT-EP/CMBT-EP05		
	High inertia	MS6H-60TL30B3-20P2			DS5L2-20P2-PTA DS5C2/K2-20P4-PTA		CP(T)-SE-BM-length	CM(T)-E05A-length	CP(T)-SF-BM-length	CM(T)-F05A-length	CPT-EP/CMT-EP05
		MS6H-60TL30BZ3-20P2					CP(T)-SE-BM-length	CMB(T)-E05A-length	CP(T)-SF-BM-length	CMB(T)-F05A-length	CPT-EP/CMBT-EP05
0.2	High inertia	MS6H-60CN30B3-20P2	DS5L2-20P2-PTA DS5C2/K2-20P4-PTA		CP(T)-SE-BM-length	CM(T)-E05A-length	CP(T)-SF-BM-length	CM(T)-F05A-length	CPT-EP/CMT-EP05		
		MS6H-60CN30BZ3-20P2			CP(T)-SE-BM-length	CM(T)-E05A-length	CP(T)-SF-BM-length	CM(T)-F05A-length	CPT-EP/CMT-EP05		
		MS6H-60TH30B3-20P2			CP(T)-SE-BM-length	CM(T)-E05A-length	CP(T)-SF-BM-length	CM(T)-F05A-length	CPT-EP/CMT-EP05		
		MS6H-60TH30BZ3-20P2			CP(T)-SE-BM-length	CMB(T)-E05A-length	CP(T)-SF-BM-length	CMB(T)-F05A-length	CPT-EP/CMBT-EP05		
	Low inertia	MS6S-60CM30B3-20P4	DS5L1/C1/K1-20P4-PTA DS5P-20P4-PTA		CP(T)-SE-BM-length	CM(T)-E05A-length	CP(T)-SF-BM-length	CM(T)-F05A-length	CPT-EP/CMT-EP05		
		MS6S-60CM30BZ3-20P4			CP(T)-SE-BM-length	CM(T)-E05A-length	CP(T)-SF-BM-length	CM(T)-F05A-length	CPT-EP/CMT-EP05		
		MS6S-60TL30B3-20P4			CP(T)-SE-BM-length	CM(T)-E05A-length	CP(T)-SF-BM-length	CM(T)-F05A-length	CPT-EP/CMT-EP05		
		MS6H-60TL30BZ3-20P4			CP(T)-SE-BM-length	CMB(T)-E05A-length	CP(T)-SF-BM-length	CMB(T)-F05A-length	CPT-EP/CMBT-EP05		
	High inertia	MS6H-60CM30B3-20P4	DS5L1/C1/K1-20P4-PTA DS5P-20P4-PTA		CP(T)-SE-BM-length	CM(T)-E05A-length	CP(T)-SF-BM-length	CM(T)-F05A-length	CPT-EP/CMT-EP05		
		MS6H-60CM30BZ3-20P4			CP(T)-SE-BM-length	CM(T)-E05A-length	CP(T)-SF-BM-length	CM(T)-F05A-length	CPT-EP/CMT-EP05		
		MS6H-60TL30B3-20P4			CP(T)-SE-BM-length	CM(T)-E05A-length	CP(T)-SF-BM-length	CM(T)-F05A-length	CPT-EP/CMT-EP05		
		MS6H-60TL30BZ3-20P4			CP(T)-SE-BM-length	CMB(T)-E05A-length	CP(T)-SF-BM-length	CMB(T)-F05A-length	CPT-EP/CMBT-EP05		
	Low inertia	MS6S-60CN30B3-20P4	DS5L2/C2/K2-20P4-PTA		CP(T)-SE-BM-length	CM(T)-E05A-length	CP(T)-SF-BM-length	CM(T)-F05A-length	CPT-EP/CMT-EP05		
		MS6S-60CN30BZ3-20P4			CP(T)-SE-BM-length	CM(T)-E05A-length	CP(T)-SF-BM-length	CM(T)-F05A-length	CPT-EP/CMT-EP05		
		MS6S-60TH30B3-20P4			CP(T)-SE-BM-length	CM(T)-E05A-length	CP(T)-SF-BM-length	CM(T)-F05A-length	CPT-EP/CMT-EP05		
		MS6S-60TH30BZ3-20P4			CP(T)-SE-BM-length	CMB(T)-E05A-length	CP(T)-SF-BM-length	CMB(T)-F05A-length	CPT-EP/CMBT-EP05		
	High inertia	MS6H-60CN30B3-20P4	DS5L2/C2/K2-20P4-PTA		CP(T)-SE-BM-length	CM(T)-E05A-length	CP(T)-SF-BM-length	CM(T)-F05A-length	CPT-EP/CMT-EP05		
		MS6H-60CN30BZ3-20P4			CP(T)-SE-BM-length	CM(T)-E05A-length	CP(T)-SF-BM-length	CM(T)-F05A-length	CPT-EP/CMT-EP05		
		MS6H-60TH30B3-20P4			CP(T)-SE-BM-length	CM(T)-E05A-length	CP(T)-SF-BM-length	CM(T)-F05A-length	CPT-EP/CMT-EP05		
		MS6H-60TH30BZ3-20P4			CP(T)-SE-BM-length	CMB(T)-E05A-length	CP(T)-SF-BM-length	CMB(T)-F05A-length	CPT-EP/CMBT-EP05		
	0.4	Low inertia	MS6S-60CN30B3-20P4		DS5L1/C1/K1-20P4-PTA DS5P-20P4-PTA		CP(T)-SE-BM-length	CM(T)-E05A-length	CP(T)-SF-BM-length	CM(T)-F05A-length	CPT-EP/CMT-EP05
			MS6S-60CN30BZ3-20P4				CP(T)-SE-BM-length	CM(T)-E05A-length	CP(T)-SF-BM-length	CM(T)-F05A-length	CPT-EP/CMT-EP05
			MS6S-60TL30B3-20P4				CP(T)-SE-BM-length	CM(T)-E05A-length	CP(T)-SF-BM-length	CM(T)-F05A-length	CPT-EP/CMT-EP05
			MS6H-60TL30BZ3-20P4				CP(T)-SE-BM-length	CMB(T)-E05A-length	CP(T)-SF-BM-length	CMB(T)-F05A-length	CPT-EP/CMBT-EP05
High inertia		MS6H-60CM30B3-20P4	DS5L1/C1/K1-20P4-PTA DS5P-20P4-PTA		CP(T)-SE-BM-length	CM(T)-E05A-length	CP(T)-SF-BM-length	CM(T)-F05A-length	CPT-EP/CMT-EP05		
		MS6H-60CM30BZ3-20P4			CP(T)-SE-BM-length	CM(T)-E05A-length	CP(T)-SF-BM-length	CM(T)-F05A-length	CPT-EP/CMT-EP05		
		MS6H-60TL30B3-20P4			CP(T)-SE-BM-length	CM(T)-E05A-length	CP(T)-SF-BM-length	CM(T)-F05A-length	CPT-EP/CMT-EP05		
		MS6H-60TL30BZ3-20P4			CP(T)-SE-BM-length	CMB(T)-E05A-length	CP(T)-SF-BM-length	CMB(T)-F05A-length	CPT-EP/CMBT-EP05		
Low inertia		MS6S-60CN30B3-20P4	DS5L2/C2/K2-20P4-PTA		CP(T)-SE-BM-length	CM(T)-E05A-length	CP(T)-SF-BM-length	CM(T)-F05A-length	CPT-EP/CMT-EP05		
		MS6S-60CN30BZ3-20P4			CP(T)-SE-BM-length	CM(T)-E05A-length	CP(T)-SF-BM-length	CM(T)-F05A-length	CPT-EP/CMT-EP05		
		MS6S-60TH30B3-20P4			CP(T)-SE-BM-length	CM(T)-E05A-length	CP(T)-SF-BM-length	CM(T)-F05A-length	CPT-EP/CMT-EP05		
		MS6S-60TH30BZ3-20P4			CP(T)-SE-BM-length	CMB(T)-E05A-length	CP(T)-SF-BM-length	CMB(T)-F05A-length	CPT-EP/CMBT-EP05		
High inertia		MS6H-60CN30B3-20P4	DS5L2/C2/K2-20P4-PTA		CP(T)-SE-BM-length	CM(T)-E05A-length	CP(T)-SF-BM-length	CM(T)-F05A-length	CPT-EP/CMT-EP05		
		MS6H-60CN30BZ3-20P4			CP(T)-SE-BM-length	CM(T)-E05A-length	CP(T)-SF-BM-length	CM(T)-F05A-length	CPT-EP/CMT-EP05		
		MS6H-60TH30B3-20P4			CP(T)-SE-BM-length	CM(T)-E05A-length	CP(T)-SF-BM-length	CM(T)-F05A-length	CPT-EP/CMT-EP05		
		MS6H-60TH30BZ3-20P4			CP(T)-SE-BM-length	CMB(T)-E05A-length	CP(T)-SF-BM-length	CMB(T)-F05A-length	CPT-EP/CMBT-EP05		
Low inertia		MS6S-80CM30B3-20P7	DS5L1/C1/K1-20P7-PTA DS5P-20P7-PTA		CP(T)-SE-BM-length	CM(T)-E05A-length	CP(T)-SF-BM-length	CM(T)-F05A-length	CPT-EP/CMT-EP05		
		MS6S-80CM30BZ3-20P7			CP(T)-SE-BM-length	CM(T)-E05A-length	CP(T)-SF-BM-length	CM(T)-F05A-length	CPT-EP/CMT-EP05		
		MS6S-80TL30B3-20P7			CP(T)-SE-BM-length	CM(T)-E05A-length	CP(T)-SF-BM-length	CM(T)-F05A-length	CPT-EP/CMT-EP05		
		MS6H-80TL30BZ3-20P7			CP(T)-SE-BM-length	CMB(T)-E05A-length	CP(T)-SF-BM-length	CMB(T)-F05A-length	CPT-EP/CMBT-EP05		
High inertia		MS6H-80CM30B3-20P7	DS5L1/C1/K1-20P7-PTA DS5P-20P7-PTA		CP(T)-SE-BM-length	CM(T)-E05A-length	CP(T)-SF-BM-length	CM(T)-F05A-length	CPT-EP/CMT-EP05		
		MS6H-80CM30BZ3-20P7			CP(T)-SE-BM-length	CM(T)-E05A-length	CP(T)-SF-BM-length	CM(T)-F05A-length	CPT-EP/CMT-EP05		
		MS6H-80TL30B3-20P7			CP(T)-SE-BM-length	CM(T)-E05A-length	CP(T)-SF-BM-length	CM(T)-F05A-length	CPT-EP/CMT-EP05		
		MS6H-80TL30BZ3-20P7			CP(T)-SE-BM-length	CMB(T)-E05A-length	CP(T)-SF-BM-length	CMB(T)-F05A-length	CPT-EP/CMBT-EP05		
0.75	Low inertia	MS6S-80CN30B3-20P7	DS5L2/C2/K2-20P7-PTA		CP(T)-SE-BM-length	CM(T)-E05A-length	CP(T)-SF-BM-length	CM(T)-F05A-length	CPT-EP/CMT-EP05		
		MS6S-80CN30BZ3-20P7			CP(T)-SE-BM-length	CM(T)-E05A-length	CP(T)-SF-BM-length	CM(T)-F05A-length	CPT-EP/CMT-EP05		
		MS6S-80TL30B3-20P7			CP(T)-SE-BM-length	CM(T)-E05A-length	CP(T)-SF-BM-length	CM(T)-F05A-length	CPT-EP/CMT-EP05		
		MS6H-80TL30BZ3-20P7			CP(T)-SE-BM-length	CMB(T)-E05A-length	CP(T)-SF-BM-length	CMB(T)-F05A-length	CPT-EP/CMBT-EP05		
	High inertia	MS6H-80CM30B3-21P0	DS5L1/C1/K1-20P7-PTA DS5P-20P7-PTA		CP(T)-SE-BM-length	CM(T)-E05A-length	CP(T)-SF-BM-length	CM(T)-F05A-length	CPT-EP/CMT-EP05		
		MS6H-80CM30BZ3-21P0			CP(T)-SE-BM-length	CM(T)-E05A-length	CP(T)-SF-BM-length	CM(T)-F05A-length	CPT-EP/CMT-EP05		
		MS6S-80TH30B3-21P0			CP(T)-SE-BM-length	CM(T)-E05A-length	CP(T)-SF-BM-length	CM(T)-F05A-length	CPT-EP/CMT-EP05		
		MS6S-80TH30BZ3-21P0			CP(T)-SE-BM-length	CMB(T)-E05A-length	CP(T)-SF-BM-length	CMB(T)-F05A-length	CPT-EP/CMBT-EP05		
	Low inertia	MS6H-80CN30B3-20P7	DS5L2/C2/K2-20P7-PTA		CP(T)-SE-BM-length	CM(T)-E05A-length	CP(T)-SF-BM-length	CM(T)-F05A-length	CPT-EP/CMT-EP05		
		MS6H-80CN30BZ3-20P7			CP(T)-SE-BM-length	CM(T)-E05A-length	CP(T)-SF-BM-length	CM(T)-F05A-length	CPT-EP/CMT-EP05		
		MS6S-80TL30B3-21P0			CP(T)-SE-BM-length	CM(T)-E05A-length	CP(T)-SF-BM-length	CM(T)-F05A-length	CPT-EP/CMT-EP05		
		MS6S-80TL30BZ3-21P0			CP(T)-SE-BM-length	CMB(T)-E05A-length	CP(T)-SF-BM-length	CMB(T)-F05A-length	CPT-EP/CMBT-EP05		
	High inertia	MS6H-80CN30B3-20P7	DS5L1/C1/K1-20P7-PTA DS5P-20P7-PTA		CP(T)-SE-BM-length	CM(T)-E05A-length	CP(T)-SF-BM-length	CM(T)-F05A-length	CPT-EP/CMT-EP05		
		MS6H-80CN30BZ3-20P7			CP(T)-SE-BM-length	CM(T)-E05A-length	CP(T)-SF-BM-length	CM(T)-F05A-length	CPT-EP/CMT-EP05		
		MS6H-80TL30B3-20P7			CP(T)-SE-BM-length	CM(T)-E05A-length	CP(T)-SF-BM-length	CM(T)-F05A-length	CPT-EP/CMT-EP05		
		MS6H-80TL30BZ3-20P7			CP(T)-SE-BM-length	CMB(T)-E05A-length	CP(T)-SF-BM-length	CMB(T)-F05A-length	CPT-EP/CMBT-EP05		
	1.0	Low inertia	MS6S-80CM30B3-21P0	DS5L1/C1/K1-20P7-PTA		CP(T)-SE-BM-length	CM(T)-E05A-length	CP(T)-SF-BM-length	CM(T)-F05A-length	CPT-EP/CMT-EP05	
			MS6S-80CM30BZ3-21P0			CP(T)-SE-BM-length	CM(T)-E05A-length	CP(T)-SF-BM-length	CM(T)-F05A-length	CPT-EP/CMT-EP05	
			MS6S-80TL30B3-21P0			CP(T)-SE-BM-length	CM(T)-E05A-length	CP(T)-SF-BM-length	CM(T)-F05A-length	CPT-EP/CMT-EP05	
			MS6H-80TL30BZ3-21P0			CP(T)-SE-BM-length	CMB(T)-E05A-length	CP(T)-SF-BM-length	CMB(T)-F05A-length	CPT-EP/CMBT-EP05	
		High inertia	MS6H-80CM30B3-21P0	DS5L1/C1/K1-20P7-PTA DS5P-20P7-PTA		CP(T)-SE-BM-length	CM(T)-E05A-length	CP(T)-SF-BM-length	CM(T)-F05A-length	CPT-EP/CMT-EP05	
			MS6H-80CM30BZ3-21P0			CP(T)-SE-BM-length	CM(T)-E05A-length	CP(T)-SF-BM-length	CM(T)-F05A-length	CPT-EP/CMT-EP05	
			MS6H-80TL30B3-21P0			CP(T)-SE-BM-length	CM(T)-E05A-length	CP(T)-SF-BM-length	CM(T)-F05A-length	CPT-EP/CMT-EP05	
			MS6H-80TL30BZ3-21P0			CP(T)-SE-BM-length	CMB(T)-E05A-length	CP(T)-SF-BM-length	CMB(T)-F05A-length	CPT-EP/CMBT-EP05	
Low inertia		MS6S-80CN30B3-21P0	DS5L2/C2/K2-20P7-PTA		CP(T)-SE-BM-length	CM(T)-E05A-length	CP(T)-SF-BM-length	CM(T)-F05A-length	CPT-EP/CMT-EP05		
		MS6S-80CN30BZ3-21P0			CP(T)-SE-BM-length	CM(T)-E05A-length	CP(T)-SF-BM-length	CM(T)-F05A-length	CPT-EP/CMT-EP05		
		MS6S-80TH30B3-21P0			CP(T)-SE-BM-length	CM(T)-E05A-length	CP(T)-SF-BM-length	CM(T)-F05A-length	CPT-EP/CMT-EP05		
		MS6S-80TH30BZ3-21P0			CP(T)-SE-BM-length	CMB(T)-E05A-length	CP(T)-SF-BM-length	CMB(T)-F05A-length	CPT-EP/CMBT-EP05		
High inertia		MS6H-80CN30B3-21P0	DS5L2/C2/K2-20P7-PTA		CP(T)-SE-BM-length	CM(T)-E05A-length	CP(T)-SF-BM-length	CM(T)-F05A-length	CPT-EP/CMT-EP05		
		MS6H-80CN30BZ3-21P0			CP(T)-SE-BM-length	CM(T)-E05A-length	CP(T)-SF-BM-length	CM(T)-F05A-length	CPT-EP/CMT-EP05		
		MS6H-80TH30B3-21P0			CP(T)-SE-BM-length	CM(T)-E05A-length	CP(T)-SF-BM-length	CM(T)-F05A-length	CPT-EP/CMT-EP05		
		MS6H-80TH30BZ3-21P0			CP(T)-SE-BM-length	CMB(T)-E05A-length	CP(T)-SF-BM-length	CMB(T)-F05A-length	CPT-EP/CMBT-EP05		

*Note: 1. Choose either forward outlet or reverse outlet.
2. Select either CMT or CMBT for connection cables, choose CMT for non-brake models and CMBT for brake models.
3. CPT-SCT-M-length refers to the encoder cable length, where "T" in CPT stands for high-flex encoder cable, and "T" in SCT stands for encoder aviation plug with threaded hole.
4. If using an adapter cable, purchase the corresponding B1 motor encoder cable and power cable.
5. For forward outlet, optional oil-resistant cable materials include CPG-SE-M/BM-length, CMG-E03A-length, and CMG-E05A-length.
6. High protection models can choose FH series drivers.

Selection and configuration list

I MS6 series

DS5 series is compatible with MS6-B2 series motors								
Power[kW]	Inertia level	Motor model	Suitable driver	Voltage level	Encoder cable	Power cable	Brake cable	Cable accessory package
0.85	High inertia	MS6H-130CM15B2-20P8	DS5L1/C1/P-21P0-PTA	AC 220V	CP(T)-SC(T)-B-length	CM(T)-L15B-length	/	JAM-C10(T)-L4
		MS6H-130CM15B22-20P8			CP(T)-SC(T)-B-length	CMB(T)-L15B-length	/	JAM-C10(T)-L7
		MS6H-130TL15B2-20P8			CP(T)-SC(T)-B-length	CM(T)-L15B-length	/	JAM-C10(T)-L4
		MS6H-130TL15B22-20P8			CP(T)-SC(T)-B-length	CMB(T)-L15B-length	/	JAM-C10(T)-L7
	Medium inertia	MS6G-130CN15B2-20P8	DS5C2/L2/K2-20P7-PTA		CP(T)-SCT-B-length	CM(T)-L15T-length	/	JAM-C10T-L4T
		MS6G-130CN15B22-20P8			CP(T)-SCT-B-length	CMB(T)-L15T-length	/	JAM-C10T-L6T
		MS6G-130TH15B2-20P8			CP(T)-SCT-B-length	CM(T)-L15T-length	/	JAM-C10T-L4T
		MS6G-130TH15B22-20P8			CP(T)-SCT-B-length	CMB(T)-L15T-length	/	JAM-C10T-L6T
	High inertia	MS6H-130CM15B2-40P8	DS5L1/C1/P-41P0-PTA	AC 380V	CP(T)-SC(T)-B-length	CM(T)-L15B-length	/	JAM-C10(T)-L4
		MS6H-130CM15B22-40P8			CP(T)-SC(T)-B-length	CMB(T)-L15B-length	/	JAM-C10(T)-L7
		MS6H-130TL15B2-40P8			CP(T)-SC(T)-B-length	CM(T)-L15B-length	/	JAM-C10(T)-L4
		MS6H-130TL15B22-40P8			CP(T)-SC(T)-B-length	CMB(T)-L15B-length	/	JAM-C10(T)-L7
	Medium inertia	MS6G-130CN15B2-40P8	DS5L2/C2/K2-41P0-PTA		CP(T)-SCT-B-length	CM(T)-L15T-length	/	JAM-C10T-L4T
		MS6G-130CN15B22-40P8			CP(T)-SCT-B-length	CMB(T)-L15T-length	/	JAM-C10T-L6T
		MS6G-130TH15B2-40P8			CP(T)-SCT-B-length	CM(T)-L15T-length	/	JAM-C10T-L4T
		MS6G-130TH15B22-40P8			CP(T)-SCT-B-length	CMB(T)-L15T-length	/	JAM-C10T-L6T
1.0	Low inertia	MS6S-100CM30B2-21P0	DS5L1/C1-21P0-PTA DS5P-21P0-PTA	AC 220V	CP(T)-SC(T)-B-length	CM(T)-L15B-length	/	JAM-C10(T)-L4
		MS6S-100TL30B2-21P0			CP(T)-SC(T)-B-length	CM(T)-L15B-length	/	JAM-C10(T)-L4
		MS6S-100CM30B22-21P0			CP(T)-SC(T)-B-length	CMB(T)-L15B-length	/	JAM-C10(T)-L7
		MS6S-100TL30B22-21P0			CP(T)-SC(T)-B-length	CMB(T)-L15B-length	/	JAM-C10(T)-L7
	Medium inertia	MS6G-130CM25B2-21P0	DS5L1/C1-21P0-PTA DS5P-21P0-PTA		CP(T)-SCT-B-length	CM(T)-L15T-length	/	JAM-C10T-L4T
		MS6G-130TL25B2-21P0			CP(T)-SCT-B-length	CM(T)-L15T-length	/	JAM-C10T-L4T
		MS6G-130CM25B22-21P0			CP(T)-SCT-B-length	CMB(T)-L15T-length	/	JAM-C10T-L6T
		MS6G-130TL25B22-21P0			CP(T)-SCT-B-length	CMB(T)-L15T-length	/	JAM-C10T-L6T
		MS6G-130CM25B2-41P0	DS5L1/C1/P-41P0-PTA	AC 380V	CP(T)-SCT-B-length	CM(T)-L15T-length	/	JAM-C10T-L4T
		MS6G-130TL25B2-41P0			CP(T)-SCT-B-length	CM(T)-L15T-length	/	JAM-C10T-L4T
		MS6G-130CM25B22-41P0			CP(T)-SCT-B-length	CMB(T)-L15T-length	/	JAM-C10T-L6T
		MS6G-130TL25B22-41P0			CP(T)-SCT-B-length	CMB(T)-L15T-length	/	JAM-C10T-L6T
		MS6G-130CN25B2-21P0	DS5L2/C2/K2-21P0-PTA	AC 220V	CP(T)-SCT-B-length	CM(T)-L15T-length	/	JAM-C10T-L6T
		MS6G-130TH25B2-21P0			CP(T)-SCT-B-length	CM(T)-L15T-length	/	JAM-C10T-L4T
		MS6G-130TH25B22-21P0			CP(T)-SCT-B-length	CMB(T)-L15T-length	/	JAM-C10T-L6T
		MS6G-130CN25B2-41P0			CP(T)-SCT-B-length	CM(T)-L15T-length	/	JAM-C10T-L4T
MS6G-130CN25B22-41P0	DS5L2/C2/K2-41P0-PTA	AC 380V	CP(T)-SCT-B-length	CM(T)-L15T-length	/	JAM-C10T-L6T		
MS6G-130TH25B2-41P0			CP(T)-SCT-B-length	CM(T)-L15T-length	/	JAM-C10T-L4T		
MS6G-130TH25B22-41P0			CP(T)-SCT-B-length	CMB(T)-L15T-length	/	JAM-C10T-L6T		
MS6G-130CN25B22-41P0			CP(T)-SCT-B-length	CMB(T)-L15T-length	/	JAM-C10T-L6T		
1.3	High inertia	MS6H-130CM15B2-41P3	DS5L1/C1/P-41P5-PTA	AC 380V	CP(T)-SC(T)-B-length	CM(T)-L15B-length	/	JAM-C10(T)-L4
		MS6H-130CM15B22-41P3			CP(T)-SC(T)-B-length	CMB(T)-L15B-length	/	JAM-C10(T)-L7
		MS6H-130TL15B2-41P3			CP(T)-SC(T)-B-length	CM(T)-L15B-length	/	JAM-C10(T)-L4
		MS6H-130TL15B22-41P3			CP(T)-SC(T)-B-length	CMB(T)-L15B-length	/	JAM-C10(T)-L7
	ultra low inertia	MS6L-100CN30B2-21P5	DS5L2/C2/K2-22P6-PTA	AC 220V	CP(T)-SCT-B-length	CM(T)-L15T-length	/	JAM-C10T-L4T
		MS6L-100CN30B22-21P5			CP(T)-SCT-B-length	CMB(T)-L15T-length	/	JAM-C10T-L6T
		MS6L-100TH30B2-21P5			CP(T)-SCT-B-length	CM(T)-L15T-length	/	JAM-C10T-L4T
		MS6L-100TH30B22-21P5			CP(T)-SCT-B-length	CMB(T)-L15T-length	/	JAM-C10T-L6T
		MS6L-100CN30B2-41P5	DS5L2/C2/K2-42P3-PTA	AC 380V	CP(T)-SCT-B-length	CM(T)-L15T-length	/	JAM-C10T-L4T
		MS6L-100CN30B22-41P5			CP(T)-SCT-B-length	CM(T)-L15T-length	/	JAM-C10T-L6T
		MS6L-100TH30B2-41P5			CP(T)-SCT-B-length	CM(T)-L15T-length	/	JAM-C10T-L4T
		MS6L-100TH30B22-41P5			CP(T)-SCT-B-length	CMB(T)-L15T-length	/	JAM-C10T-L6T
	Low inertia	MS6S-100CM30B2-21P5	DS5L1/C1/P-21P5-PTA	AC 220V	CP(T)-SC(T)-B-length	CM(T)-L15B-length	/	JAM-C10(T)-L4
		MS6S-100CM30B22-21P5			CP(T)-SC(T)-B-length	CMB(T)-L15B-length	/	JAM-C10(T)-L7
		MS6G-110CM30B2-21P5	DS5L1/C1/P-21P5-PTA DS5L1/C1/P-22P3-PTA	AC 220V	CP(T)-SCT-B-length	CM(T)-L15T-length	/	JAM-C10T-L4T
		MS6G-110TL30B2-21P5			CP(T)-SCT-B-length	CM(T)-L15T-length	/	JAM-C10T-L4T
MS6G-110CM30B22-21P5		CP(T)-SCT-B-length			CMB(T)-L15T-length	/	JAM-C10T-L6T	
MS6G-110TL30B22-21P5		CP(T)-SCT-B-length			CMB(T)-L15T-length	/	JAM-C10T-L6T	
MS6G-110CN30B2-21P5		CP(T)-SCT-B-length			CM(T)-L15T-length	/	JAM-C10T-L4T	
MS6G-110CN30B22-21P5		CP(T)-SCT-B-length			CMB(T)-L15T-length	/	JAM-C10T-L6T	
Medium inertia	MS6G-110TH30B2-21P5	DS5L2/C2/K2-21P5-PTA	AC 220V	CP(T)-SCT-B-length	CM(T)-L15T-length	/	JAM-C10T-L6T	
	MS6G-110TH30B22-21P5			CP(T)-SCT-B-length	CM(T)-L15T-length	/	JAM-C10T-L4T	
	MS6G-110TH30B2-21P5			CP(T)-SCT-B-length	CMB(T)-L15T-length	/	JAM-C10T-L4T	
	MS6G-110TH30B22-21P5			CP(T)-SCT-B-length	CMB(T)-L15T-length	/	JAM-C10T-L6T	

DS5 series is compatible with MS6-B2 series motors									
Power[kW]	Inertia level	Motor model	Suitable driver	Voltage level	Encoder cable	Power cable	Brake cable	Cable accessory package	
1.5	Medium inertia	MS6G-110CM30B2-41P5	DS5L1/C1/P-41P5-PTA DS5L1/C1/P-42P3-PTA	AC 380V	CP(T)-SCT-B-length	CM(T)-L15T-length	/	JAM-C10T-L4T	
		MS6G-110TL30B2-41P5			CP(T)-SCT-B-length	CM(T)-L15T-length	/	JAM-C10T-L4T	
		MS6G-110CM30B2Z-41P5			CP(T)-SCT-B-length	CMB(T)-L15T-length	/	JAM-C10T-L6T	
		MS6G-110TL30B2Z-41P5			CP(T)-SCT-B-length	CMB(T)-L15T-length	/	JAM-C10T-L6T	
		MS6G-110CN30B2-41P5	DS5L2/C2/K2-41P5-PTA		CP(T)-SCT-B-length	CM(T)-L15T-length	/	JAM-C10T-L4T	
		MS6G-110CN30B2Z-41P5			CP(T)-SCT-B-length	CMB(T)-L15T-length	/	JAM-C10T-L6T	
		MS6G-110TH30B2-41P5			CP(T)-SCT-B-length	CM(T)-L15T-length	/	JAM-C10T-L4T	
		MS6G-110TH30B2Z-41P5			CP(T)-SCT-B-length	CMB(T)-L15T-length	/	JAM-C10T-L6T	
		MS6G-130CM20B2-21P5		CP(T)-SCT-B-length	CM(T)-L15T-length	/	JAM-C10T-L4T		
		MS6G-130TL20B2-21P5		CP(T)-SCT-B-length	CM(T)-L15T-length	/	JAM-C10T-L4T		
		MS6G-130CM20B2Z-21P5		CP(T)-SCT-B-length	CMB(T)-L15T-length	/	JAM-C10T-L6T		
		MS6G-130TL20B2Z-21P5		CP(T)-SCT-B-length	CMB(T)-L15T-length	/	JAM-C10T-L6T		
		MS6G-130CM15B2-21P5	DS5L1/C1/P-21P5-PTA DS5L1/C1/P-22P3-PTA	AC 220V	CP(T)-SCT-B-length	CMB(T)-L15T-length	/	JAM-C10T-L6T	
		MS6G-130CM15B2Z-21P5			CP(T)-SCT-B-length	CM(T)-L15T-length	/	JAM-C10T-L4T	
		MS6G-130TL15B2-21P5			CP(T)-SCT-B-length	CM(T)-L15T-length	/	JAM-C10T-L4T	
		MS6G-130CM15B2Z-21P5			CP(T)-SCT-B-length	CMB(T)-L15T-length	/	JAM-C10T-L6T	
		MS6G-130TL15B2Z-21P5	CP(T)-SCT-B-length		CMB(T)-L15T-length	/	JAM-C10T-L6T		
		MS6G-130CN20B2-21P5	DS5L2/C2/K2-21P5-PTA		CP(T)-SCT-B-length	CM(T)-L15T-length	/	JAM-C10T-L4T	
		MS6G-130CN20B2Z-21P5			CP(T)-SCT-B-length	CMB(T)-L15T-length	/	JAM-C10T-L6T	
		MS6G-130CN15B2-21P5			CP(T)-SCT-B-length	CM(T)-L15T-length	/	JAM-C10T-L4T	
		MS6G-130CN15B2Z-21P5			CP(T)-SCT-B-length	CM(T)-L15T-length	/	JAM-C10T-L4T	
		MS6G-130TH20B2-21P5			CP(T)-SCT-B-length	CMB(T)-L15T-length	/	JAM-C10T-L6T	
		MS6G-130TH20B2Z-21P5			CP(T)-SCT-B-length	CMB(T)-L15T-length	/	JAM-C10T-L6T	
		MS6G-130TH15B2-21P5			CP(T)-SCT-B-length	CM(T)-L15T-length	/	JAM-C10T-L4T	
		MS6G-130TH15B2Z-21P5			CP(T)-SCT-B-length	CMB(T)-L15T-length	/	JAM-C10T-L6T	
		MS6G-130CM20B2-41P5	DS5C1/L1/P-41P5-PTA DS5C1/L1/P-42P3-PTA		AC 380V	CP(T)-SCT-B-length	CM(T)-L15T-length	/	JAM-C10T-L4T
		MS6G-130CM20B2Z-41P5				CP(T)-SCT-B-length	CMB(T)-L15T-length	/	JAM-C10T-L6T
		MS6G-130TL20B2-41P5				CP(T)-SCT-B-length	CM(T)-L15T-length	/	JAM-C10T-L4T
		MS6G-130TL20B2Z-41P5		CP(T)-SCT-B-length		CMB(T)-L15T-length	/	JAM-C10T-L6T	
		MS6G-130TH20B2-41P5		CP(T)-SCT-B-length		CM(T)-L15T-length	/	JAM-C10T-L4T	
		MS6G-130TH20B2Z-41P5		CP(T)-SCT-B-length		CMB(T)-L15T-length	/	JAM-C10T-L6T	
		MS6G-130TH15B2-41P5		CP(T)-SCT-B-length		CM(T)-L15T-length	/	JAM-C10T-L4T	
	MS6G-130TH15B2Z-41P5	CP(T)-SCT-B-length		CMB(T)-L15T-length		/	JAM-C10T-L6T		
	High inertia	MS6H-130CM20B2-21P5	DS5L1/C1/P-21P5-PTA	AC 220V		CP(T)-SC(T)-B-length	CM(T)-L15B-length	/	JAM-C10(T)-L4
		MS6H-130CM20B2Z-21P5				CP(T)-SC(T)-B-length	CMB(T)-L15B-length	/	JAM-C10(T)-L7
		MS6H-130TL20B2-21P5				CP(T)-SC(T)-B-length	CM(T)-L15B-length	/	JAM-C10(T)-L4
		MS6H-130TL20B2Z-21P5				CP(T)-SC(T)-B-length	CMB(T)-L15B-length	/	JAM-C10(T)-L7
		MS6H-130CM15B2-21P8	DS5L1/C1/P-22P6-PTA	AC 220V	CP(T)-SC(T)-B-length	CM(T)-L15B-length	/	JAM-C10(T)-L4	
		MS6H-130CM15B2Z-21P8			CP(T)-SC(T)-B-length	CMB(T)-L15B-length	/	JAM-C10(T)-L7	
		MS6H-130TL15B2-21P8			CP(T)-SC(T)-B-length	CM(T)-L15B-length	/	JAM-C10(T)-L4	
MS6H-130TL15B2Z-21P8		CP(T)-SC(T)-B-length			CMB(T)-L15B-length	/	JAM-C10(T)-L7		
High inertia	MS6H-130CM15B2-41P8	DS5L1/C1/P-42P3-PTA	AC 380V	CP(T)-SC(T)-B-length	CM(T)-L15B-length	/	JAM-C10(T)-L4		
	MS6H-130CM15B2Z-41P8			CP(T)-SC(T)-B-length	CM(T)-L15B-length	/	JAM-C10(T)-L4		
	MS6H-130TL15B2-41P8			CP(T)-SC(T)-B-length	CMB(T)-L15B-length	/	JAM-C10(T)-L7		
	MS6H-130TL15B2Z-41P8			CP(T)-SC(T)-B-length	CMB(T)-L15B-length	/	JAM-C10(T)-L7		
2.3	Medium inertia	MS6G-130CM15B2-42P3	DS5L1/C1/P-42P3-PTA DS5L1/C1/P-43P0-PTA	AC 380V	CP(T)-SCT-B-length	CM(T)-L15T-length	/	JAM-C10T-L4T	
		MS6G-130TL15B2-42P3			CP(T)-SCT-B-length	CM(T)-L15T-length	/	JAM-C10T-L4T	
		MS6G-130CM15B2Z-42P3			CP(T)-SCT-B-length	CMB(T)-L15T-length	/	JAM-C10T-L6T	
		MS6G-130TL15B2Z-42P3			CP(T)-SCT-B-length	CMB(T)-L15T-length	/	JAM-C10T-L6T	

Selection and configuration list

I MS6 series

DS5 series is compatible with MS6-B2 series motors									
Power[kW]	Inertia level	Motor model	Suitable driver	Voltage level	Encoder cable	Power cable	Brake cable	Cable accessory package	
2.3	Medium inertia	MS6G-130CM15B2-22P3	DS5L1/C1/P-22P3-PTA	AC 220V	CP(T)-SCT-B-length	CM(T)-L15T-length	/	JAM-C10T-L4T	
		MS6G-130TL15B2-22P3			CP(T)-SCT-B-length	CM(T)-L15T-length	/	JAM-C10T-L4T	
		MS6G-130CM15BZ2-22P3			CP(T)-SCT-B-length	CMB(T)-L15T-length	/	JAM-C10T-L6T	
		MS6G-130TL15BZ2-22P3			CP(T)-SCT-B-length	CMB(T)-L15T-length	/	JAM-C10T-L6T	
		MS6G-130CM15E2-42P3	DS5L1/C1/P-42P3-PTA DS5L1/C1/P-43P0-PTA	AC 380V	CP(T)-SCT-B-length	CM(T)-L15T-length	/	JAM-C10T-L4T	
		MS6G-130TL15E2-42P3			CP(T)-SCT-B-length	CM(T)-L15T-length	/	JAM-C10T-L4T	
		MS6G-130CM15E2-42P3			CP(T)-SCT-B-length	CMB(T)-L15T-length	/	JAM-C10T-L6T	
		MS6G-130TL15E2-42P3			CP(T)-SCT-B-length	CMB(T)-L15T-length	/	JAM-C10T-L6T	
		MS6G-130CM15E2-22P3	DS5L1/C1/P-22P3-PTA	AC 220V	CP(T)-SCT-B-length	CM(T)-L15T-length	/	JAM-C10T-L4T	
		MS6G-130TL15E2-22P3			CP(T)-SCT-B-length	CM(T)-L15T-length	/	JAM-C10T-L4T	
		MS6G-130CM15E2-22P3			CP(T)-SCT-B-length	CMB(T)-L15T-length	/	JAM-C10T-L6T	
		MS6G-130TL15E2-22P3			CP(T)-SCT-B-length	CMB(T)-L15T-length	/	JAM-C10T-L6T	
	High inertia	MS6H-130CM15B2-22P3	DS5L1/C1/P-22P6-PTA	AC 220V	CP(T)-SC(T)-B-length	CM(T)-L15B-length	/	JAM-C10(T)-L4	
		MS6H-130CM15BZ2-22P3			CP(T)-SC(T)-B-length	CMB(T)-L15B-length	/	JAM-C10(T)-L7	
		MS6H-130TL15B2-22P3			CP(T)-SC(T)-B-length	CM(T)-L15B-length	/	JAM-C10(T)-L4	
		MS6H-130TL15BZ2-22P3			CP(T)-SC(T)-B-length	CMB(T)-L15B-length	/	JAM-C10(T)-L7	
		MS6H-130CM15B2-42P3	DS5L1/C1/P-42P3-PTA DS5L1/C1/P-43P0-PTA	AC 380V	CP(T)-SC(T)-B-length	CM(T)-L15B-length	/	JAM-C10(T)-L4	
		MS6H-130CM15BZ2-42P3			CP(T)-SC(T)-B-length	CMB(T)-L15B-length	/	JAM-C10(T)-L7	
		MS6H-130TL15B2-42P3			CP(T)-SC(T)-B-length	CM(T)-L15B-length	/	JAM-C10(T)-L4	
		MS6H-130TL15BZ2-42P3			CP(T)-SC(T)-B-length	CMB(T)-L15B-length	/	JAM-C10(T)-L7	
		Medium inertia	MS6G-130CN15B2-42P3	DS5L2/C2/K2-42P3-PTA	AC 380V	CP(T)-SCT-B-length	CM(T)-L15T-length	/	JAM-C10T-L4T
			MS6G-130CN15BZ2-42P3			CP(T)-SCT-B-length	CMB(T)-L15T-length	/	JAM-C10T-L6T
			MS6G-130TH15B2-42P3			CP(T)-SCT-B-length	CM(T)-L15T-length	/	JAM-C10T-L4T
			MS6G-130TH15BZ2-42P3			CP(T)-SCT-B-length	CMB(T)-L15T-length	/	JAM-C10T-L6T
	MS6G-130CN15B2-22P3		DS5L2/C2/K2-22P3-PTA	AC 220V	CP(T)-SCT-B-length	CM(T)-L15T-length	/	JAM-C10T-L4T	
	MS6G-130CN15BZ2-22P3				CP(T)-SCT-B-length	CM(T)-L15T-length	/	JAM-C10T-L6T	
	MS6G-130TH15B2-22P3				CP(T)-SCT-B-length	CM(T)-L15T-length	/	JAM-C10T-L4T	
	MS6G-130TH15BZ2-22P3				CP(T)-SCT-B-length	CMB(T)-L15T-length	/	JAM-C10T-L6T	
2.5	ultra low inertia	MS6L-100CN30B2-42P5	DS5L2/C2/K2-43P0-PTA	AC 380V	CP(T)-SCT-B-length	CM(T)-L15T-length	/	JAM-C10T-L4T	
		MS6L-100CN30BZ2-42P5			CP(T)-SCT-B-length	CMB(T)-L15T-length	/	JAM-C10T-L6T	
		MS6L-100TH30B2-42P5			CP(T)-SCT-B-length	CM(T)-L15T-length	/	JAM-C10T-L4T	
		MS6L-100TH30BZ2-42P5			CP(T)-SCT-B-length	CMB(T)-L15T-length	/	JAM-C10T-L6T	
3.0	High inertia	MS6H-180CM15B2-43P0	DS5L1/C1/P-43P0-PTA	AC 380V	CP(T)-SL-B-length	CM(T)-XL20A-length	/	JAM-L15-XL4	
		MS6H-180CM15BZ2-43P0			CP(T)-SL-B-length	CMB(T)-XL20A-length	/	JAM-L15-XL6	
		MS6H-180TL15B2-43P0			CP(T)-SL-B-length	CM(T)-XL20A-length	/	JAM-L15-XL4	
		MS6H-180TL15BZ2-43P0			CP(T)-SL-B-length	CMB(T)-XL20A-length	/	JAM-L15-XL6	
	High inertia	MS6H-180CN15B2-43P0	DS5L2/C2/K2-43P0-PTA	AC 380V	CP(T)-SL-B-length	CM(T)-XL20A-length	/	JAM-L15-XL4	
		MS6H-180CN15BZ2-43P0			CP(T)-SL-B-length	CMB(T)-XL20A-length	/	JAM-L15-XL6	
		MS6G-180CN15B2-43P0			CP(T)-SLT-B-length	CM(T)-XL20T-length	/	JAM-L15T-XL4T	
		MS6G-180CN15BZ2-43P0			CP(T)-SLT-B-length	CMB(T)-XL20T-length	/	JAM-L15T-XL6T	
	Medium inertia	MS6G-180TH15B2-43P0			CP(T)-SLT-B-length	CM(T)-XL20T-length	/	JAM-L15T-XL4T	
		MS6G-180TH15BZ2-43P0			CP(T)-SLT-B-length	CMB(T)-XL20T-length	/	JAM-L15T-XL6T	
		MS6S-130CN30B2-43P0			CP(T)-SCT-B-length	CM(T)-XL20T-length	/	JAM-C10T-XL4T	
		MS6S-130TH30B2-43P0			CP(T)-SCT-B-length	CM(T)-XL20T-length	/	JAM-C10T-XL4T	
		MS6S-130CN30BZ2-43P0			CP(T)-SCT-B-length	CMB(T)-XL20T-length	/	JAM-C10T-XL6T	
		MS6S-130TH30BZ2-43P0			CP(T)-SCT-B-length	CMB(T)-XL20T-length	/	JAM-C10T-XL6T	
	4.4	High inertia	MS6H-180CM15B2-44P4	DS5C1/P-45P5-PTA	AC 380V	CP(T)-SL-B-length	CM(T)-XL60-length	/	JAM-L15-XL4
			MS6H-180TL15B2-44P4			CP(T)-SL-B-length	CM(T)-XL60-length	/	JAM-L15-XL4
			MS6H-180CM15BZ2-44P4			CP(T)-SL-B-length	CMB(T)-XL60-length	/	JAM-L15-XL6
			MS6H-180TL15BZ2-44P4			CP(T)-SL-B-length	CMB(T)-XL60-length	/	JAM-L15-XL6
High inertia		MS6H-180CN15B2-44P4	DS5C2/K2-45P5-PTA			CP(T)-SL-B-length	CM(T)-XL60-length	/	JAM-L15-XL4
		MS6H-180CN15BZ2-44P4				CP(T)-SL-B-length	CMB(T)-XL60-length	/	JAM-L15-XL6
		MS6G-180CN15B2-44P4				CP(T)-SLT-B-length	CM(T)-XL60T-length	/	JAM-L15T-XL4T
		MS6G-180CN15BZ2-44P4				CP(T)-SLT-B-length	CMB(T)-XL60T-length	/	JAM-L15T-XL6T
Medium inertia		MS6G-180TH15B2-44P4				CP(T)-SLT-B-length	CM(T)-XL60T-length	/	JAM-L15T-XL4T
		MS6G-180TH15BZ2-44P4				CP(T)-SLT-B-length	CMB(T)-XL60T-length	/	JAM-L15T-XL6T
	MS6G-180TH15BZ2-44P4	CP(T)-SLT-B-length				CMB(T)-XL60T-length	/	JAM-L15T-XL6T	
	MS6S-130CN30B2-45P0	CP(T)-SCT-B-length				CM(T)-XL60T-length	/	JAM-C10T-XL4T	
	MS6S-130CN30BZ2-45P0	CP(T)-SCT-B-length				CMB(T)-XL60T-length	/	JAM-C10T-XL6T	
	MS6S-130TH30B2-45P0	CP(T)-SCT-B-length				CM(T)-XL60T-length	/	JAM-C10T-XL4T	
5.0	Low inertia	MS6S-130TH30BZ2-45P0	CP(T)-SCT-B-length	CM(T)-XL60T-length	/	JAM-C10T-XL6T			
		MS6S-130TH30BZ2-45P0	CP(T)-SCT-B-length	CMB(T)-XL60T-length	/	JAM-C10T-XL6T			

I MS6 series

DS5 series is compatible with MS6-B2 series motors											
Power[kW]	Inertia level	Motor model	Suitable driver	Voltage level	Encoder cable	Power cable	Brake cable	Cable accessory package			
5.5	High inertia	MS6H-180CM15B2-45P5	DS5C1/P-45P5-PTA	AC 380V	CP(T)-SL-B-length	CM(T)-XL60-length	/	JAM-L15-XL4			
		MS6H-180CM15BZ2-45P5			CP(T)-SL-B-length	CMB(T)-XL60-length	/	JAM-L15-XL6			
		MS6H-180TL15B2-45P5			CP(T)-SL-B-length	CM(T)-XL60-length	/	JAM-L15-XL4			
		MS6H-180TL15BZ2-45P5			CP(T)-SL-B-length	CMB(T)-XL60-length	/	JAM-L15-XL6			
		MS6H-180CM15E2-45P5			CP(T)-SL-B-length	CM(T)-XL60-length	/	JAM-L15-XL4			
		MS6H-180CM15E2-45P5			CP(T)-SL-B-length	CMB(T)-XL60-length	/	JAM-L15-XL6			
	High inertia	MS6H-180CN15B2-45P5	DS5C2/K2-45P5-PTA		CP(T)-SL-B-length	CM(T)-XL60-length	/	JAM-L15-XL4			
		MS6H-180CN15BZ2-45P5			CP(T)-SL-B-length	CMB(T)-XL60-length	/	JAM-L15-XL6			
		MS6H-180CN15E2-45P5			CP(T)-SL-B-length	CM(T)-XL60-length	/	JAM-L15-XL4			
		MS6H-180CN15E2-45P5			CP(T)-SL-B-length	CMB(T)-XL60-length	/	JAM-L15-XL6			
		Medium inertia			MS6G-180CN15B2-45P5	DS5C2/K2-45P5-PTA	CP(T)-SLT-B-length	CM(T)-XL60T-length	/	JAM-L15T-XL4T	
					MS6G-180CN15BZ2-45P5		CP(T)-SLT-B-length	CMB(T)-XL60T-length	/	JAM-L15T-XL6T	
	MS6G-180TH15B2-45P5		CP(T)-SLT-B-length		CM(T)-XL60T-length		/	JAM-L15T-XL4T			
	MS6G-180TH15BZ2-45P5		CP(T)-SLT-B-length		CMB(T)-XL60T-length		/	JAM-L15T-XL6T			
	7.5		High inertia		MS6H-180CM15B2-47P5		DS5C1/P-47P5-PTA	CP(T)-SL-B-length	CM(T)-XL60-length	/	JAM-L15-XL4
					MS6H-180TL15B2-47P5			CP(T)-SL-B-length	CMB(T)-XL60-length	/	JAM-L15-XL6
		MS6H-180CM15BZ2-47P5			CP(T)-SL-B-length	CM(T)-XL60-length		/	JAM-L15-XL4		
		MS6H-180TL15BZ2-47P5			CP(T)-SL-B-length	CMB(T)-XL60-length		/	JAM-L15-XL6		
MS6H-180CM15E2-47P5		CP(T)-SL-B-length			CM(T)-XL60-length	/		JAM-L15-XL4			
MS6H-180CM15E2-47P5		CP(T)-SL-B-length			CMB(T)-XL60-length	/		JAM-L15-XL6			
High inertia		MS6H-180CN15B2-47P5	DS5C2/K2-47P5-PTA		CP(T)-SL-B-length	CM(T)-XL60-length	/	JAM-L15-XL4			
		MS6H-180CN15BZ2-47P5			CP(T)-SL-B-length	CMB(T)-XL60-length	/	JAM-L15-XL6			
		MS6H-180CN15E2-47P5			CP(T)-SL-B-length	CM(T)-XL60-length	/	JAM-L15-XL4			
		MS6H-180CN15E2-47P5			CP(T)-SL-B-length	CMB(T)-XL60-length	/	JAM-L15-XL6			
		Medium inertia			MS6G-180CN15B2-47P5	DS5C2/K2-47P5-PTA	CP(T)-SLT-B-length	CM(T)-XL60T-length	/	JAM-L15T-XL4T	
					MS6G-180CN15BZ2-47P5		CP(T)-SLT-B-length	CMB(T)-XL60T-length	/	JAM-L15T-XL6T	
MS6G-180TH15B2-47P5	CP(T)-SLT-B-length		CM(T)-XL60T-length		/		JAM-L15T-XL4T				
MS6G-180TH15BZ2-47P5	CP(T)-SLT-B-length		CMB(T)-XL60T-length		/		JAM-L15T-XL6T				
13	Medium inertia		MS6G-200TH17B2-413P0-F		DS5C2-415P0-PTA		CPT-ZDL-B-length	CM(T)-D60-length	/	JAM-L15-D4	
			MS6G-200TH17BZ2-413P0-F				CPT-ZDL-B-length	CM(T)-D60-length	/	JAM-L15-D4	
		MS6G-200TH17B2-413P0-Y	CPT-ZDL-B-length			CM(T)-D60-length	/	JAM-L15-D4			
		MS6G-200TH17B2-417P0-F	CPT-ZDL-B-length			CM(T)-D60-length	/	JAM-L15-D4			
		17	Medium inertia			MS6G-200TH17BZ2-417P0-F	CPT-ZDL-B-length	CM(T)-D60-length	/	JAM-L15-D4	
						MS6G-200TH17B2-417P0-Y	CPT-ZDL-B-length	CM(T)-D60-length	/	JAM-L15-D4	

*Note: E2 motor is a special shaft diameter motor, with a special shaft diameter of 22mm for 2.3kw motor and 35mm for 5.5kw and 7.5kw motor.

Product accessories

| Quick connector

- Provide convenient wiring terminals
- For 100W~15kW drivers.



| Absolute value battery box

- Battery box model: CP-B-BATT
- The battery is not rechargeable



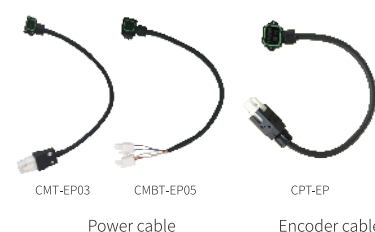
| JC-CB bus cable

- EtherCAT motion bus dedicated communication cable
- Adopting industrial grade Category 5e four-core Ethernet cable



| Adapter cable

- Power cable
- Encoder cable



| Power cable

- Provide standard cable length specifications: 2/3/5/8/10/12/16/20/25/30 meters
- Customizable length
- Optional purchase of cable connectors (excluding cables)



| Encoder cable

- Provide standard cable length specifications: 2/3/5/8/10/12/16/20/25/30 meters
- Customizable length
- Optional purchase of cable connectors (excluding cables)



| Regenerative resistor

- Release bus capacitor regeneration voltage
- Please refer to the user manual for the selection of regeneration resistors



| DB9F side cable

- Provide cable specifications of 1.5 meters
- Can be connected to a PC to achieve control of the servo upper computer



DM6C series multi-axis servo driver

Powerful performance | precise intelligent control | quality choice



Product characteristics

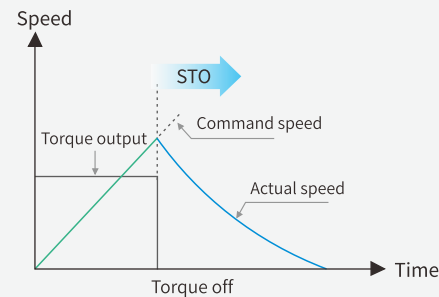
- Safe and reliable

Standard STO function

- ◆ **Support STO.** When the safe torque function is enabled, the internal hardware circuit of the drive will trigger, forcibly shutting down the power transistor of the drive, causing the motor to stop running and protecting personal and equipment safety.

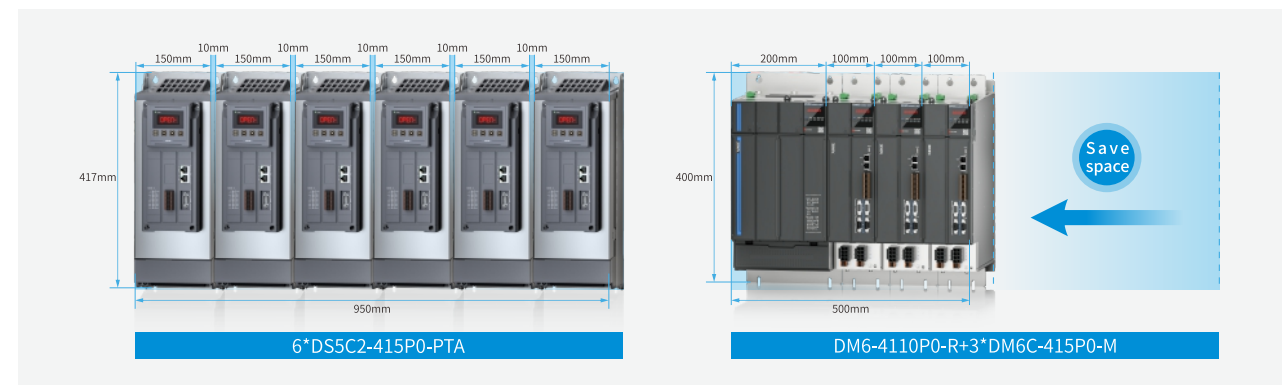
24V control power supply independent supply

- ◆ The panel supports independent 24V control power supply, and can still communicate with the upper computer even when the main circuit is not powered.



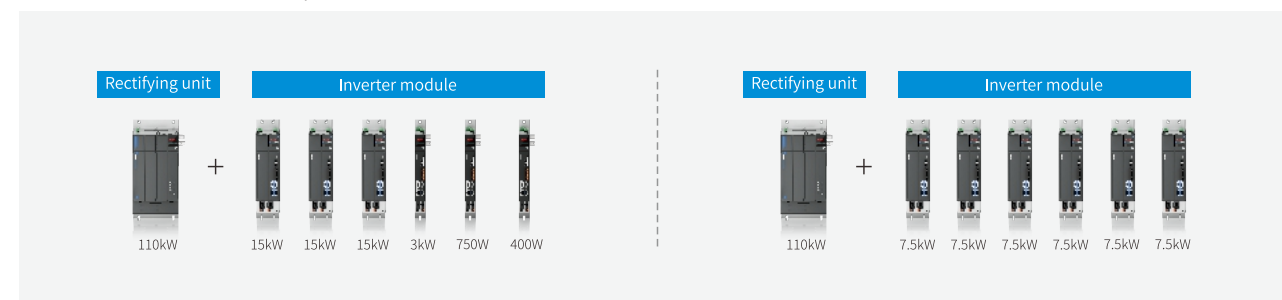
- Space saving, convenient wiring, flexible configuration

- ◆ The design of equal-height and equal-depth book-style modular units allows for compact side-by-side installation, maximizing cabinet space utilization.
- ◆ Only one set of power cables is needed. Inside, a reliable connection between modules is achieved through a common bus with copper bars and screw locking.
- ◆ Inverter modules of 15KW and below use plug-in power terminals, saving approximately 30% in wiring time.



Flexible combination

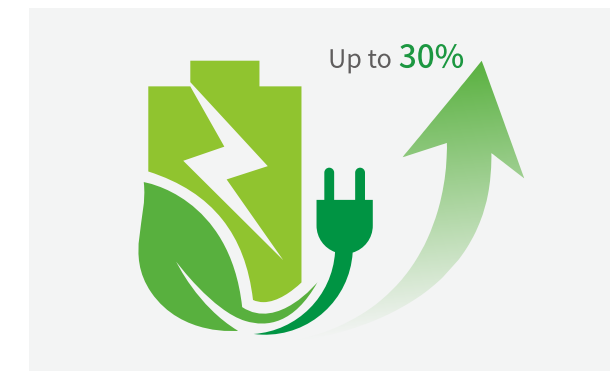
- ♦ By using a combination of rectifier and inverter modules, taking the 110kW rectifier unit as an example, the following inverter module combinations are possible:



- Efficient and energy-saving

DC common busbar, energy-saving and environmentally friendly

- ♦ Using common DC bus technology for energy exchange, reducing energy loss of the driver, expected to save up to 30% electricity, more energy-efficient.



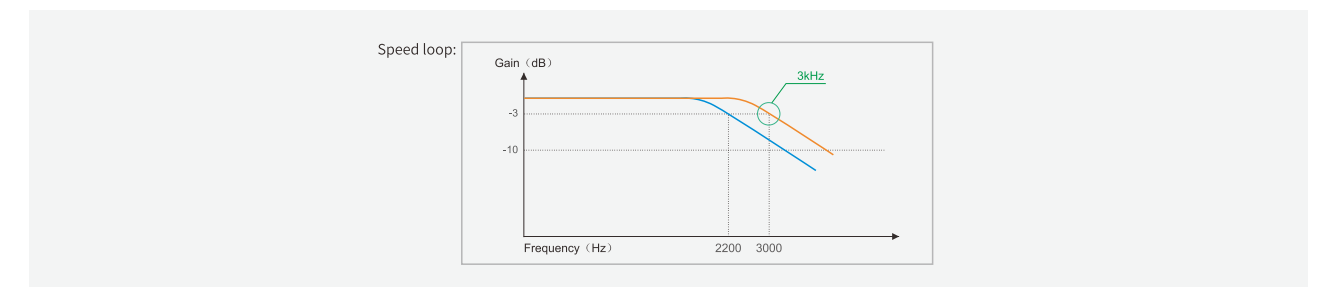
- High protection

- ◆ Independent air duct design to prevent dust or foreign objects from entering the control circuit.
- ◆ Enhance the three proofings to improve the environmental resistance of the driver.



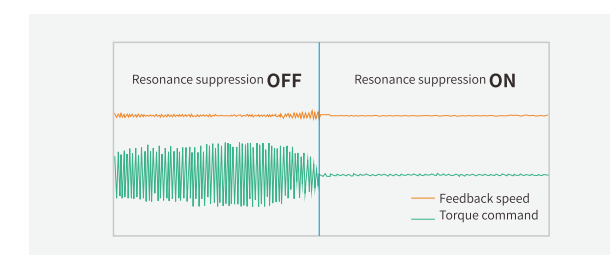
- High dynamic response, vibration suppression, and efficient tuning

- ♦ 3kHz speed loop response bandwidth. Synchronization cycle 250μs. High dynamic response, improving production efficiency.
- ♦ Advanced control algorithms provide the optimal solution for achieving fast and flexible results in fast positioning systems.



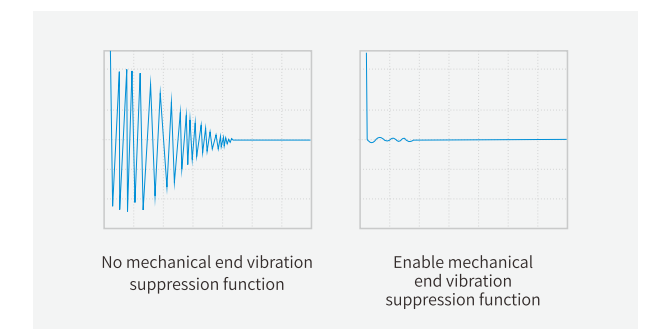
Resonance suppression

- ◆ The resonance suppression control algorithm can effectively shorten the tuning time, eliminate mechanical resonance, and make path tracking smooth and accurate.
- ◆ Resonance frequency automatic inspection, with stronger usability.
- ◆ The accuracy of vibration frequency recognition has been improved by 50%.
- ◆ The resonance frequency analysis time is reduced by 50%.

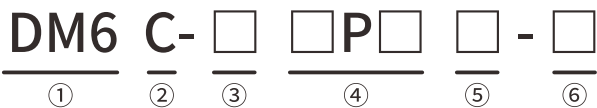


Mechanical end vibration suppression

- By using advanced control algorithms, vibration and noise suppression at the mechanical end can be achieved. Effectively solve the vibration at the end of the cantilever beam mechanism, shorten the tuning time, and improve product accuracy.



Model naming rule



No.	Item	Content
①	Product series	DM6: DM6 series
②	Product type	C: EtherCAT bus type Default: Rectification unit and braking unit
③	Voltage level	4: AC380V
④	Driver power	0P4: 400W 0P7: 750W 1P5: 1.5kW 3P0: 3kW 5P5: 5.5KW 7P5: 7.5kW 11P0: 11kW 15P0: 15kW 22P0: 22kW 32P0: 32kW 45P0: 45kW 55P0: 55kW 75P0: 75kW 110P0: 110kW 160P0: 160KW
⑤	Inversion axes	S: single axis Default: two axes
⑥	Unit type	R: rectification unit M: inverter unit

Driver model list

Power(kW)	Rated output current(A)	Rectifier module
22.0	56	DM6-422P0-R (in development)
45.0	107	DM6-445P0-R (in development)
75.0	152	DM6-475P0-R (in development)
110.0	240	DM6-4110P0-R
160.0	358	DM6-4160P0-R (in development)

Power(kW)	Inverter module	Axis number	Axis power (power*axis number)	Rated current (A)	Maximum current (A)	Suitable motor (recommended)
0.4	DM6C-40P4-M	2	0.4*2	2.8	8.4	MS6S-60CN30B3-20P4
						MS6S-60CN30BZ3-20P4
						MS6S-60TH30B3-20P4
						MS6S-60TH30BZ3-20P4
						MS6H-60CN30B3-20P4
						MS6H-60CN30BZ3-20P4
						MS6H-60TH30B3-20P4
						MS6H-60TH30BZ3-20P4
0.7	DM6C-40P7-M	2	0.75*2	4.8	14.4	MS6S-80CN30B3-20P7
						MS6S-80CN30BZ3-20P7
						MS6S-80TH30B3-20P7
						MS6S-80TH30BZ3-20P7
						MS6H-80CN30B3-20P7
						MS6H-80CN30BZ3-20P7
						MS6H-80TH30B3-20P7
						MS6H-80TH30BZ3-20P7
1.5	DM6C-41P5-M	2	1.5*2	6	18	MS6G-110CN30B2-41P5
						MS6G-110CN30BZ2-41P5
						MS6G-110TH30B2-41P5
						MS6G-110TH30BZ2-41P5
						MS6G-130CN20B2-41P5
						MS6G-130CN20BZ2-41P5
						MS6G-130CN15B2-41P5
						MS6G-130CN15BZ2-41P5
						MS6G-130TH20B2-41P5
						MS6G-130TH20BZ2-41P5
						MS6G-130TH15B2-41P5
						MS6G-130TH15BZ2-41P5
3.0	DM6C-43P0-M	2	3.0*2	11	29.7	MS6H-180CN15B2-43P0
						MS6H-180CN15BZ2-43P0
						MS6G-180CN15B2-43P0
						MS6G-180CN15BZ2-43P0
						MS6G-180TH15B2-43P0
						MS6G-180TH15BZ2-43P0
						MS6S-130CN30B2-43P0
						MS6S-130TH30B2-43P0
						MS6S-130CN30BZ2-43P0
						MS6S-130TH30BZ2-43P0

Power(kW)	Inverter module	Axis number	Axis power (power*axis number)	Rated current (A)	Maximum current (A)	Suitable motor (recommended)
5.5	DM6C-45P5-M	2	5.5*2	20	50	MS6H-180CN15B2-44P4
						MS6H-180CN15BZ2-44P4
						MS6G-180CN15B2-44P4
						MS6G-180CN15BZ2-44P4
						MS6G-180TH15B2-44P4
						MS6G-180TH15BZ2-44P4
						MS6S-130CN30B2-45P0
						MS6S-130TH30B2-45P0
						MS6H-180CN15B2-45P5
						MS6H-180CN15BZ2-45P5
						MS6H-180CN15E2-45P5
						MS6H-180CN15EZ2-45P5
						MS6G-180CN15B2-45P5
						MS6G-180CN15BZ2-45P5
						MS6G-180TH15B2-45P5
						MS6G-180TH15BZ2-45P5
						MS6H-180CN15B2-47P5
						MS6H-180CN15BZ2-47P5
7.5	DM6C-47P5-M	2	7.5*2	25	62.5	MS6H-180CN15E2-47P5
						MS6H-180CN15EZ2-47P5
						MS6G-180CN15B2-47P5
						MS6G-180CN15BZ2-47P5
						MS6G-180TH15B2-47P5
						MS6G-180TH15BZ2-47P5
						MS6G-200TH17B2-417P0-F
						MS6G-200TH17B2-413P0-F
15.0	DM6C-415P0-M	2	15.0*2	37	77.7	MS6G-200TH17BZ2-417P0-F
						MS6G-200TH17BZ2-413P0-F
						MS6G-200TH17B2-417P0-Y
						MS6G-200TH17B2-413P0-Y
						MS6G-200TH30B2-422P0-YL01
						MS6G-200TH30B2-415P0-YL01
						MS6G-200TH17B2-421P0-F
						MS6G-200TH17BZ2-421P0-F
32.0	DM6C-432P0S-M	1	32.0*1	65	130	MS6G-200TH17B2-421P0-Y
						MS6G-200TH17B2-427P0-F
						MS6G-200TH17BZ2-427P0-F
						MS6G-200TH17B2-427P0-Y
						MS6G-265TH17B2-430P0-F
						MS6G-265TH17B2-430P0-Y
						MS6G-265TH17B2-448P0-F
						MS6G-265TH17B2-448P0-Y
45.0	DM6C-445P0S-M	1	45.0*1	100	250	MS6G-265TH17B2-448P0-Y
55.0	DM6C-455P0S-M	1	55.0*1	126	315	MS6G-265TH20B2-456P0-Y01
						MS6G-265TH17B2-460P0-F
75.0	DM6C-475P0S-M	1	75.0*1	152	380	MS6G-265TH17B2-460P0-Y
						MS6G-265TH17B2-475P0-F
						MS6G-265TH17B2-475P0-Y

Driver specification list

Function	Control mode			
	Position control	Speed control	Torque control	Bus control
EtherCAT type DM6C series	●	●	●	●

Function	Control method								
	Pulse	Long line drive	Analog input	External displacement sensor	ABZ differential encoder	USB Type-C	RS485	SI input	SO output
EtherCAT type DM6C series					●	●	●	6	4

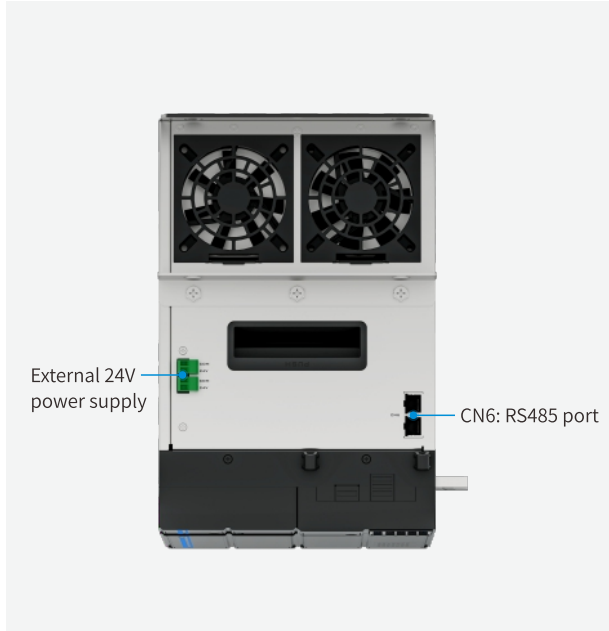
Technical specification

Specification		Model	Inverter unit
		DM6C-M series	
Basic specification	Power range (KW)		0.4KW-75KW
	Input power supply		DC537V-679V
	Control circuit power supply		DC24V
	Encoder feedback		19-bit/23-bit communication encoder
	Control mode		PWM control, sine wave current drive mode
	Using environment	Ambient temperature	Operation:-10°C~40°C (no condensation)/Storage:-20°C~60°C (no condensation)
		Ambient humidity	Operation/Storage: Below 90%RH (no condensation)
		Vibration/impact resistance	4.9m/s²/19.6m/s²
	Function	Protection function	Overvoltage, undervoltage, overheating, overcurrent, overload, overspeed, excessive position deviation, output short circuit, encoder abnormality, overtravel protection, oscillation protection, etc.
		STO	Standard configured
Communication interface		USB Type-C, RS-485, EtherCAT	
Position output	Display and operation	6-digit LED indicator light, power indicator light, 5 buttons operation	
	Frequency division function	Yes	
	Collector Z-phase output	Yes	
Analog input		No	
I/O signal	Digital input (SI)		6 channels
			Servo enable, alarm clear, prohibit forward rotation, prohibit reverse rotation, torque limit selection, internal speed selection, mode switching
			Pulse input prohibition, zero speed locking, position deviation clearing, internal position step change signal, internal control mode direction switching
	Digital output (SO)		4 channels
			Positioning completed, servo ready, alarm output, torque limit output, same speed detection, rotation detection, speed reached
Brake release output, warning output			
Position control mode	Pulse command mode		Not support
	Control mode		Internal position/EtherCAT motion bus
	Feedforward compensation		0~100% (set the resolution to 1%)
	Positioning completed width setting		1~65535 instruction units (set resolution to 1 instruction unit)
	Electronic gear ratio		1/65530≤B/A≤65535
Speed control mode	Control method		Internal three-segment speed, external speed mode
	Instruction smoothing method		Low-pass filter, smoothing filter
	Analog input	Voltage range	NO
		Input impedance	NO
	Torque limit		Internal parameters
	Speed change rate		When the rated external load changes from 0% to 100%: below ±0.01% (at rated speed)
Rated voltage ±10%: 0.01%(at rated speed)			
Torque control mode	Control mode		Environmental temperature of 20 ± 25°C: below ±0.01% (at rated speed)
			Internal torque
			NO
	Analog input	Input impedance	NO
Speed limit		Internal parameters	
Bus control mode	Communication protocol		EtherCAT protocol

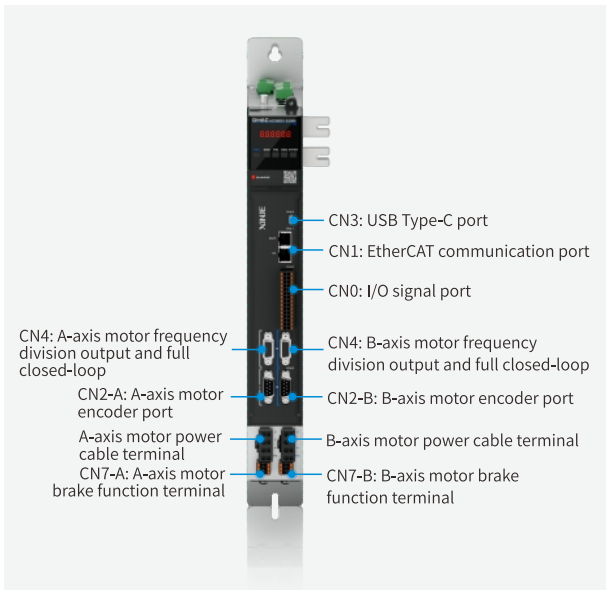
Specification		Model	Rectifying unit
			DM6-R series
Basic specification	Power range (KW)		22KW, 45KW, 75KW, 110KW, 160KW
	Input power supply		Three phase AC380V~440V, 50Hz/60Hz
	Control circuit power supply		DC24V
	Control mode		Three phase full wave rectification IPM, PWM control, sine wave current drive mode
	Using environment	Ambient temperature	Operation:-10°C~40°C (no condensation)/Storage:-20°C~60°C (no condensation)
		Ambient humidity	Operation/Storage: Below 90%RH (no condensation)
		Vibration/impact resistance	4.9M/S ² /19.6M/S ²
	Protection function		Overvoltage, undervoltage, overheating, oscillation protection, phase loss protection, etc

Terminal definition

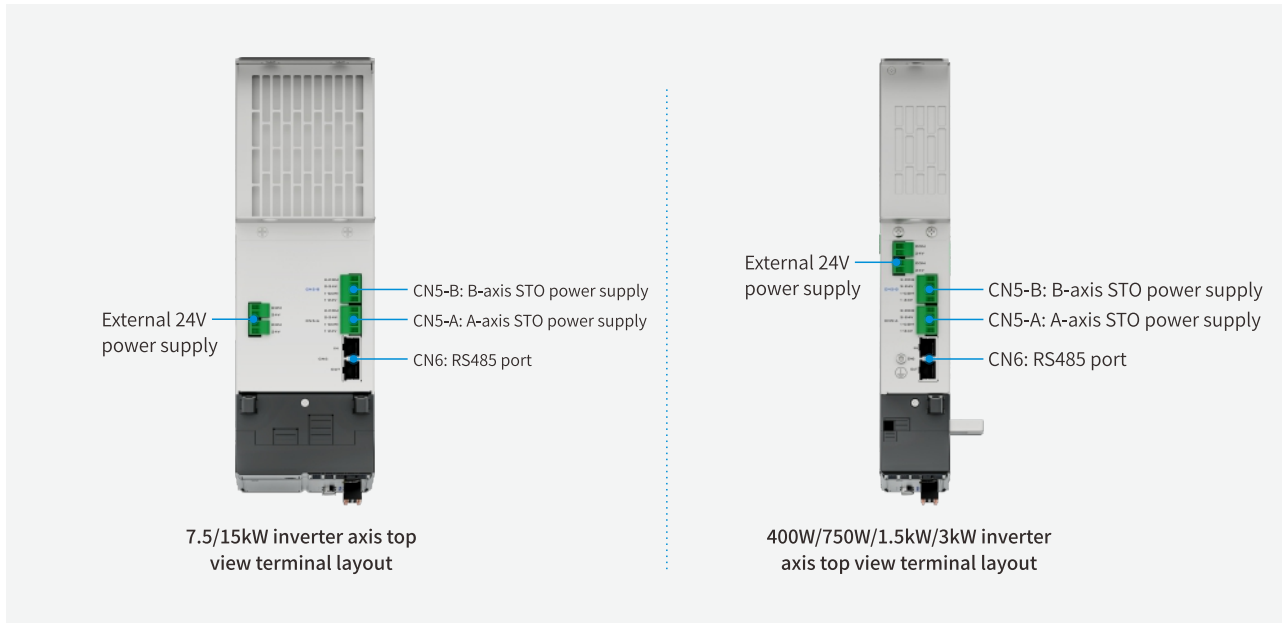
Terminal arrangement of rectifier unit
DM6-4110P0-R



Front terminal layout of inverter module
DM6C 15kW/7.5kW/5.5kW/3kW/1.5kW/
750W/400W



Top view terminal layout of inverter module
DM6C 15kW/7.5kW/5.5kW/3kW/1.5kW/750W/400W



Terminal definition

① CN0 (I/O terminals)

No.	Name	Explanation	No.	Name	Explanation
1	SI1+	Axis A SI1+ (high-speed)	16	SO4-	Axis B SO4-
2	SI1-	Axis A SI1- (high Speed)	17	SO4+	Axis B SO4+
3	SI2+	Axis A SI2+ (high speed)	18	COM	Axis B output terminal ground
4	SI2-	Axis A SI2- (high speed)	19	SO3	Axis B SO3
5	SI3	Axis A SI3	20	SO2	Axis B SO2
6	SI4	Axis A SI4	21	SO1	Axis B SO1
7	SI5	Axis A SI5	22	+24VI	Axis B input +24V
8	SI6	Axis A SI6	23	SI6	Axis B SI6
9	+24V	Axis A input +24V	24	SI5	Axis B SI5
10	SO1	Axis A SO1	25	SI4	Axis B SI4
11	SO2	Axis A SO2	26	SI3	Axis B SI3
12	SO3	Axis A SO3	27	SI2-	Axis B SI2- (high speed)
13	COM	Axis A output terminal ground	28	SI2+	Axis B SI2+ (high speed)
14	SO4+	Axis A SO4+	29	SI1-	Axis B SI1- (high speed)
15	SO4-	Axis A SO4-	30	SI1+	Axis B SI1+ (high speed)

③ CN2 (encoder)

No.	Definition	No.	Definition
1	Motor temperature detection	6	GND
2	Motor temperature detection	7	GND
3	485-B	8	+5V
4	485-A	9	+5V
5	PE	/	/

⑤ CN4 (frequency division output and fully closed-loop signal)

No.	Name	Explanation	No.	Name	Explanation
1	QBH-A+	Fully closed-loop input A+	9	FPA+	Encoder frequency division output A+
2	QBH-A-	Fully closed-loop input A-	10	FPA-	Encoder frequency division output A-
3	GND	Grating ruler GND	11	FPB+	Encoder frequency division output B+
4	QBH-B+	Fully closed-loop input B+	12	FPB-	Encoder frequency division output B-
5	QBH-B-	Fully closed-loop input B-	13	FPZ+	Encoder frequency division output Z+
6	QBH-Z+	Fully closed-loop input Z+	14	FPZ-	Encoder frequency division output Z-
7	QBH-Z-	Fully closed-loop input Z-	15	5V	Grating ruler power supply 5V
8	GND	Grating ruler GND	/	/	Idle pins

⑦ CN6 (CAN+RS485+station number allocation)

No.	Name	No.	Definition
1	CANH	9	CANH
2	CANL	10	CANL
3	GND	11	GND
4	485-A	12	485-A
5	485-B	13	485-B
6	485GND	14	485GND
7	OUT-TX	15	IN-TX
8	OUT-RX	16	IN-RX

② CN1 (EtherCAT port)

No.	Name	No.	Name
1	TX A+	9	TX B+
2	TX A-	10	TX B-
3	RX A+	11	RX B+
4	-	12	-
5	-	13	-
6	RX A-	14	RX B-
7	-	15	-
8	-	16	-

④ CN3 (USB Type-C port)

No.	Name	No.	Name
A1	GND	B1	GND
A4	USB-VBUS	B4	USB-VBUS
A6	USB-D+	B6	USB-D+
A7	USB-D-	B7	USB-D-
A9	USB-VBUS	B9	USB-VBUS
A12	GND	B12	GND

⑥ CN5 (STO signal)

Name	Explanation
1	STO1-COM
2	STO1-24V
3	STO2-COM
4	STO2-24V

⑧ CN7 (brake terminals)

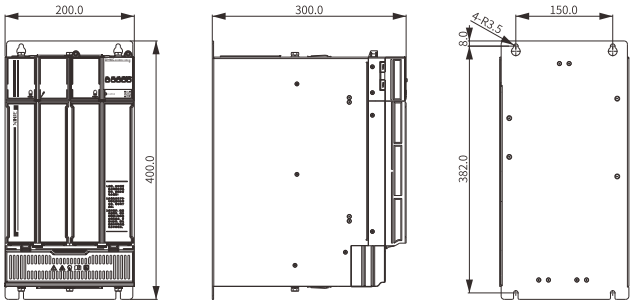
No.	Name	No.	Name
1	/	4	/
2	BK-	5	BK+
3	/	6	/

Installation dimension

(unit: mm)

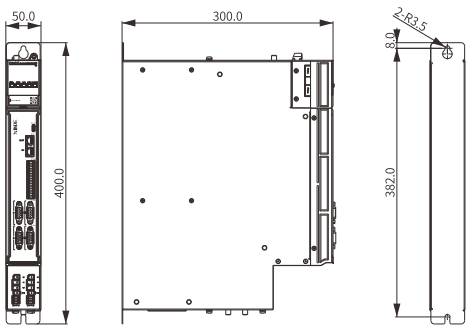
■ Rectifying unit

DM6-4110P0-R

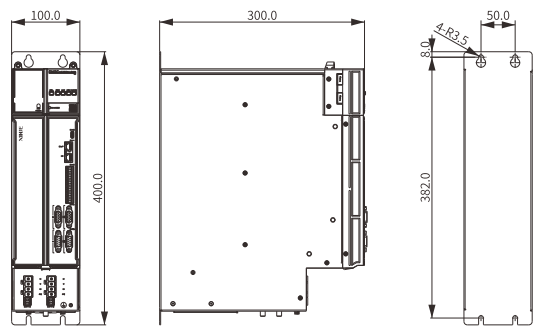


■ Inverter unit

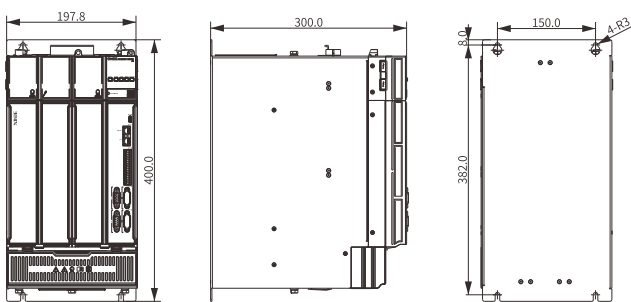
DM6C-40P4/40P7/41P5/43P0-M



DM6C-45P5/47P5/415P0-M



DM6C-455P0S/475P0S-M



DL6 series

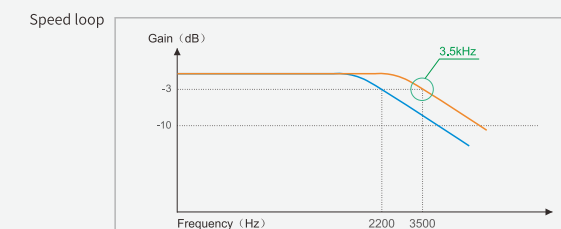
fully functional linear drive servo driver



Product features

High dynamic response

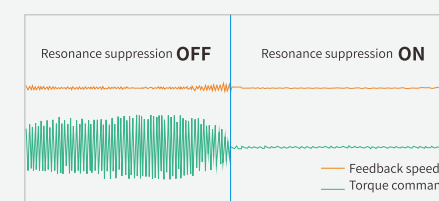
- 3.5kHz speed loop response bandwidth. Synchronization period 250μs. High dynamic response improves production efficiency.
- Advanced control algorithms provide the optimal solution for achieving fast and flexible results in fast positioning systems.



Suppress vibration, Efficient tuning

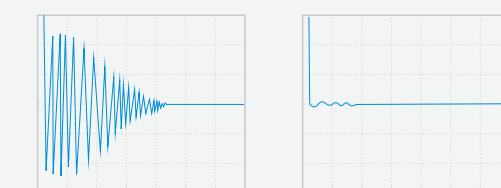
Resonance suppression

- The resonance suppression control algorithm can effectively shorten the tuning time, eliminate mechanical resonance, and make path tracking smooth and accurate.
- Resonance frequency automatic inspection, with stronger usability.
- The accuracy of vibration frequency recognition has been improved by 50%.
- The resonance frequency analysis time is reduced by 50%.



Mechanical end vibration suppression

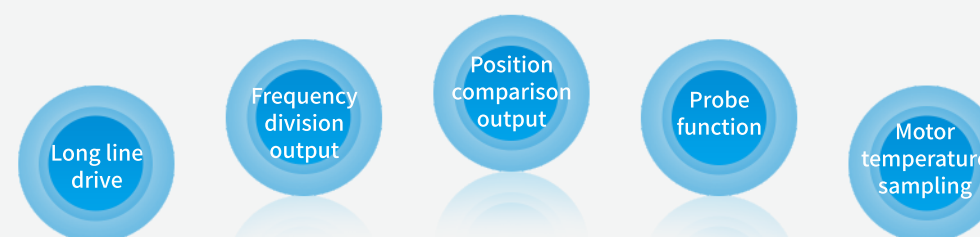
- By using advanced control algorithms, vibration and noise suppression of mechanical ends can be achieved. Effectively solve the vibration at the end of the cantilever beam mechanism, shorten the tuning time, and improve product accuracy.



No mechanical end vibration suppression function Enable mechanical end vibration suppression function

Fully functional

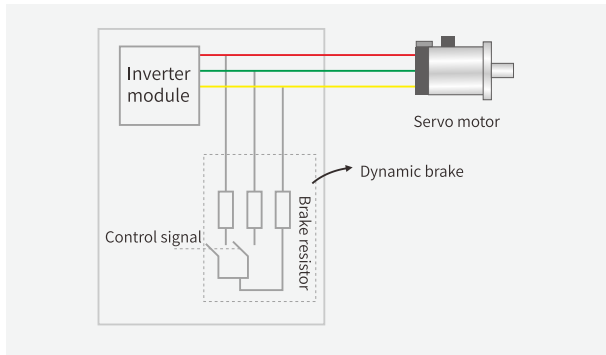
- The DL6 series is equipped with long line drive, frequency division output, position comparison output, probe function, motor temperature sampling and other functions.



Reliable operation

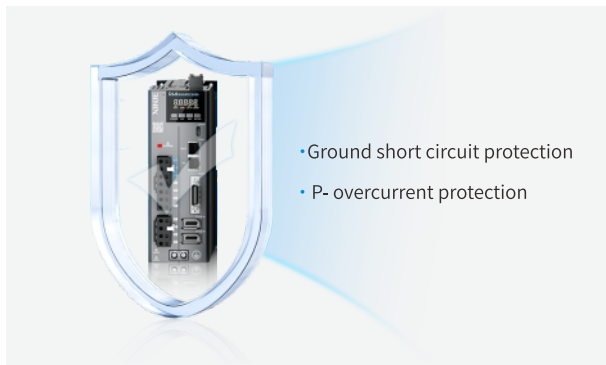
Dynamic braking

- When there is a power outage or alarm during the operation of the motor, the servo will be turned off, and the three-phase circuit of the motor will be short circuited. The servo motor will quickly stop, thus protecting the safety of people and machines.



Multiple protection functions

- Support multiple protection functions, such as ground short circuit protection, P- overcurrent protection, etc., with ultra-low failure rate, users can use it with more peace of mind.



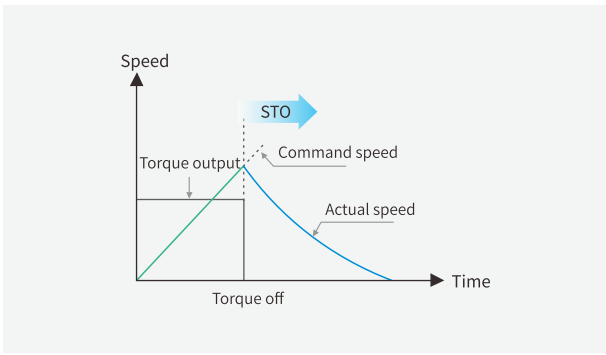
Equipped with a brand new upper computer debugging serial port

- Standard Type-C debugging port.



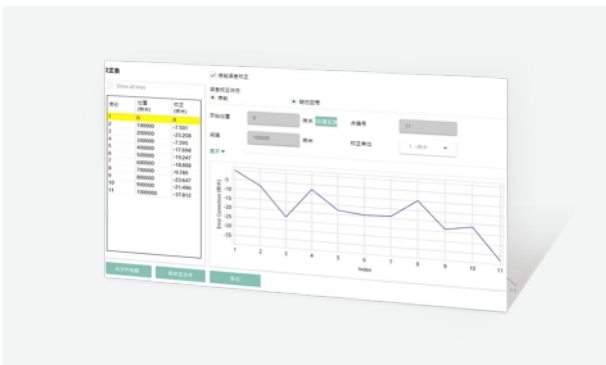
STO function

- Support STO. When the safety torque function is enabled, the internal hardware circuit of the driver will trigger, forcibly shutting down the power transistor of the driver, causing the motor to stop running and protecting personal and equipment safety.



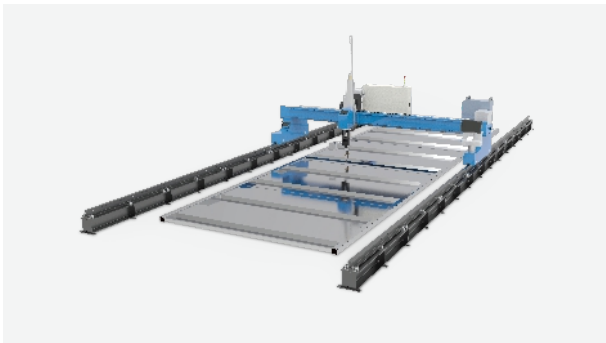
Higher positioning accuracy

- The positioning accuracy compensation function helps achieve higher absolute positioning accuracy.



Gantry function

- Introducing a new gantry synchronization algorithm, the two axes are highly synchronized during motion, ensuring high response and synchronization performance even at high speed.



Naming rule

DL 6 □ - 2 □ □ □ - GS

① ② ③ ④ ⑤ ⑥

①	Symbol	Product name
	DL	Linear drive servo driver

②	Symbol	Product series
	6	6 series

③	Symbol	Product type
	Default	Standard

④	Symbol	Rated input voltage
	2	AC220V
	4	AC380V

⑤	Symbol	Rated output current
	003	2.8A
	006	6A

⑥	Symbol	Special function
	Default	Standard type
	GS	Gantry synchronization

Driver model list

Current	Series	DL6 series
2.8A		DL6-2003
2.8A		DL6-2003-GS
6A		DL6-2006
6A		DL6-2006-GS

Driver specification list

Function	Driver specification list								
	Position control			Speed control		Torque control		Bus control	
DL6 series	●			●		●		●	

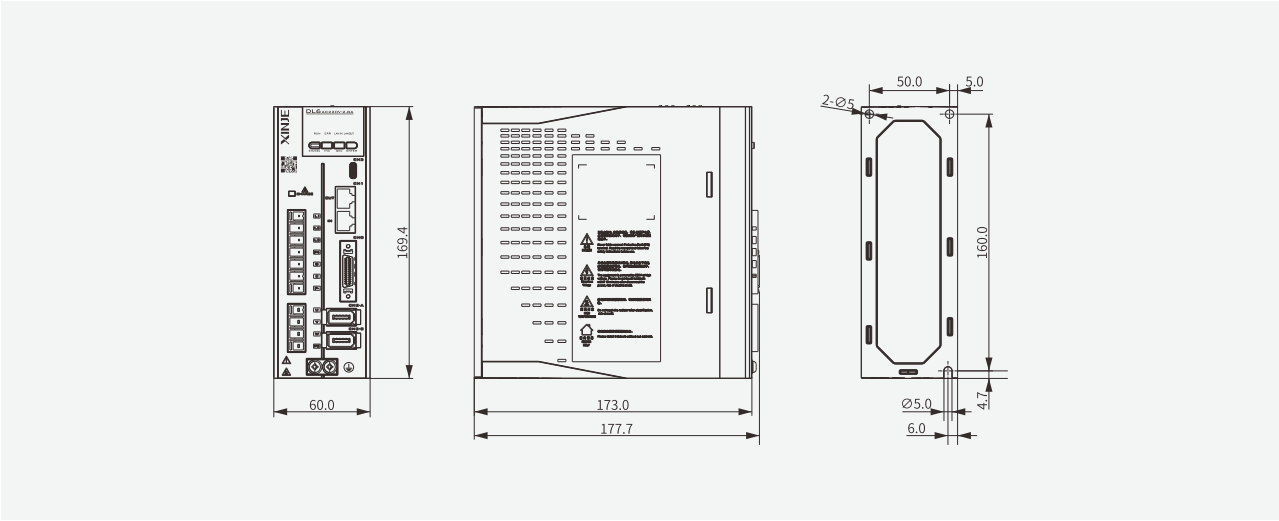
Function	Control method								
	Pulse	Long line drive	Analog input	External displacement sensor	ABZ differential feedback	USB Type-C	RS485	SI input	SO output
DL6 series	●	●		●	●	●		7	6

Technical specification

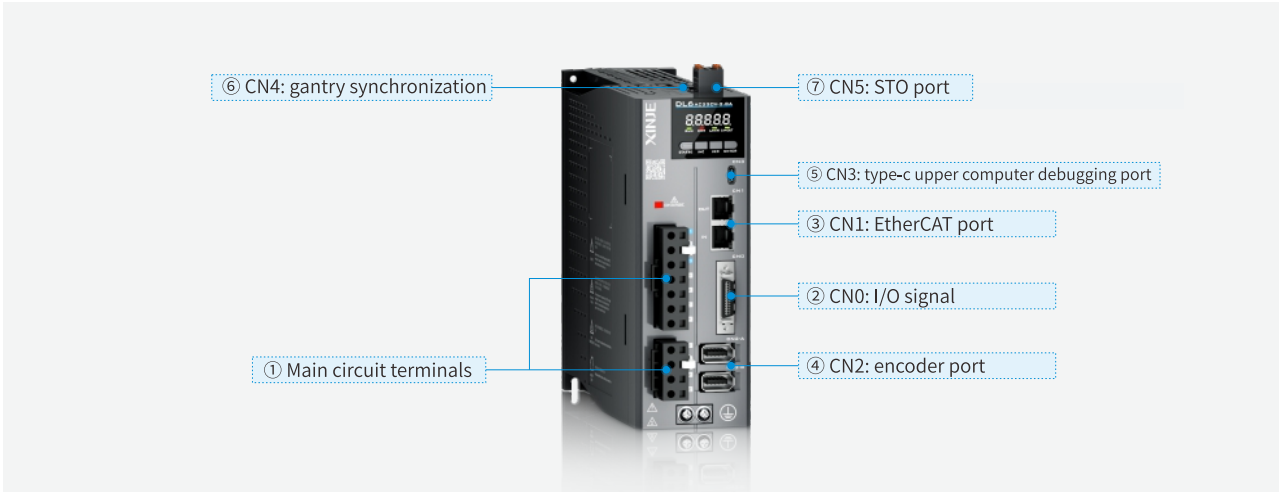
Item		DL6 series linear drive servo driver
Basic specification	Input current	Single phase/three-phase AC200~240V, 50Hz/60Hz
	Encoder feedback	ABZ incremental encoder, absolute Biss-c encoder
	Control method	Three phase full wave rectification IPM, PWM control, sine wave current drive mode
	Control mode	Position mode, speed mode, torque mode
	Using environment	Ambient temperature
		Ambient humidity
		Vibration/impact resistance
		Installation site
		Installation method
	Function	Protection function
		Dynamic brake
		Communication function
		Braking resistor
		Display and operation
I/O signal	Digital input	7 channels input
		Two channels of high-speed SI support probe function
	Digital output	6 channels digital output (two of the SO terminals are in differential form)
		Positioning completed, servo ready, alarm output, speed reached, rotation detection, torque limit output, same speed detection, brake release output

Outline dimension

(unit:mm)



Port distribution



① Main circuit terminals

Terminal	Function	Explanation
L1, L2, L3	Main circuit power input terminal	Single phase/three-phase AC200~240V, 50/60Hz (If single phase power supply is used, please connect L1/L3, otherwise it will affect parameter memory when power off)
P+, D, C	Use built-in braking resistor	Short circuit P+ and D terminals, disconnect P+ and C
	Use external braking resistor	Connect the braking resistor to the P+ and C terminals, and disconnect the P+ and D short-circuit wires: set P0-25=power value, P0-26=resistance value
P+, P-	Bus terminal	Real time voltage of the busbar can be measured, please be aware of the danger
U, V, W, PE	Motor connection terminal	Connect to the motor
⊕	Grounding terminal	The ground wire is on the heat sink. Please confirm a good grounding before powering on

② CN0

No.	Name	Explanation	No.	Name	Explanation
1	+24V	+24V	14	SI3	Ordinary input terminal 3
2	SI4	Ordinary input terminal 4	15	SI5	Ordinary input terminal 5
3	SI6	Ordinary input terminal 6	16	SI7	Ordinary input terminal 7
4	COM	Output common terminal	17	SO3	Ordinary output terminal 3
5	SO4	Ordinary output terminal 4	18	SO1	High speed output terminal 1
6	SO2	High speed output terminal 2	19	DO_24V	High speed output +24V power supply
7	OA+	Encoder frequency division output OA+	20	OA-	Encoder frequency division output OA-
8	OB+	Encoder frequency division output OB+	21	OB-	Encoder frequency division output OB-
9	OZ+	Encoder frequency division output OZ+	22	OZ-	Encoder frequency division output OZ-
10	P+5V	Pulse +5V	23	P-	Pulse-
11	D+5V	Direction +5V	24	D-	Direction-
12	SI1	High speed input terminal 1	25	SI2	High speed input terminal 2
13	P+/D+24V	Pulse/direction +24V	26	GND	Frequency division output ground

⑤ CN3

No.	Definition	No.	Definition
A1	GND	B1	GND
A4	USB-VBUS	B4	USB-VBUS
A6	USB-D+	B6	USB-D+
A7	USB-D-	B7	USB-D-
A9	USB-VBUS	B9	USB-VBUS
A12	GND	B12	GND

⑦ CN5

No.	Name	Explanation	No.	Name	Explanation
1	EDM+	EDM output+	4	EDM-	EDM output-
2	24V	24V output	5	COM	Public ground
3	STO1	STO1 circuit input	6	STO2	STO2 circuit input

③ CN1

No.	Name	No.	Name
1	TX A+	9	TX B+
2	TX A-	10	TX B-
3	RX A+	11	RX B+
4	-	12	-
5	-	13	-
6	RX A-	14	RX B-
7	-	15	-
8	-	16	-

④ CN2 (CN2-A)

No.	Definition	No.	Definition
1	Power supply	6	Incremental encoder B-Biss-C encoder DATA-
2	GND	7	Incremental encoder Z+
3	Incremental encoder A+ Biss-C encoder CLK+	8	Incremental encoder Z-
4	Incremental encoder A- Biss-C encoder CLK	9	Motor temperature+
5	Incremental encoder B+ Biss-C encoder DATA+	10	Motor temperature-

(CN2-B)

No.	Definition	No.	Definition
1	Power supply	6	-
2	GND	7	Rotary encoder A
3	Hall U+	8	Rotary encoder B
4	Hall V+	9	-
5	Hall W+	10	-

⑥ CN4

Name	Explanation
1	TX A+
2	TX A-
3	RX A+
4	-
5	-
6	RX A-
7	-
8	-

Low voltage servo system

Lightweight and compact, easy to install and debug

The low-voltage servo system launched by Xinje can be used for AGV/RGV vehicles. Its motion axis adopts a low-voltage synchronous motor, which can provide different motor power options of 0.1kW~1.5kW according to the load size, achieving fast response, high stability and high-precision control throughout the entire motion control process. Through the coordinated motion between motors, precise walking and reversing can be achieved, providing reliable solution for the implementation of intelligent logistics.



*Note: The models that have been put into production can be found in the subsequent model list. Some models have not yet been put into production, please stay tuned.

DF3 series low voltage servo driver



Appearance innovation

New appearance design, rich interfaces, compact size, lightweight body, meeting the equipment installation requirements of the AGV industry

Powerful functionality

Support multiple control modes, built-in 24V brake output, alarm synchronous braking and other functions to meet customer usage requirements

Diverse communication

Support multiple communication protocols such as CANopen and MODBUS to meet different communication function requirements of users

Easy debugging

Gain adjustment only requires three steps, greatly reducing equipment debugging time and greatly improving on-site debugging efficiency

MF series low voltage servo motor



The body is shorter

Optimize magnetic circuit structure, further shorten motor size, MF5H has a 30% reduction in body compared to MF3S

Overload capacity

The entire series comes standard with triple overload, making it faster and more stable to start and stop under overload conditions

Accuracy guarantee

The motor comes standard with a self-developed 17-bit magnetic encoder, greatly improving positioning accuracy

Excellent performance

The insulation level has reached the highest F level in the industry, fully ensuring the stability of on-site applications

Protective capability

The protection level reaches IP67, making it easy to cope with harsh environments such as oil, water vapor, and dust, ensuring the reliability of the motor

Naming rule and model list

| Low voltage servo driver naming rule

DF 3 E - 04 10 Z - A

① ② ③ ④ ⑤ ⑥ ⑦

① Name

Symbol	Product name
DF	Low voltage servo driver

④ Driver power

Symbol	Rated output power
02	200W
04	400W
07	750W
15	1.5kW

② Series number

Symbol	Specification
3	Series number

⑤ Rated current

Symbol	Rated output current
06	6A
10	10A
20	20A
40	40A

③ Control function

Symbol	Function
E	Pulse, RS485, CANopen
C	EtherCAT Under development

⑥ Driver function

Symbol	Driver function
Z	Servo directly driving brake
Vacant	Cannot directly driving brake

⑦ Series

Symbol	Specification
A	Small size 400W driver

| Low voltage servo driver model list

Series	Driver name	Power (W)	Maximum continuous output current (A)	Peak current(A)	Control mode
DF3 series DC24V~70V	DF3E-0206	200	6	18	RS485, PULSE, CANOPEN
	DF3E-0410-A	400	10	30	RS485, PULSE, CANOPEN
	DF3E-0410				RS485, PULSE, CANOPEN
	DF3E-0410Z				RS485, PULSE, CANOPEN
	DF3E-0720	750	20	60	RS485, PULSE, CANOPEN
	DF3E-0720Z				RS485, PULSE, CANOPEN
	DF3E-1540	1500	40	120	RS485, PULSE, CANOPEN

| Low voltage servo motor naming rule

MF5H - 60 C M 30 B Z □ - 5 04

① ② ③ ④ ⑤ ⑥ ⑦ ⑧ ⑨ ⑩

① Type

Symbol	Inertia
MF3S	Low inertia
MF5H	High inertia

② Flange

Symbol	Flange
60	60 flange
80	80 flange
130	130 flange

③ Encoder type

Symbol	Type
C	Magnetic encoder

④ Encoder accuracy

Symbol	Specification
M	Multi-turn 17-bit

⑤ Rated speed

Symbol	Rated speed
30	3000rpm

⑥ Motor shaft specification

Symbol	Specification
B	With key and oil seal

⑦ Power-off brake

Symbol	Specification
Z	With brake
Vacant	Without brake

⑧ Motor connector type

Symbol	Plug type
1	Amp plug
2	Aviation plug

⑨ Power-off brake

Symbol	Voltage
5	48V

⑩ Rated power

Symbol	Power
02	200W
04	400W
07	750W
12	1.2kW
15	1.5kW

Naming rule and model list

| Low voltage servo motor model list

Series	Power supply voltage(V)	Model	Power (W)	Rated torque (N.m)	Rated speed (rpm)	Rated current (A)	Encoder type
MF5 series	DC48	MF5H-60CM30B(Z)1-502	200	0.64	3000	6.0	Magnetic encoder 17-bit
		MF5H-60CM30B(Z)1-504	400	1.27	3000	11	Magnetic encoder 17-bit
		MF5H-80CM30B(Z)2-507	750	2.39	3000	20	Magnetic encoder 17-bit
		MF5H-80CM30B(Z)2-512	1200	3.82	3000	33	Magnetic encoder 17-bit
MF3 series		MF3S-130CM30B(Z)2-515	1500	4.8	3000	31.5	Magnetic encoder 17-bit

| Low voltage servo cable naming rule

CP - SP - M - Length

① ② ③ ④

① Cable type

Symbol	Specification
CP	Normal encoder cable

② Plug type

Symbol	Specification
SP	9-pin Amp plug
SV	7-core waterproof small aviation plug
SC	10-core small aviation plug

③ Battery box type

Symbol	Battery box type
M	Without battery box
BM	With battery box

④ Cable length

Symbol	Length (m)
01	1
02	2
03	3
05	5

CM - P 15 A - Length

① ② ③ ④ ⑤

① Cable type		② Plug type		③ Cable diameter type		④ Termial type		⑤ Cable length	
Symbol	Specification	Symbol	Specification	Symbol	Cable diameter (mm ²)	Symbol	Type	Symbol	Length (m)
CM	Normal power cable	P	4-core Amp plug	15	1.5	Vacant	U-shaped terminal	01	1
		V	6-core waterproof small aviation plug	20	2	A	Pin terminal	02	2
		XL	4-core medium-sized aviation plug	60	6			03	3
								05	5

| Low voltage servo adaptation table

Series	Power (W)	Servo motor	Suitable driver	Encoder cable	Power cable	Brake cable
High inertia 48VDC	200	MF5H-60CM30B1-502	DF3E-0206	CP-SP-M- Length	CM-P15A-Length	
		MF5H-60CM30BZ1-502	DF3E-0206	CP-SP-M-Length	CM-P15A-Length	CB-P03-Length
High inertia 48VDC	400	MF5H-60CM30B1-504	DF3E-0410-A DF3E-0410 DF3E-0410-Z	CP-SP-BM-Length	CM-P15A-Length	-
		MF5H-60CM30BZ1-504	DF3E-0410-A DF3E-0410 DF3E-0410-Z	CP-SP-BM-Length	CM-P15A-Length	CB-P03-Length
High inertia 48VDC	750	MF5H-80CM30B2-507	DF3E-0720 DF3E-0720Z	CP-SV-BM-Length	CM-V20-Length	-
High inertia 48VDC	750	MF5H-80CM30BZ2-507	DF3E-0720 DF3E-0720Z	CP-SV-BM-Length	CMB-V20-Length	-
High inertia 48VDC	1200	MF5H-80CM30B2-512	DF3E-1540	CP-SV-BM-Length	CM-V40-Length	-
		MF5H-80CM30BZ2-512	DF3E-1540	CP-SV-BM-Length	CMB-V40-Length	-
Low inertia 48VDC	1500	MF3S-130CM30B2-515	DF3E-1540	CP-SC-B-Length	CM-XL60-Length	-
		MF3S-130CM30BZ2-515		CP-SC-B-Length	CMB-XL60-Length	-

*Note: The MF5H series motor adopts a single multi turn integrated encoder. If you need to use the multi turn function, please purchase a cable with a battery box.

Technical parameter table

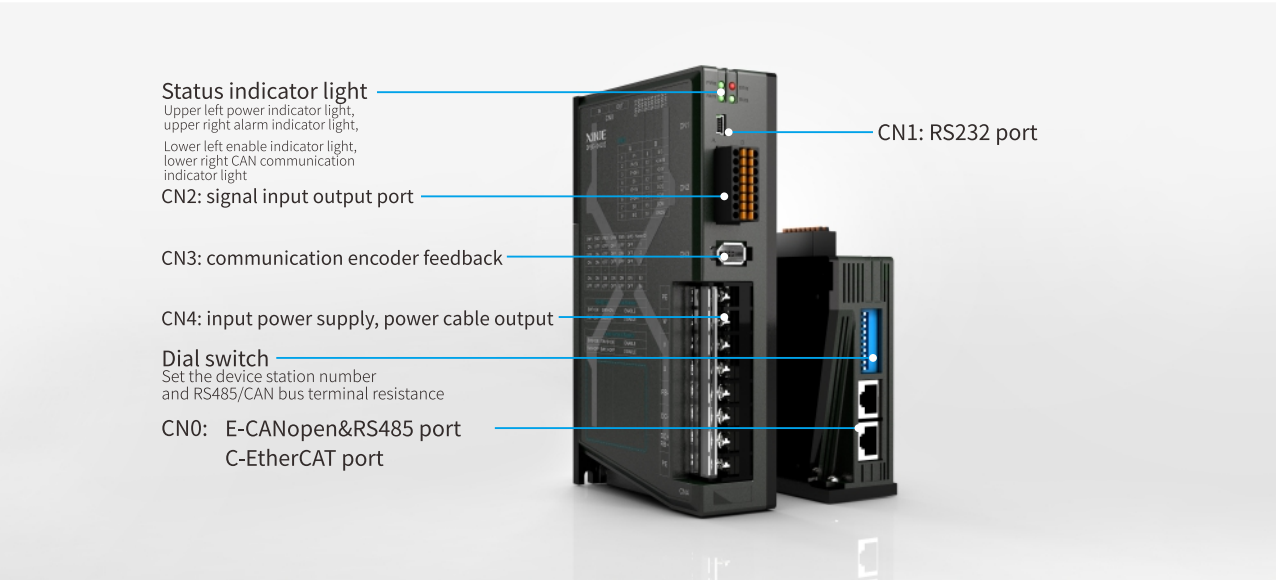
| Driver technical parameters

Item		DF3E-0206	DF3E-0410	DF3E-0720	DF3E-1540
Basic specification	Power	200W	400W	750W	1500W
	Input power supply				
	Rated output current	DC24V-70V			
		6	10	20	40
	Peak current (PEAK)	18	30	60	120
	Encoder feedback	17-bit communication encoder			
	Communication mode	RS232, RS485, CANopen			
	Using environment	Operation:-10°C~40°C (no condensation)/Storage:-20°C ~60°C (no condensation)			
		Operation/storage: 20%~90% RH (no condensation)			
		Vibration/impact resistance			
		4.9m/s ² / 19.6m/s ²			
		Installation site			
		A place without dust, dry, vibration, or corrosive substances			
	Installation method	Vertical or horizontal installation			
		External brake resistor can be connected			
	Energy consumption braking	Overvoltage, undervoltage, overheating, overcurrent, overload, overspeed, excessive position deviation, output short circuit, encoder abnormality, regeneration abnormality protection, overtravel protection, oscillation protection, operation disconnection protection, etc			
	Protection function	At 0~100% load: below ±0.1% (at rated speed)			
	Load variation rate	Rated voltage ±10%: 0.01% (at rated speed)			
	Voltage variation rate	20±25°C: below ±0.1% (at rated speed)			
	Temperature change rate	4 channels digital input (brake models have 3 channels digital input)			
I/O signal	Digital input	Servo enable, alarm clear, prohibit forward rotation, prohibit reverse rotation, torque limit selection, internal speed selection, gear ratio switching, mode switching, pulse input prohibition, position deviation clearing, internal position step change signal			
		3 channels digital output			
	Digital output	Positioning completed, servo ready, alarm output, speed reached, rotation detection, torque limit output, same speed detection, brake release output			
		Support pulse+direction, AB phase, CW/CCW			

| Motor technical parameters

Voltage level		DC48V			
Motor model MF		3S-130	5H-60	5H-60	5H-80
		130CM30B(Z)2	CM30B(Z)1	CM30B(Z)1	CM30B(Z)2
		515	502	504	507
Rated power (W)		1500	200	400	750
Rated current (A)		31.5	6	11	20
Rated speed (PRM)		3000	3000	3000	3000
Maximum speed (PRM)		3500	3500	3500	3500
Rated torque (N · M)		4.8	0.64	1.27	2.39
Maximum torque (N · M)		14.4	1.92	3.81	7.17
Rotor inertia (10 ⁻⁷ KGM)		15018(15275)	320(332)	556(562)	1437(1500)
Axial force of bearing (N)		300	74	74	147
Radial force of bearing (N)		600	245	245	392
Inertia type		Low inertia	High inertia	High inertia	High inertia
Pole pairs		5	5	5	5
Encoder bit		17	17	17	17
Encoder type		Magnetic	Magnetic	Magnetic	Magnetic
Cooling method		Natural cooling			
Motor insulation grade		CLASSF(155°C)			
Protection level		IP66	IP67	IP65	
Using environment	Ambient temperature	-10°C~+40°C (not frozen)			
	Ambient humidity	20%~90% RH (non condensing)			

Terminal definition



CN0 port (E type port)

Pin	Definition
1	CAN_H
2	CAN_L
3	CGND
4	485+
5	485-
6	GND
Others	Reserved

CN1 port

Pin	Definition	Explanation
1	TXD	RS232 send
2	RXD	RS232 receive
3	GND	RS232 signal ground

Cn2 port (taking DF3E-0410 as an example)

Pin	Definition
1	P-
2	P+5V
3	P+24V
4	D-
5	D+5V
6	D+24V
7	SI1
8	SI2
9	SI3
10	SI4/+24VS
11	+24V
12	SO1
13	SO2
14	SO3
15	COM
16	-/GNDS

*Note:The terminal function of CN2 is divided into two types. One is the non brake type, with terminal 10 serving as SI4 and terminal 16 as an empty terminal. Another type is the brake type, where the 10th terminal has a +24VS function and the 16th terminal is GNDS, which can be used for brake control.

CN4 port (main circuit terminals)

Pin	Definition
1	PE
2	W
3	V
4	U
5	RB-
6	DC-
7	DC+/RB+
8	PE

*Note: ① RB+ and RB- connected to external resistors
② Taking DF3E-0410 as an example.

CN3 port (communication encoder feedback)

Pin	Definition
1	5V
2	GND
3	/
4	/
5	485+
6	485-

Adjust the communication station number of the low-voltage servo by using the DIP switches SW1-SW6 (Excluding DF3E-0410-A, DF3E-0206)

Station number	SW1	SW2	SW3	SW4	SW5	SW6
1	ON	OFF	OFF	OFF	OFF	OFF
2	OFF	ON	OFF	OFF	OFF	OFF
3	ON	ON	OFF	OFF	OFF	OFF
...	...	...	...	...	...	...
63	ON	ON	ON	ON	ON	ON
64	OFF	OFF	OFF	OFF	OFF	OFF

Adjust the communication station number of the low-voltage servo by using the DIP switches SW1-SW4 (Excluding DF3E-0410-A, DF3E-0206)

Station number	SW1	SW2	SW3	SW4
1	ON	OFF	OFF	OFF
2	OFF	ON	OFF	OFF
3	ON	ON	OFF	OFF
...	...	...	...	...
15	ON	ON	ON	ON
16	OFF	OFF	OFF	OFF

SW7 and SW8 control whether the internal terminal resistance of RS485 is turned on

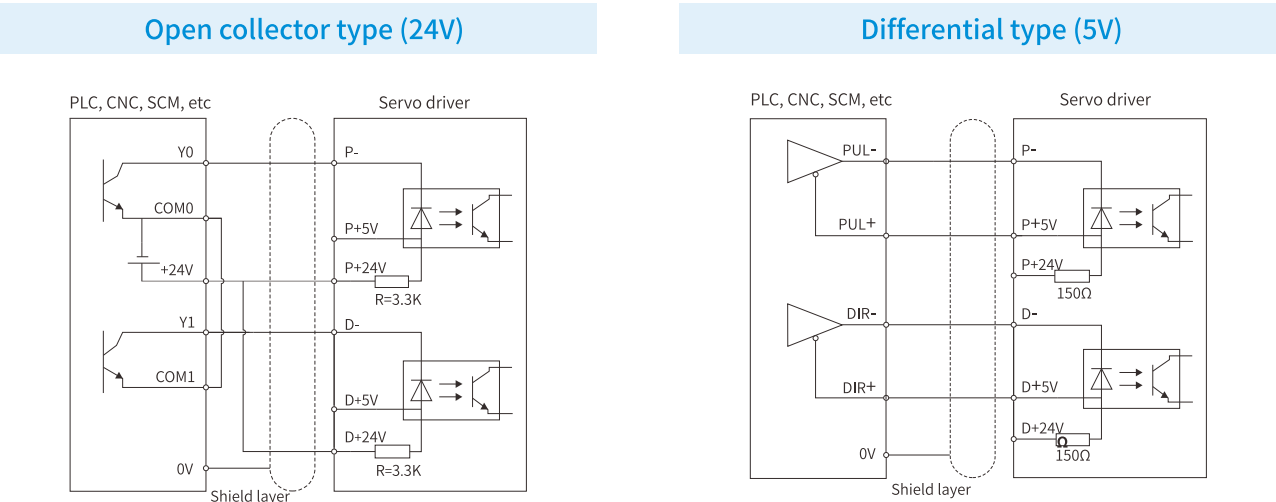
RS485 internal terminal resistance			
SW7=ON	SW8=ON	Turn ON	
SW7=OFF	SW8=OFF	Turn OFF	

SW9 and SW10 control whether the internal terminal resistance of CAN is turned on

CAN internal terminal resistance			
SW9=ON	SW10=ON	Turn ON	
SW9=OFF	SW10=OFF	Turn OFF	

Typical wiring diagram

The interface circuit for open collector/differential signal pulse input is shown in the wiring diagram below:



When the higher-level device adopts open collector output, please note to suspend P+5V and D+5V when using this connection method.

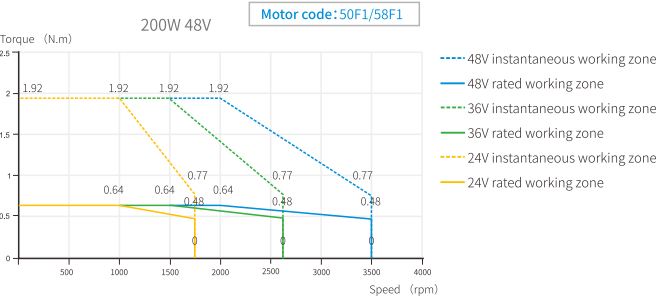
Note: ① The power supply voltage range for P-/P+24V and D-/D+24V is 18V~28V. If it is below 18V, there may be pulse and direction abnormalities.
② To resist interference, please make sure to use twisted pair shielded wires.

When the higher-level device uses 5V differential signal output, use the diagram connection method. Please note to suspend P+24V and D+24V.

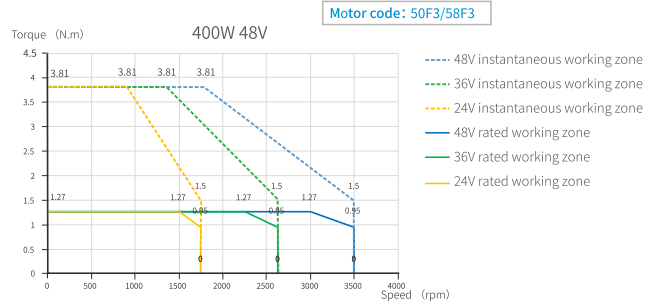
Note: ① The power supply voltage range for P-/P+5V and D-/D+5V is 3.3V~5V. If it is lower than 3.3V, there may be pulse and direction abnormalities.
② To resist interference, please make sure to use twisted pair shielded wires.
③ The servo pulse input port is conducting at 10mA.

Torque frequency characteristic curve

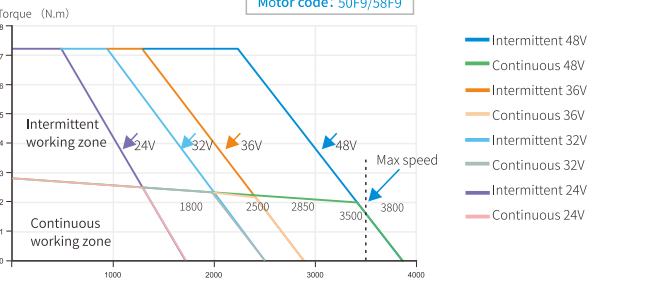
MF5H-60CM30B1-502
MF5H-60CM30BZ1-502



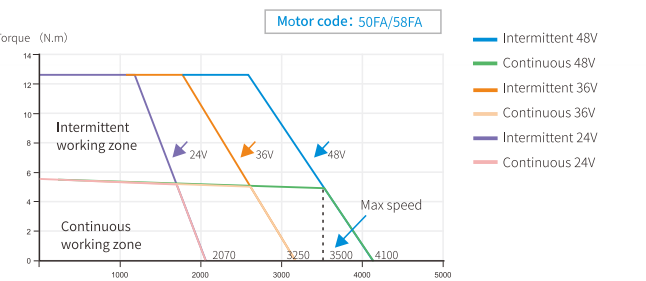
MF5H-60CM30B1-504
MF5H-60CM30BZ1-504



MF5H--80CM30B2-507
MF5H--80CM30BZ2-507

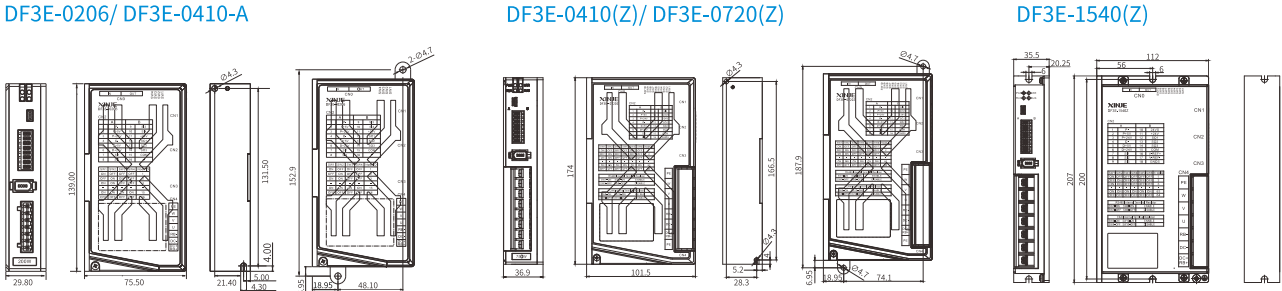


MF3S-130CM30B2-515
MF3S-130CM30BZ2-515



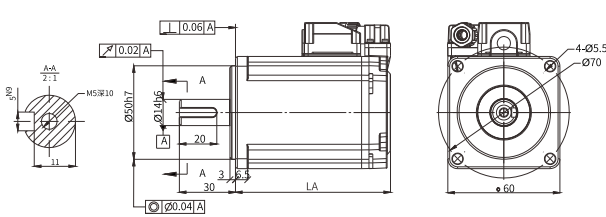
Installation dimension (unit: mm)

Low voltage servo driver



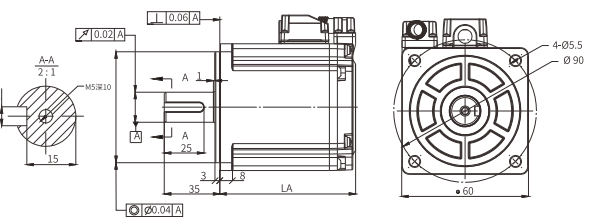
Low voltage servo motor

60 series motor



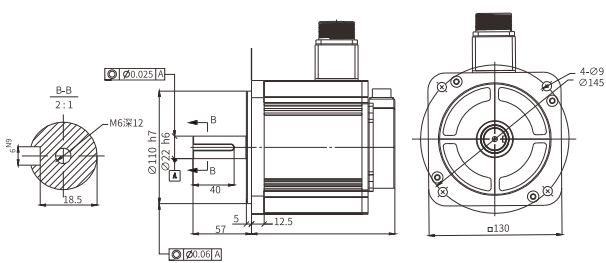
Motor type	Motor model	LA	Inertia type	Series
Non brake type	MF5H-60CM30B1-502	66.9	High inertia	MF5H Series
Brake type	MF5H-60CM30BZ1-502	93.7		
Non brake type	MF5H-60CM30B1-504	82.9		
Brake type	MF5H-60CM30BZ1-504	109.65		

80 series motor



Motor type	Motor model	LA	Inertia type	Series
Non brake type	MF5H-80CM30B2-507	85.7	High inertia	MF5H Series
Brake type	MF5H-80CM30BZ2-507	117.6		

130 series motor



Motor type	Motor model	LA	Inertia type	Series
Non brake type	MF3S-130CM30B2-515	140	Low inertia	MF3S Series
Brake type	MF3S-130CM30BZ2-515	168		